



COMPSTAT'2010

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_y
Accuracy of π , and
 π_y

Conclusions

Using Auxiliary Information Under a Generic Sampling Design

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Outline

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Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_{ij}
Accuracy of π_i and
 π_{ij}

Conclusions

- 1 Theoretical results
 - Auxiliary information
 - A class of estimators
 - The best estimator
- 2 Simulation results
 - Simulated π_i and π_{ij}
 - Accuracy of π_i and π_{ij}
- 3 Conclusions



Auxiliary information

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

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results

Auxiliary information

A class of estimators

The best estimator

Simulation results

Simulated π , and

π_{ij}

Accuracy of π , and

π_{ij}

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- Auxiliary information plays a relevant role in sampling to obtain improved design and/or more efficient estimators
- When auxiliary information is used at the estimation stage, the *ratio*, *product* and *regression* methods are widely employed in many situations
- Researchers interested in the estimation of population parameters can find a huge variety of proposals in the literature. New estimators are usually proposed by modifying the structure of existing ones but...
 - without reasonable motivations
 - comparing them with estimators that are less efficient
 - overlooking that, at best, they can be equivalent to the regression estimator
- This practice has inundated the literature with papers whose theoretical and practical relevance appears rather questionable



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19th International
Conference on
Computational
Statistics

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Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results
Simulated π , and
 π_{ij}
Accuracy of π , and
 π_{ij}

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Computational
Statistics

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A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_y
Accuracy of π , and
 π_y

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19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_y
Accuracy of π , and
 π_y

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19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results
Simulated π , and
 π_y
Accuracy of π , and
 π_y

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19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results
Simulated π , and
 π_y
Accuracy of π , and
 π_y

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19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

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results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_y
Accuracy of π , and
 π_y

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19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information

A class of estimators

The best estimator

Simulation results

Simulated π , and

π_{ij}

Accuracy of π_i and

π_{ij}

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Motivated by Bacanli and Kadilar (BK, 2008), we intend to show how the problem of finding the best estimator for the mean of a study variable can be treated under a generic sampling design by means of a very simple class of estimators

- The class is not exhaustive and a more general discussion can be found, among others, in Diana and Perri (2007)
- The best estimator in the class is compared with BK estimators according to UPS, where inclusion probability are computed on the basis of a limited numbers of samples



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19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_y
Accuracy of π , and
 π_y

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19th International
Conference on
Computational
Statistics

Giancarlo Diana,
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Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_{ij}
Accuracy of π , and
 π_{ij}

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Notation

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Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information

A class of estimators

The best estimator

Simulation results

Simulated π , and
 π_{ij}

Accuracy of π , and
 π_{ij}

Conclusions

- $U = \{1, 2, \dots, N\}$ a finite population
- Y a study variable with unknown mean $\bar{Y} = N^{-1} \sum_{i=1}^N y_i$
- X an auxiliary variable with $\bar{X} = N^{-1} \sum_{i=1}^N x_i$ known
- $p(s)$ a generic sampling design
- s a sample of size n from $p(s)$
- $\pi_i = \sum_{s \ni i} p(s)$ and $\pi_{ij} = \sum_{s \ni (i,j)} p(s)$ the first and second order inclusion probabilities
- $\hat{\bar{Y}}, \hat{\bar{X}}$ two unbiased estimators of \bar{Y}, \bar{X} under $p(s)$
- τ a constant that may be related to population parameters



A class of estimators for \bar{Y}

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results
Simulated π , and
 π_y
Accuracy of π , and
 π_y

Conclusions

We introduce a very simple class of estimators for \bar{Y} as

$$\hat{Y}_{pr} = \hat{Y} \frac{\bar{X} + \tau}{\hat{X} + \tau}$$

Expanding it in a Taylor's series (δ -method) and retaining only terms up to the second degree, we get - for n sufficiently large - the first order approximation of the bias (B) and mean square error (MSE)

$$B(\hat{Y}_{pr}) = \frac{1}{\bar{X} + \tau} \left[\frac{\bar{Y} \text{Var}(\hat{X})}{\bar{X} + \tau} - \text{Cov}(\hat{X}, \hat{Y}) \right]$$

$$\text{MSE}(\hat{Y}_{pr}) = \text{Var}(\hat{Y}) + \frac{\bar{Y}^2 \text{Var}(\hat{X})}{(\bar{X} + \tau)^2} - \frac{2\bar{Y} \text{Cov}(\hat{X}, \hat{Y})}{\bar{X} + \tau}$$



Optimality of the class

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information

A class of estimators

The best estimator

Simulation results

Simulated π , and

π_y

Accuracy of π , and

π_y

Conclusions

Minimization of $MSE(\hat{Y}_{pr})$ is achieved for

$$\tau = \bar{X} \frac{[C(\hat{X})^2 - C(\hat{X}, \hat{Y})]}{C(\hat{X}, \hat{Y})}$$

with $C(\hat{X}) = \sqrt{\text{Var}(\hat{X})/\bar{X}}$, $C(\hat{X}, \hat{Y}) = \text{Cov}(\hat{X}, \hat{Y})/\bar{X}\bar{Y}$. For this optimum choice, we get

$$\min MSE(\hat{Y}_{pr}) = \text{Var}(\hat{Y})(1 - \rho_{\hat{X}, \hat{Y}}^2)$$

which is the variance of the regression estimator

$$\hat{Y}_{lr} = \hat{Y} + \beta_{\hat{Y}, \hat{X}}(\bar{X} - \hat{X})$$



Optimality of the class

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_y
Accuracy of π , and
 π_y

Conclusions

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$$\hat{Y}_{lr} = \hat{Y} + \beta_{\hat{Y}, \hat{X}}(\bar{X} - \hat{X})$$

Optimality of \hat{Y}_{lr} is well-known in sampling theory but this aspect is very often overlooked. Why?



Efficiency considerations

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators

The best estimator

Simulation results

Simulated π , and
 π_y

Accuracy of π , and
 π_y

Conclusions

- All the estimators belonging to the class can be only, at best, as efficient as \hat{Y}_{lr} . They are equivalent to it only when

$$\tau = \bar{X} \frac{C(\hat{X})^2 - C(\hat{X}, \hat{Y})}{C(\hat{X}, \hat{Y})}$$



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19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators

The best estimator

Simulation results

Simulated π , and
 π_y

Accuracy of π , and
 π_y

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- For instance, the following estimators (in SRSWOR) are not optimum in the class

Authors	Estimators	τ
Sisodia and Dwivedi (1981)	$\hat{Y}_{SD} = \hat{Y} \frac{\hat{X} + C_x}{\hat{X}}$	C_x
Singh and Kakran (1993)	$\hat{Y}_{SK} = \hat{Y} \frac{\hat{X} + \beta_2(x)}{\hat{X} + \beta_2(x)}$	$\beta_2(x)$
Upadhyaya and Singh (1999)	$\hat{Y}_{US1} = \hat{Y} \frac{\bar{X}\beta_2(x) + C_x}{\hat{X}\beta_2(x) + C_x}$	$C_x/\beta_2(x)$
	$\hat{Y}_{US2} = \hat{Y} \frac{\hat{X}C_x + \beta_2(x)}{\hat{X}C_x + \beta_2(x)}$	$\beta_2(x)/C_x$



Bacanli-Kadilar estimators

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators

The best estimator

Simulation results

Simulated π , and
 π_y

Accuracy of π , and
 π_y

Conclusions

Previous estimators have been considered by Bacanli and Kadilar (2008) under UPSWOR by replacing \hat{Y} and \hat{X} with Horvitz-Thompson estimator

$$\hat{T}_{HT} = \frac{1}{N} \sum_{i \in s} \frac{t_i}{\pi_i}, \quad t = x, y$$

with

$$\text{Var}(\hat{T}_{HT}) = \frac{1}{N^2} \sum_{i=1}^N \sum_{j=1}^N \left(\frac{\pi_{ij} - \pi_i \pi_j}{\pi_i \pi_j} \right) t_i t_j, \quad t = x, y$$



Bacanli-Kadilar estimators

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators

The best estimator

Simulation results

Simulated π , and
 π_y
Accuracy of π_i and
 π_y

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- The modified estimators have been analytically compared with the ratio estimator $\hat{Y}_r = (\hat{Y}_{HT} / \hat{X}_{HT}) \bar{X}$
- Numerical comparisons have been performed by using exact expressions for π_i and π_{ij} inherited from the *adaptive cluster sampling*



Some questions

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators

The best estimator

Simulation results

Simulated π , and
 π_{ij}

Accuracy of π_i and
 π_{ij}

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1 BK estimators belong to the proposed class but they are not optimum

2 Why to compare these estimators with $\hat{Y}_r = (\hat{Y}_{HT}/\hat{X}_{HT})\bar{X}$ and not with $\hat{Y}_{lr} = \hat{Y}_{HT} + \beta_{\hat{Y}_{HT}, \hat{X}_{HT}}(\bar{X} - \hat{X}_{HT})$?

It is well-known that $MSE(\hat{Y}_r) \geq MSE(\hat{Y}_{lr})$
BK estimators can not outperform \hat{Y}_{lr}

3 The use of the exact expressions for π_i and π_{ij} from *adaptive cluster sampling* seems to be rather questionable



Some questions

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators

The best estimator

Simulation results

Simulated π , and
 π_{ij}

Accuracy of π_i and
 π_{ij}

Conclusions

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Some questions

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators

The best estimator

Simulation results

Simulated π , and
 π_{ij}

Accuracy of π_i and
 π_{ij}

Conclusions

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Some questions

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information

A class of estimators

The best estimator

Simulation results

Simulated π , and

π_{ij}

Accuracy of π , and

π_{ij}

Conclusions

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Possible solution: $\hat{\pi}_i$ and $\hat{\pi}_{ij}$



Computing π_i and π_{ij}

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π_i and
 π_{ij}

Accuracy of π_i and
 π_{ij}

Conclusions

- The explicit derivation of π_i and π_{ij} becomes prohibitive when N and/or n increase: $\binom{N}{n}$ samples are to be investigated
- To overcome the problem, a solution can be adopted by simulating π_i and π_{ij}
- implement in R the procedure drawing the PPS samples by `sample(U, n, replace=FALSE, prob=p)`



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19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π_i and
 π_{ij}
Accuracy of π_i and
 π_{ij}

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Algorithm

- each unit has a selection probability $p_i = u_i / \sum_{j=1}^N u_j$
 - $M < \binom{N}{n}$ samples WOR are independently drawn from U
 - M_i and M_{ij} are the number of samples that contain unit i and units (i, j)
 - estimate π_i and π_{ij} with $\hat{\pi}_i = M_i/M$ and $\hat{\pi}_{ij} = M_{ij}/M$
 - modify HT-estimator and its variance by using $\hat{\pi}_i$ and $\hat{\pi}_{ij}$
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19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

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A class of estimators
The best estimator

Simulation results

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 π_{ij}
Accuracy of π_i and
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19th International
Conference on
Computational
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 π_{ij}
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 π_{ij}

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19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π_i and
 π_{ij}
Accuracy of π_i and
 π_{ij}

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19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π_i and
 π_{ij}
Accuracy of π_i and
 π_{ij}

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 - 3 M_i and M_{ij} are the number of samples that contain unit i and units (i,j)
 - 4 estimate π_i and π_{ij} with $\hat{\pi}_i = M_i/M$ and $\hat{\pi}_{ij} = M_{ij}/M$
 - 5 modify HT-estimator and its variance by using $\hat{\pi}_i$ and $\hat{\pi}_{ij}$
- implement in R the procedure drawing the PPS samples by `sample(U, n, replace=FALSE, prob=p)`



Computing π_i and π_{ij}

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Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π_i and
 π_{ij}
Accuracy of π_i and
 π_{ij}

Conclusions

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Computing π_i and π_{ij}

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π_i and
 π_{ij}
Accuracy of π_i and
 π_{ij}

Conclusions

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Computing π_i and π_{ij}

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π_i and
 π_{ij}
Accuracy of π_i and
 π_{ij}

Conclusions

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Numerical examples

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_{ij}
Accuracy of π , and
 π_{ij}

Conclusions

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Numerical examples

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_{ij}
Accuracy of π , and
 π_{ij}

Conclusions

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Numerical examples

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_y
Accuracy of π , and
 π_y

Conclusions

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Numerical examples

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_{ij}
Accuracy of π , and
 π_{ij}

Conclusions

- Numerical study on real data from Cochran (1977, p. 34): weekly expenditure on food (y), weekly family income (x) and number of persons per family (z)
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Numerical examples

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_{ij}
Accuracy of π , and
 π_{ij}

Conclusions

- Numerical study on real data from Cochran (1977, p. 34): weekly expenditure on food (y), weekly family income (x) and number of persons per family (z)
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Numerical examples

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_{ij}
Accuracy of π , and
 π_{ij}

Conclusions

- Numerical study on real data from Cochran (1977, p. 34): weekly expenditure on food (y), weekly family income (x) and number of persons per family (z)
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Numerical examples

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_{ij}
Accuracy of π , and
 π_{ij}

Conclusions

- Numerical study on real data from Cochran (1977, p. 34): weekly expenditure on food (y), weekly family income (x) and number of persons per family (z)
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MSE under exact and simulated π_i and π_{ij} - SRSWOR

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_{ij}
Accuracy of π , and
 π_{ij}

Conclusions

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n	\hat{Y}_r	\hat{Y}_{lr}	\hat{Y}_{SD}	\hat{Y}_{SK}	\hat{Y}_{US1}	\hat{Y}_{US2}
10	6.119	6.098	6.118	6.122	6.119	6.154
	6.108	6.063	6.107	6.112	6.109	6.148
15	3.152	3.141	3.152	3.154	3.152	3.170
	3.148	3.14	3.145	3.147	3.145	3.162
20	1.669	1.663	1.669	1.670	1.669	1.678
	1.669	1.667	1.668	1.669	1.669	1.678



MSE under exact and simulated π_i and π_{ij} - SRSWOR

19th International Conference on Computational Statistics

Giancarlo Diana, Pier Francesco Perri

Theoretical results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π_i and π_{ij}
Accuracy of π_i and π_{ij}

Conclusions

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	1.669	1.667	1.668	1.669	1.669	1.678

- ♠ despite of the severe reduction of the cardinality of the sample space, no striking differences appear in the precision of the estimators
- ♠ small variations tend to disappear as $n \uparrow$



MSE under exact and simulated π_i and π_{ij} - SRSWOR

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Giancarlo Diana, Pier Francesco Perri

Theoretical results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π_i and π_{ij}
Accuracy of π_i and π_{ij}

Conclusions

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MSE under exact and simulated π_i and π_{ij} - Midzuno UPS

19th International Conference on Computational Statistics

Giancarlo Diana, Pier Francesco Perri

Theoretical results

Auxiliary information

A class of estimators

The best estimator

Simulation results

Simulated π , and

π_{ij}

Accuracy of π , and

π_{ij}

Conclusions

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n	Method	\hat{Y}_r	\hat{Y}_{lr}	\hat{Y}_{SD}	\hat{Y}_{SK}	\hat{Y}_{US1}	\hat{Y}_{US2}
10	Midzuno	5.978	5.498	5.976	5.988	5.980	6.064
	Est. prob.	5.813	4.945	5.796	5.917	5.832	6.665
15	Midzuno	3.102	2.963	3.102	3.106	3.103	3.134
	Est. prob.	2.877	2.065	2.870	2.925	2.886	3.267
20	Midzuno	1.649	1.606	1.649	1.650	1.649	1.663
	Est. prob.	1.405	0.886	1.401	1.425	1.408	1.571



MSE under exact and simulated π_i and π_{ij} - Midzuno UPS

19th International Conference on Computational Statistics

Giancarlo Diana, Pier Francesco Perri

Theoretical results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and π_{ij}
Accuracy of π_i and π_{ij}

Conclusions

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- ♣ **UPS with $\hat{\pi}_i$ and $\hat{\pi}_{ij}$ offers the best solution if compared with the Midzuno scheme (and SRSWOR)**
- ♣ \hat{Y}_{lr} outperforms all the other estimators whatever n
- ♣ the gain in efficiency rises as $n \uparrow$



MSE under exact and simulated π_i and π_{ij} - Midzuno UPS

19th International Conference on Computational Statistics

Giancarlo Diana, Pier Francesco Perri

Theoretical results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and π_{ij}
Accuracy of π_i and π_{ij}

Conclusions

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MSE under exact and simulated π_i and π_{ij} - Midzuno UPS

19th International Conference on Computational Statistics

Giancarlo Diana, Pier Francesco Perri

Theoretical results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and π_{ij}
Accuracy of π_i and π_{ij}

Conclusions

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Final remarks

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_{ij}
Accuracy of π_i and
 π_{ij}

Conclusions

- Numerical comparisons based on the first order MSE seem to be not affected by n
- When using auxiliary information at the estimation stage, the optimal estimator is the regression estimator. No improvement upon it can be achieved, at least up to the first order of approximation
- The awareness of this aspect should avoid the proliferation of estimators that appear different each others but whose efficiency is known in advance
- When using UPS, the cumbersome problem of the explicit derivation of π_i and π_{ij} can be reduced by their estimation over a limited number of samples



Final remarks

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_{ij}
Accuracy of π_i and
 π_{ij}

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Final remarks

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_{ij}
Accuracy of π_i and
 π_{ij}

Conclusions

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Final remarks

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_{ij}
Accuracy of π , and
 π_{ij}

Conclusions

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Thanks for your attention



References

19th International
Conference on
Computational
Statistics

Giancarlo Diana,
Pier Francesco
Perri

Theoretical
results

Auxiliary information
A class of estimators
The best estimator

Simulation results

Simulated π , and
 π_y
Accuracy of π , and
 π_y

Conclusions

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