

# Monotone Graphical Multivariate Markov Chains

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# Outline

## Multivariate Markov chains

Dynamic relations among marginal processes

Multi edge graphs

Parametric models for transition probabilities

Testing equality and inequality constraints

Example

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# Graphical models for Markov chains

The idea of graphical models is to represent the dependence structure of a multivariate random vector by a graph, where the nodes correspond to the variables and the edges between nodes describe the association structure among the variables

***We apply a graphical approach to analyze the dynamic relationships among the marginal processes of a multivariate Markov chain***

# Graphical models for Markov chains

*We apply a graphical approach to analyze the dynamic relationships among the marginal processes of a multivariate Markov chain*

## **Our graphical approach offers:**

- ▶ a graphical representation that allows a direct and intuitive understanding of the dynamic associations which can exist among the processes of an MMC
- ▶ the possibility to investigate potential causal, monotone dependence and contemporaneous relationships by testing simple hypotheses on parameters

## Multivariate Markov chain: basic notation

$$\mathbf{A}_{\mathcal{V}} = \{A_j(t) : t = 0, 1, 2, \dots, \quad j \in \mathcal{V}\} \quad \mathcal{V} = \{1, \dots, q\}$$

- ▶ an **univariate process**  $A_j(t)$  takes values on  $\mathcal{A}_j = \{1, 2, \dots, s_j\}$   $j \in \mathcal{V}$
- ▶ for  $\mathcal{S} \subset \mathcal{V}$ , a **marginal process** is  $\mathbf{A}_{\mathcal{S}} = \{A_j(t) : t = 0, 1, 2, \dots, j \in \mathcal{S}\}$
- ▶  $\bar{\mathbf{A}}_{\mathcal{V}}(t-1) = \{A_{\mathcal{V}}(r) : r \leq t-1\}$  is the **past** history up to  $t-1$  of  $\mathbf{A}_{\mathcal{V}}$
- ▶  $\times_{j \in \mathcal{V}} \mathcal{A}_j$  is the **joint state space**

$\mathbf{A}_{\mathcal{V}}$  is a **first order multivariate Markov chain** (with  $q$  components)

$$A_{\mathcal{V}}(t) \perp\!\!\!\perp \bar{\mathbf{A}}_{\mathcal{V}}(t-2) | A_{\mathcal{V}}(t-1) \quad \forall t = 1, 2, \dots$$



In general, different types of dependence relations are relevant when the time dimension of the variables is taken into account:

- ▶ the **effect of the past** of a process **on the present** of another
  - ↔ **Granger non-causality**
  - ↔ **monotone dependence coherent with a stochastic ordering**
  
- ▶ the relation among processes **at the same time**
  - ↔ **contemporaneous dependence**

## Dynamic relations

Given 2 disjoint marginal processes  $\mathbf{A}_{\mathcal{T}}$  and  $\mathbf{A}_{\mathcal{S}}$   
of an MMC  $\mathbf{A}_{\mathcal{V}}$

► i) *Granger non-causality condition*

$\mathbf{A}_{\mathcal{T}}$  is not Granger caused by  $\mathbf{A}_{\mathcal{S}}$  with respect to  $\mathbf{A}_{\mathcal{V}}$

$$\Leftrightarrow A_{\mathcal{T}}(t) \perp\!\!\!\perp A_{\mathcal{S}}(t-1) | A_{\mathcal{V} \setminus \mathcal{S}}(t-1) \quad \forall t = 1, 2, \dots$$

**the past of  $\mathbf{A}_{\mathcal{S}}$  does not contain additional information on the present of  $\mathbf{A}_{\mathcal{T}}$ , given the past of  $\mathbf{A}_{\mathcal{V} \setminus \mathcal{S}}$**

## Dynamic relations

Given 2 disjoint marginal processes  $\mathbf{A}_{\mathcal{T}}$  and  $\mathbf{A}_{\mathcal{S}}$   
of an MMC  $\mathbf{A}_{\mathcal{V}}$

► ii) *Contemporaneous independence condition*

$\mathbf{A}_{\mathcal{T}}$  and  $\mathbf{A}_{\mathcal{S}}$  are contemporaneously conditionally independent  
with respect to  $\mathbf{A}_{\mathcal{V}}$

$$\Leftrightarrow A_{\mathcal{T}}(t) \perp\!\!\!\perp A_{\mathcal{S}}(t) | A_{\mathcal{V}}(t-1) \quad \forall t = 1, 2, \dots$$

**two marginal processes are independent at each time point,  
given past information on all processes of the chain**

# ME graphs

## a Multi Edge graph

encodes the G-noncausal and contemporaneous independence relations among the marginal processes of an MMC

in an ME graph  $G = (\mathcal{V}, \mathcal{E})$ , the nodes in the set  $\mathcal{V}$  represent the univariate components of an MMC and directed and bi-directed edges in the set  $\mathcal{E}$  describe the dependence structure among them

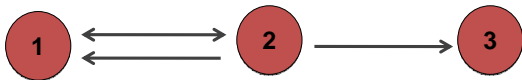
## In a multi edge graph

- ▶ there exists a one-to-one correspondence between the nodes  $j \in \mathcal{V}$  and the univariate processes  $\mathbf{A}_j, j \in \mathcal{V}$ , of the MMC  $\mathbf{A}_{\mathcal{V}}$
- ▶ any pair of nodes,  $i, k \in \mathcal{V}$ , may be joined by directed edges  $i \rightarrow k, i \leftarrow k$ , and by bi-directed edge  $i \leftrightarrow k$
- ▶ each pair of distinct nodes can be connected by up to all the 3 types of edges
- ▶ sets of G-noncausality and contemporaneous independence restrictions are associated with missing directed and bi-directed edges, respectively
- ▶ Example  $\mathcal{V} = \{1, 2, 3\}$   $\mathcal{E} = \{2 \rightarrow 1, 2 \rightarrow 3, 1 \leftrightarrow 2\}$



## Graph terminology

- ◇ if there is  $i \rightarrow j$ , then  $i$  is a *parent* of  $j$ ,  
 $Pa(S) = \{i \in \mathcal{V} : i \rightarrow j \in \mathcal{E}, j \in S\}$  is the *set of parents* of  $S \subset \mathcal{V}$
- ◇ if there is  $i \leftrightarrow j$ , the nodes  $i, j$  are *neighbors*,  
 $Nb(S) = \{i \in \mathcal{V} : i \leftrightarrow j \in \mathcal{E}, j \in S\}$  is the *set of neighbors* of  $S \subset \mathcal{V}$



- ✓ in the example:  $Pa(1) = \{1, 2\}$ ,  $Pa(2) = \{2\}$ ,  $Pa(3) = \{2, 3\}$ ;  
 $Nb(1) = \{1, 2\}$ ,  $Nb(2) = \{1, 2\}$ ,  $Nb(3) = \{3\}$

# Graphical models

***Graphical models associate missing edges of a graph with some conditional independence restrictions imposed on a multivariate probability distribution***

***In the multi edge graphical models for MMC  
missing edges have a direct significance in terms of  
G-noncausal and contemporaneous independence restrictions  
imposed on the transition probabilities***

# Markov properties of ME graphs

## Graphical MMC

An MMC is graphical with respect to an ME graph  $G = (\mathcal{V}, \mathcal{E})$  iff its transition probabilities satisfy the following conditional independencies for all  $t = 1, 2, \dots$

$$\mathbf{C1)} \quad A_{\mathcal{S}}(t) \perp\!\!\!\perp A_{\mathcal{V} \setminus Pa(\mathcal{S})}(t-1) | A_{Pa(\mathcal{S})}(t-1) \quad \forall \mathcal{S} \in \mathcal{P}(\mathcal{V})$$

$$\mathbf{C2)} \quad A_{\mathcal{S}}(t) \perp\!\!\!\perp A_{\mathcal{V} \setminus Nb(\mathcal{S})}(t) | A_{\mathcal{V}}(t-1) \quad \forall \mathcal{S} \in \mathcal{P}(\mathcal{V})$$



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$$\mathbf{C2)} \quad A_S(t) \perp\!\!\!\perp A_{\mathcal{V} \setminus Nb(S)}(t) | A_{\mathcal{V}}(t-1) \quad \forall S \in \mathcal{P}(\mathcal{V})$$

### Condition C1)

- ▶ the past of  $A_{\mathcal{V} \setminus Pa(S)}$  is not informative for the present of  $A_S$  as long as we know the past of  $Pa(S)$
- ▶ is a **G-noncausality** condition
- ▶  $A_{\mathcal{V} \setminus Pa(S)} \not\leftrightarrow A_S$ , i.e.  **$A_S$  is not G-caused by  $A_{\mathcal{V} \setminus Pa(S)}$  wrt  $A_{\mathcal{V}}$**
- ▶ corresponds to missing directed edges
- ▶ refers to processes at two consecutive time-points

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$$\mathbf{C2)} \quad \mathbf{A_S}(t) \perp\!\!\!\perp \mathbf{A_{\mathcal{V} \setminus Nb(S)}}(t) | \mathbf{A_{\mathcal{V}}}(t-1) \quad \forall S \in \mathcal{P}(\mathcal{V})$$

## Condition C2)

- ▶  $\mathbf{A_S}$  and  $\mathbf{A_{\mathcal{V} \setminus Nb(S)}}$  are independent of each other at any point in time as long as we know the past of  $\mathbf{A_{\mathcal{V}}}$
- ▶ is a **contemporaneous independence** condition
- ▶  $\mathbf{A_S} \leftrightarrow \mathbf{A_{\mathcal{V} \setminus Nb(S)}}$ , i.e.  $\mathbf{A_S}$  and  $\mathbf{A_{\mathcal{V} \setminus Nb(S)}}$  are contemporaneously independent wrt  $\mathbf{A_{\mathcal{V}}}$
- ▶ corresponds to missing bi-directed edges
- ▶ refers to processes at the same time-points

Example: Reading G-noncausal and CI restrictions **C1)** and **C2)** off an ME graph



- ▶ the G-noncausality conditions associated to the missing directed edges in the graph are:

$$\mathbf{A}_{\{1,3\}} \not\Rightarrow \mathbf{A}_2; \quad \mathbf{A}_1 \not\Rightarrow \mathbf{A}_{\{2,3\}}; \quad \mathbf{A}_3 \not\Rightarrow \mathbf{A}_{\{1,2\}}$$

- ▶ the contemporaneous independence condition associated to the missing bi-directed edges in the graph is:

$$\mathbf{A}_3 \Leftrightarrow \mathbf{A}_{\{1,2\}}$$

# Monotone dependence

Given 2 variables  $A_j$  and  $A_k$   
with ordered categories in the sets  $\mathcal{A}_j$  and  $\mathcal{A}_k$

if a **monotone dependence of  $A_j$  on  $A_k$  exists:**

the conditional distributions of  $A_j$  given  $A_k$   
become stochastically greater in a coherent way with the order of the  
categories of  $A_k$  in  $\mathcal{A}_k$

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## Stochastic orderings

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## Stochastic orderings

### Simple

$$(A_j|A_k = k) \preceq_s (A_j|A_k = k + 1) \iff P[A_j \leq j|A_k = k] \geq P[A_j \leq j|A_k = k + 1]$$

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## Stochastic orderings

### Uniform

$$(A_j|A_k = k) \preceq_u (A_j|A_k = k + 1) \iff P[A_j > j|A_j \geq j, A_k = k] \leq P[A_j > j|A_j \geq j, A_k = k + 1]$$

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## Stochastic orderings

Likelihood ratio

$$(A_j|A_k = k) \preceq_{lr} (A_j|A_k = k + 1) \iff \frac{P[A_j=j|A_k=k]}{P[A_j=j+1|A_k=k]} \leq \frac{P[A_j=j|A_k=k+1]}{P[A_j=j+1|A_k=k+1]}$$



## Monotone Graphical MMC

A graphical MMC is monotone with respect to an ME graph  $G = (\mathcal{V}, \mathcal{E})$  iff there exists at least one  $A_j, j \subseteq \mathcal{V}$ , whose dependence on its parents is monotone

- ▶ the dependence of  $A_j(t)$  on  $A_k(t-1), \forall k \in Pa(j)$ , is monotone  $\forall t$
- ▶ the distributions of  $A_j(t)$  conditioned by  $A_{Pa(j)}(t-1)$  can be partially ordered coherently with the orderings on the sets  $\mathcal{A}_k, k \in Pa(j)$  according to a stochastic dominance criterion (*simple, uniform, LR*)
- ▶ NB. the dominance criterion concerns only the marginal processes in an MMC and does not refer to their joint behavior

# A multivariate logistic model for transition probabilities

**G-noncausality, CI and monotone dependence conditions are equivalent to equality and inequality constraints on interactions of a multivariate logistic model which parameterize the transition probabilities**

- ▶  $\mathcal{I} = \times_{j \in \mathcal{V}} \mathcal{A}_j$  is the joint state space
- ▶  $\mathbf{i} = (i_1, i_2, \dots, i_q)' \in \mathcal{I}$  is a state
- ▶ for a pair of states  $\mathbf{i} \in \mathcal{I}$ ,  $\mathbf{i}' \in \mathcal{I}$ ,  $p(\mathbf{i} | \mathbf{i}')$  are the joint transition probabilities

# A multivariate logistic model for transition probabilities

Given  $\mathbf{i}' \in \mathcal{I}$ ,

for  $p(\mathbf{i} | \mathbf{i}')$ ,  $\mathbf{i} \in \mathcal{I}$ , we adopt a Glogoneck-McCullagh multivariate logistic model whose marginal interaction parameters

$$\eta^P(\mathbf{i}_P | \mathbf{i}') \quad P \subseteq \mathcal{V}, P \neq \emptyset, \mathbf{i}_P \in \times_{j \in P} \mathcal{A}_j$$

are contrasts of logarithms of marginal transition probabilities  $p(\mathbf{i}_P | \mathbf{i}')$

- ▶ G-noncausality and CI relations correspond to equality constraints on the  $\eta^P(\mathbf{i}_P | \mathbf{i}')$  while hypotheses of monotone dependence impose inequality constraints on  $\eta^P(\mathbf{i}_P | \mathbf{i}')$

- └ Parametric models for transition probabilities
- └ Testing equality and inequality constraints

## Testing dynamic relations

For an MMC with  $p(\mathbf{i}|\mathbf{i}^*) > 0$  it holds that, for  $\mathbf{i}_P \in \times_{j \in P} \mathcal{A}_j$

- ▶ G-noncausality condition **C1**)  $\Leftrightarrow \eta^P(\mathbf{i}_P|\mathbf{i}^*) = \eta^P(\mathbf{i}_P|\mathbf{i}_{Pa(P)}^*)$ ,  $P \subseteq \mathcal{V}$ ,  $P \neq \emptyset$
- ▶ CI condition **C2**)  $\Leftrightarrow \eta^P(\mathbf{i}_P|\mathbf{i}^*) = 0$   $P$  is not a bi-connected set

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▶ CI condition **C2**)  $\Leftrightarrow \eta^P(\mathbf{i}_P|\mathbf{i}') = 0$   $P$  is not a bi-connected set

▶ the requirements **C1**), **C2**) for a graphical MMC correspond to simple linear constraints on the  $\eta^P(\mathbf{i}_P|\mathbf{i}')$  parameters

▶ testing the hypotheses **C1**), **C2**) is a standard parametric problem

▶ the restrictions under **C1**), **C2**) can be rewritten as  $C \ln(M\pi) = \mathbf{0}$

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- └ Parametric models for transition probabilities
- └ Testing equality and inequality constraints

# Testing monotone dependence

For a graphical MMC with  $p(\mathbf{i} | \mathbf{i}^*) > 0$  it holds that

- ▶ positive (**negative**) monotone dependence

$\Leftrightarrow$

$$\eta^j(\mathbf{i}_j | \mathbf{i}_{Pa(j) \setminus k}^*, i_k) \leq (\geq) \eta^j(\mathbf{i}_j | \mathbf{i}_{Pa(j) \setminus k}^*, i_k + 1),$$

$$k \in Pa(j), j \in \mathcal{M}, \mathcal{M} \subseteq \mathcal{V}, \mathcal{M} \neq \emptyset$$



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- ▶ The simple, uniform and likelihood ratio orderings are obtained when the logits  $\eta^j(\mathbf{i}_j | \mathbf{i}_{Pa(j)}^*)$  subjected to inequality constraints are of global, continuation and local types
- ▶ the inequality constraints for monotone dependence have a compact expression given by  $K \ln(M\pi) \geq 0$

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- └ Parametric models for transition probabilities
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## Likelihood ratio tests

- ▶  $H_G: \mathbf{C} \ln(\mathbf{M}\boldsymbol{\pi}) = \mathbf{0}$  (graphical MMC)
- $H_M: \mathbf{C} \ln(\mathbf{M}\boldsymbol{\pi}) = \mathbf{0}, \mathbf{K} \ln(\mathbf{M}\boldsymbol{\pi}) \geq \mathbf{0}$  (monotone graphical MMC)
- $H_U$ : unrestricted model
- ▶  $L_G, L_M, L_U$  denote the max log-likelihood functions under  $H_G, H_M, H_U$

## Likelihood ratio tests

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### Testing equality constraints: $H_G$ vs $H_U$

under suitable assumptions (*Fahrmeir and Kaufmann, 1987*)

⇒ **the null asymptotic distribution of the statistic**

$$LRT = 2(L_U - L_G) \text{ is } \chi^2$$

## Likelihood ratio tests

- ▶  $H_G: C \ln(M\pi) = \mathbf{0}$  (graphical MMC)
- $H_M: C \ln(M\pi) = \mathbf{0}, K \ln(M\pi) \geq \mathbf{0}$  (monotone graphical MMC)
- $H_U$ : unrestricted model
- ▶  $L_G, L_M, L_U$  denote the max log-likelihood functions under  $H_G, H_M, H_U$

### Testing inequality constraints: $H_M$ vs $H_G$ and $H_M$ vs $H_U$

- ▶ under suitable assumptions (*Fahrmeir and Kaufmann, 1987*)
- ▶ the parametric space under  $H_M$  is defined by linear inequality constraints

$\Rightarrow$  the statistics  $LRT = 2(L_G - L_M)$  and  $LRT = 2(L_U - L_M)$   
 are asymptotically chi-bar-squared  $\bar{\chi}^2$  distributed  
 ( $\bar{\chi}^2$  is a mixture of  $\chi^2$ 's, *Silvapulle and Sen, 2005*)

- └ Parametric models for transition probabilities
- └ Testing equality and inequality constraints

## Computational procedures:

- ▶ ML estimation methods for multinomial data under equality and inequality constraints are adapted to the MMC context
- ▶ Monte Carlo methods to simulate the asymptotic p-values of the LRT statistics  $2(L_G - L_M)$  and  $2(L_U - L_M)$
- ▶ procedures for computing ML estimates and p-values are implemented in the R-package *hmmm* by Colombi

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## In summary, our approach provides

missing directed and bi-directed edges in ME graph



G-noncausality and CI conditions



linear constraints on interactions which parameterize  
the transition probabilities

monotone dependence



inequality constraints on interactions which parameterize  
the transition probabilities

► Example: ME graph for pasta spaghetti data

DATA:

- binary data collected on 365 days (Dec. 2006 - Jan. 2009) by an Italian wholesale dealer
- a 3-dimensional binary time series of sales levels of 3 Italian brands (*Amato*  $A_1$ , *Barilla*  $A_2$ , *Divella*  $A_3$ ) of pasta (*spaghetti*)
- 3-variate Markov chain of spaghetti data  $\{A_1, A_2, A_3\}$  with categories: low and high level

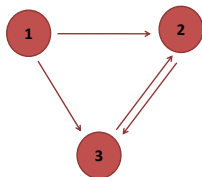


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the MC of spaghetti data is monotone graphical wrt the ME graph



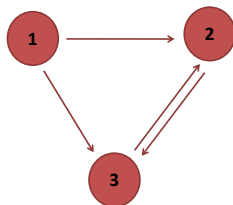
- test for CI:  $LRT = 44.81, p = 0.44$
- test for G-noncausality and monotone dep.  $LRT = 0, p = 1$

- ▶ Example: ME graph for pasta spaghetti data

the graph encodes:

the G-noncausality and CI relations:

$$\mathbf{A}_{\{2,3\}} \not\rightarrow \mathbf{A}_1, \mathbf{A}_1 \leftrightarrow \mathbf{A}_2 \leftrightarrow \mathbf{A}_3$$



- ▶ the current sales level of *Amato* does not depend on previous sales of *Divella* or *Barilla*
- ▶ there is no influence between the contemporaneous sales of all 3 brands

► Example: ME graph for pasta spaghetti data

the graph encodes:

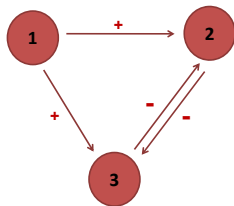
+ monotone dependence

for  $1 \rightarrow 1$ ,  $2 \rightarrow 2$ ,  $3 \rightarrow 3$ ,

$1 \rightarrow 2$ ,  $1 \rightarrow 3$

- monotone dependence

for  $2 \rightarrow 3$  and  $3 \rightarrow 2$



- sales of all brands depend positively on their own previous sales levels
- a high level of sales of *Barilla* and *Divella* on one day is more probable when the quantity which *Amato* previously sold was high
- given previous high sales level of *Divella*, a low level of *Barilla* sales is more probable, and vice versa

*THANKS FOR  
YOUR ATTENTION!!*