

Threshold Accepting for Credit Risk Assessment and Validation

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1 Introduction

- Basel II and credit risk clustering
- Optimal size and number of clusters

2 Ex-post validation

- Actual number of defaults

3 Optimal buckets

4 Conclusion

- Summary - Outlook
- For further reading

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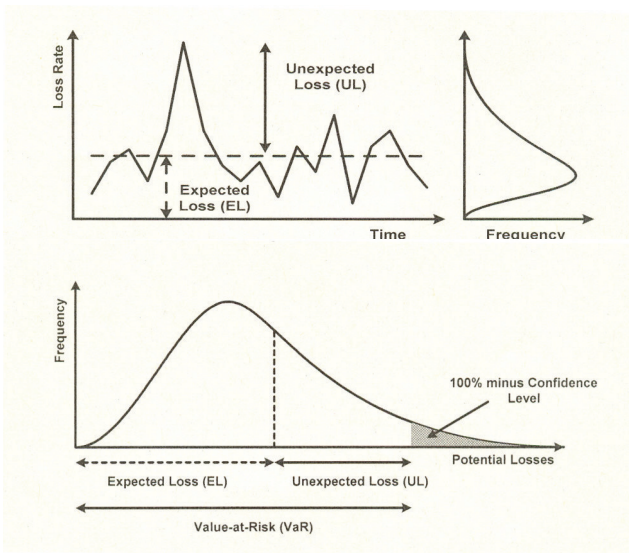
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Basel II and credit risk clustering



Regulatory Capital

Accurate regulatory capital calculation.

Credit Risk Bucketing

- Step 1: Compute borrowers' probability of default (p_k)

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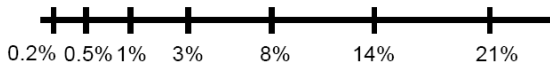
- Step 1: Compute borrowers' probability of default (p_k)

Regulatory Capital

Accurate regulatory capital calculation.

Credit Risk Bucketing

- Step 2: Assign borrowers to groups (grades)

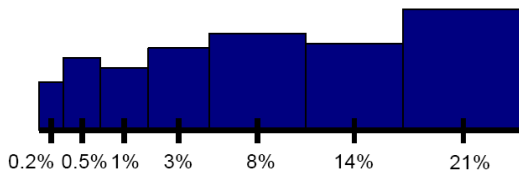


Regulatory Capital

Accurate regulatory capital calculation.

Credit Risk Bucketing

- Step 3: Compute MCR for each grade (based on its \bar{p}_g)



Regulatory Capital

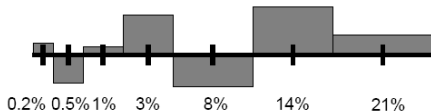
Accurate regulatory capital calculation.

Credit Risk Bucketing

- Step 1: Compute borrowers' probability of default (p_k)
- Step 2: Assign borrowers to groups (grades)
- Step 3: Compute MCR for each grade (based on its \bar{p}_g)
- **Approximation Error**

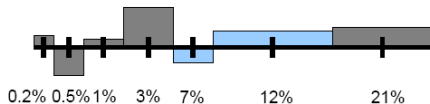
Approximation Error

Using \bar{p}_g instead of individual p_k causes a loss in precision.



Meaningful assignment of borrowers to clusters

Choose appropriate size and number of clusters to minimize over/understatement of MCR and allow statistical ex-post validation



Optimal Credit Risk Rating System

Choose appropriate size and number of grades

(Ex post)

- *Predicts defaults correctly*

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Validate Actual Number of Defaults

Predicted correctly if $D_g^a \in [D_{g,l}^f; D_{g,u}^f]$ with confidence $1-\alpha$

- $D_{g,l}^f = n_g \cdot \max(\bar{p}_g - \varepsilon, 0)$
- $D_{g,u}^f = n_g \cdot \min(\bar{p}_g + \varepsilon, 1)$

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Model actual defaults as binary variable

$$\mathbb{P}_{int} = \mathbb{P} \left(D_{g,l}^f \leq D_g^a \leq D_{g,u}^f \right)$$

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- $D_{g,l}^f = n_g \cdot \max(\bar{p}_g - \varepsilon, 0)$
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Binomial distribution

$$\mathbb{P}_{int} = \sum_{k=D_{g,l}^f}^{D_{g,u}^f} \binom{n_g}{k} \bar{p}_g^k (1 - \bar{p}_g)^{n_g - k} \geq 1 - \alpha.$$

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- Objective function for minimizing within grades variance

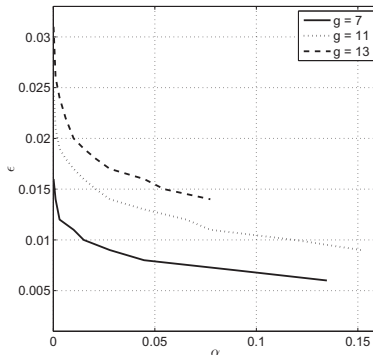
$$\min \sum_g \sum_{k \in g} \left(\bar{p}_{c,g} - p_{c,k} \right)^2 \quad (1)$$

- Objective function for minimizing regulatory capital

$$\min \sum_g \sum_{k \in g} 1.06 \cdot \left| UL \left(\bar{p}_g \right) - UL \left(p_k \right) \right| \quad (2)$$

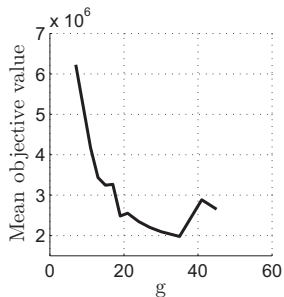
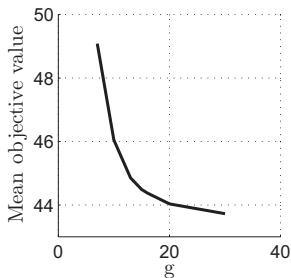
Feasible region

Minimizing regulatory capital using the validation technique
($\alpha = 1.5\%$, $\varepsilon = 1\%$)



Optimum bucket setting

Within grades variace (left), Regulatory capital (right)



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Summary

- Minimum capital requirements to cover unexpected losses
- Threshold Accepting to cluster loans with real-world constraints
- Optimal size and number of buckets based on ex-post validation

Outlook

- Relax default risk independence constraint
- Alternative assumptions for actual default distributions



P. Winker.

On Optimization Heuristics in Econometrics: Applications of Threshold Accepting.

Wiley, New York, 2001.



Basel Committee on Banking Supervision.

Capital Standards a Revised Framework.

Bank for International Settlements, 2006.



M. Lyra and J. Paha and S. Paterlini and P. Winker.

Optimization Heuristics for Determining Internal Rating Grading Scales.

Computational Statistics & Data Analysis, Article in Press.



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Validation Structural Credit Portfolio Models.

In: Model Risk in Finance, forthcoming.

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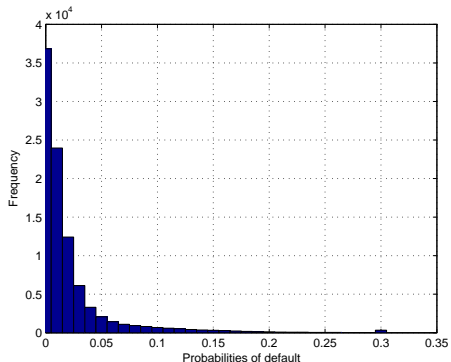
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Data description

- portfolio of 93 580 retail borrowers.
- LGDs range between 0.17 and 1.
- p_k vary from 0.000001% to 30%.



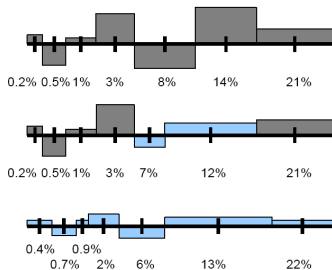
Credit Risk Assignment - Side Constraints

- Enforced by constraint handling techniques
 - \bar{p}_g in bucket $\not\leq 0.03\%$
 - Each bucket $\not\leq 35\%$ of total bank exposure
- Considered in the structure of the algorithm
 - No bucket overlapping
 - Buckets correspond to all borrowers

Optimization Heuristics

Optimal partition of k bank clients in g clusters

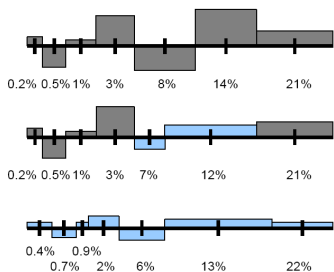
- 1 Generate random starting thresholds (candidate solution)
- 2 Alter current candidate solution
- 3 Accept or reject new candidate solution
- 4 Repeat until a very good solution is found



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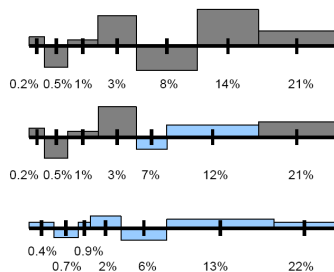
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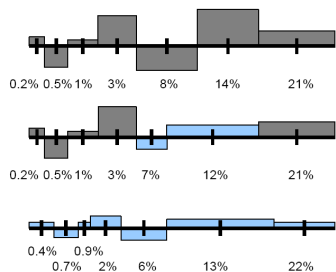
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Threshold Accepting - The Basic Idea

- Generate a random candidate solution and determine its objective function value
- Repeat a predefined number of iterations
 - Modify candidate solution and determine its objective function value
 - Replace current solution with modified solution if new solutions yields
 - An improved objective function value or
 - A deterioration that is smaller than some threshold (predefined by a threshold sequence)

Algorithm 1 Threshold Accepting Algorithm.

- 1: Initialize n_R , n_{S_τ} , and $\tau_r, r = 1, 2, \dots, n_R$
 - 2: Generate at random a solution $x^0 \in [\alpha_l \alpha_u] \times [\beta_l \beta_u]$
 - 3: **for** $r = 1$ to n_R **do**
 - 4: **for** $i = 1$ to n_{S_τ} **do**
 - 5: Generate neighbor at random, $x^1 \in \mathcal{N}(x^0)$
 - 6: **if** $f(x^1) - f(x^0) < \tau_r$ **then**
 - 7: $x^0 = x^1$
 - 8: **end if**
 - 9: **end for**
 - 10: **end for**
-

Threshold Accepting - Candidate Solutions

- Starting Candidate Solution
 - For g buckets, select $g-1$ upper bucket thresholds from actual pds
 - Discrete search \Rightarrow Each solution constitutes a new partition
- New Candidate Solution
 - Determine some bucket threshold of current solution randomly
 - Replace with new pd from interval [next lower threshold; next higher threshold]
 - Shrink interval linearly in the number of iterations;
 $[(I + 1) - i]/I$

Threshold Accepting - Updating Objective Function Values

- Alter only one bucket threshold per iteration
- New objective function differs from that of the current solution only in contribution of two buckets
- Only compute those two buckets' fitness and update objective function value of current solution
- Consequence: Tremendous increase in search speed

Threshold Accepting - Threshold Sequence

- Idea: Use mean of last 100 weighted fitness differences (in absolute values) as threshold T
- If last fitness differences were mainly
 - improvements, T shrinks \Rightarrow Stay on path to (local) optimum
 - deteriorations, T increases \Rightarrow Overcome (local) optimum and search for a new one
- Weights (w_1, w_2) for restrictive threshold sequence
 - Fitness improvement (frequent and high at the beginning of the search) $\Rightarrow w_1 = i/l$
 - Fitness deterioration (frequent and high at the end of the search) $\Rightarrow w_2 = 1 - i/l$
- Scale above means with $(1-i/l)$ for further restrictiveness

Algorithm 2 Pseudocode for TA with data driven generation of threshold sequence.

```

1: Initialize  $l$ ,  $Ls = (0, \dots, 0)$  of length 100
2: Generate at random an initial solution  $x^c$ , set  $\tau = f(x^c)$ 
3: for  $i = 1$  to  $l$  do
4:   Generate at random  $x^n \in \mathcal{N}(x^c)$ 
5:   Delete first element of  $Ls$ 
6:   if  $f(x^n) - f(x^c) < 0$  then
7:     add  $|f(x^n) - f(x^c)| \cdot (i/l)$  as last element to  $Ls$ 
8:   else
9:     add  $|f(x^n) - f(x^c)| \cdot (1 - i/l)$  as last element to  $Ls$ 
10:  end if
11:   $\tau = \overline{Ls} \cdot (1 - i/l)$ 
12:  if  $f(x^n) - f(x^c) < \tau$  then
13:     $x^c = x^n$ 
14:  end if
15: end for

```

Constraint Handling - Rejection Technique in TA

- Both candidate solutions are feasible
 - TA: Select the new candidate if $f(g_n) + T \leq f(g_c)$
- One solution is feasible, select the feasible
- No feasible solution
 - Select fewer violations
 - Select with regard to fitness
 - TA: Select the new candidate if $f(g_n) + T \leq f(g_c)$

Constraint Handling - Penalty Technique in TA

- Penalize candidate solutions' objective value by a factor $A \in [1; 3.7183] \Rightarrow f_c(g) = f_u(g) \cdot A$
- A rises in the number of iterations i and the degree of constraint violation $a \in [0; 1] \Rightarrow A = \left(1 + \exp\left(\frac{i}{T}\right)\right)^a$
- $a = 1$, if
 - all buckets besides one are empty, and
 - EAD is concentrated in one bucket.
- Select the new candidate if $f_c(g_n) + T \leq f_c(g_c)$

Table: Objective function for minimizing within grades variance(1)

	Best	Mean	Worst	s.d.	q90%	Freq
			g = 7			
TA ^a	18.6836	18.6836	18.6836	$3.6731 \cdot 10^{-8}$	18.6836	8/10
TA ^b	18.6552	24.4809	46.2984	8.2478	24.8221	1/10
			g = 10			
TA ^a	9.7293	9.7293	9.7293	$5.3490 \cdot 10^{-7}$	9.7293	1/10
TA ^b	9.1118	10.3545	10.9233	0.8520	10.9108	1/10
			g = 13			
TA ^a	6.6716	6.6716	6.6716	$2.9353 \cdot 10^{-6}$	6.6716	1/10
TA ^b	6.5974	10.0515	14.5469	2.7151	12.4890	1/6
			g = 16			
TA ^a	5.2454	5.2454	5.2454	$1.9032 \cdot 10^{-6}$	5.2454	1/10
TA ^b	10.3647	10.3647	10.3647	0.0000	10.3647	1/1

^aActual number of defaults constraint^bUnexpected loss constraint

Table: Objective function for minimizing unexpected losses (2)

	Best	Mean	Worst	s.d.	q90%	Freq
			$g = 7$			
TA ^a	6,228,874	6,228,874	6,228,874	$9.8170 \cdot 10^{-10}$	6,228,874	10/10
TA ^b	6,419,727	6,423,788	6,426,403	2,053	6,420,826	1/10
			$g = 11$			
TA ^a	4,165,257	4,167,952	4,182,902	5,999	4,165,257	7/10
TA ^b	5,534,072	5,636,388	5,814,094	101,283	5,538,839	1/10
			$g = 13$			
TA ^a	3,425,092	3,435,627	3,436,798	3,701.71	3,436,798	1/10
TA ^b	5,192,945	5,608,280	5,929,156	230,630	5,846,709	1/9
			$g = 15$			
TA ^a	3,245,441	3,245,636	3,247,260	571.05	3,245,445	1/10
TA ^b	5,627,306	6,285,472	7,166,148	647,632	6,945,510	1/3

^aActual number of defaults constraint^bUnexpected loss constraint