

COMPSTAT 2010

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Score moment estimates

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August 17, 2010

Motivation

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- Instead of $f(x; \hat{\theta}_{ML})$, a few numbers characterizing the data would be useful in further analysis. However, moments $m_k = E(X - m_1)^k$, $m_1 = EX$ are often queer expressions containing special functions, and moments of heavy-tailed distributions do not exist, so that the approach $\hat{m}_k = m_k(\hat{\theta}_{ML})$ is not used

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- Complex problems are solved by using 'pure' data not 'adapted' to the assumed model by an adequate inference function (Pearson correlation coefficient)

Problem

- The reason: The score function $r(x; \theta) = (r_{\theta_1}, \dots, r_{\theta_m})$, $r_{\theta_j}(x; \theta) = \frac{\partial}{\partial \theta_j} \log f(x; \theta)$, is a *vector function*, suitable for estimation of parameters, but too complicated to afford useful proposals of sensible numeric characteristics of distributions and too complicated to be used in more complex problems

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- The problem: To find a relevant scalar inference function $S(x; \theta)$ reflecting basic features of the model distribution, and to use moments

$$M_k(\theta) = \int_{\mathcal{X}} S^k(x; \theta) f(x; \theta) dx$$

for generalized moment estimates

Location distributions

- Location distribution $g(y - \mu)$, $\mu \in \mathbb{R}$, g unimodal, regular, with support \mathbb{R}

Scalar score

$$r_{\mu}(y; \mu) = \frac{\partial}{\partial \mu} \log g(y - \mu) = S_G(y - \mu)$$

where function

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- Scalar score of a distribution with support \mathbb{R}

$$S_G(y; \theta) = -\frac{1}{g(y; \theta)} \frac{d}{dy} g(y; \theta)$$

Log-location distributions - I

The log-location distribution (Lawless 2003) F of random variable $X = \eta^{-1}(Y)$ with support $\mathcal{X} = (0, \infty)$ has density

$$f(x; \tau) = g(u)\eta'(x),$$

where $g(y - \mu)$ is the density of 'prototype' distribution on \mathbb{R} ,

$$u = \eta(x) - \eta(\tau)$$

and the 'log-location' parameter $\tau = \eta^{-1}(\mu)$ is the 'image' of the location μ of the prototype

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- Scalar score

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- t-score (a general concept)

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where (Johnson, 1949)

$$\eta(x) = \begin{cases} \log(x - a) & \text{if } \mathcal{X} = (a, \infty) \\ \log \frac{(x - a)}{(b - x)} & \text{if } \mathcal{X} = (a, b) \end{cases}$$

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- However, to use relation $\frac{\partial}{\partial \tau} \log f(x; \theta) = \eta'(\tau) T(x; \theta)$,
 θ has to be in the form $\theta = (\eta^{-1}(\mu), \theta_2, \dots, \theta_m)$

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- τ is usually taken as scale parameter, but $\tau = \eta^{-1}(\mu)$ and $T(\tau; \theta) = 0$. Perhaps the most important value is not the parameter, but the 'center' of the distribution itself

Definitions

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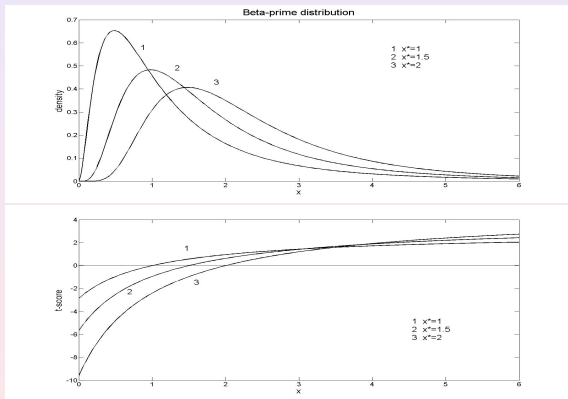
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- $E_{\theta} S^2$ Fisher information for x^*

Example: Scalar scores of beta-prime distribution

$$f(x) = \frac{1}{B(p,q)} \frac{x^{p-1}}{(x+1)^{p+q}} \quad T(x) = \frac{qx-p}{x+1} \quad x^* = \frac{p}{q} \quad S(x) = \frac{q}{p} \frac{qx-p}{x+1}$$



Consequences

- Measure of variability: Score variance: the reciprocal Fisher information

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- Estimates: Important are not the estimates of θ , but the sample t-mean $\hat{x}^* = x^*(\hat{\theta}_{ML})$ and sample score standard deviation $\hat{\omega} = \omega(\hat{\theta}_{ML})$, which make possible to compare results for various models with different parameters

Score moment estimators

- $\hat{\theta}_{SM}$ by a generalized moment method

$$\frac{1}{n} \sum_{i=1}^n S^k(x_i; \theta) = E_{\theta} S^k, \quad k = 1, \dots, m$$

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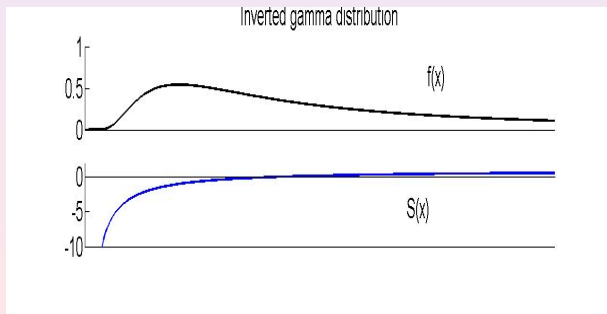
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- Scalar scores of heavy-tailed distributions are bounded: estimates are robust
- In cases of heavy-tailed distributions, estimates have asymptotic efficiencies ~ 0.9 .

Inverted gamma distribution

Support $(0, \infty)$, densities and t-scores

$$f(x) = \frac{\gamma^\alpha}{x\Gamma(\alpha)} x^{-\alpha} e^{-\gamma/x} \quad T(x) = \alpha - \gamma/x$$

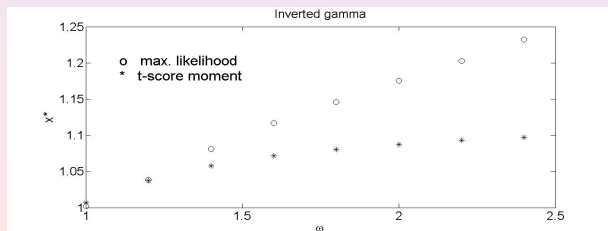
$$x^* = \frac{\gamma}{\alpha}, ET^2 = \alpha, \omega^2 = \frac{(x^*)^2}{ET^2} = \frac{\gamma^2}{\alpha^3}, S(x) = \frac{\alpha^2}{\gamma} (1 - x^*/x)$$



Estimation

$$\sum_{i=1}^n (1 - x^*/x_i) = 0$$
$$\frac{1}{n} \sum_{i=1}^n (1 - x^*/x_i)^2 = \alpha$$

\hat{x}^* is the harmonic mean



Generalized beta family

Support $\mathcal{X} = (0, \infty)$ and densities

$$f(x; \tau, \alpha, \nu) = \frac{1}{\nu^\alpha B(\nu\alpha, \alpha)} \frac{(x/\tau)^{\nu\alpha-1}}{[(x/\tau) + 1/\nu]^{(1+\nu)\alpha}}$$

where B is the beta function. The t-score is

$$T(x; \tau; \alpha, \nu) = \alpha \frac{(x/\tau) - 1}{(x/\tau) + 1/\nu}$$

The first three t-score moments $ET = 0$, $ET^2 = \frac{\nu}{(\nu+1)\alpha+1}$

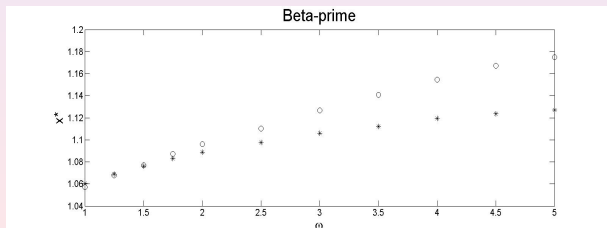
$ET^3 = \frac{2\nu(1-\nu)}{[(\nu+1)\alpha+1][(\nu+1)\alpha+2]}$ are independent of τ

Generalized beta family, $\tau = 1$

By setting $\tau = 1$ we obtain equations

$$\hat{\nu} : \sum_{i=1}^n \frac{x_i - 1}{x_i + 1/\hat{\nu}} = 0$$

and $\hat{\alpha} = (\hat{\nu}/\rho - 1)/(\hat{\nu} + 1)$, where $\rho = \frac{1}{n} \sum_{i=1}^n \left(\frac{x_i - 1}{x_i + 1/\hat{\nu}} \right)^2$



Estimation of the Threshold Parameter

Uniform distribution on $[0, \gamma]$. ML estimator is $\hat{\gamma}_{ML} = x_{(n)}$. The t-score is

$$T(x) = \frac{2x}{\gamma} - 1,$$

so that

$$\frac{1}{n} \sum_{i=1}^n \frac{2x_i}{\gamma} = 1$$

The score moment solution

$$\hat{\gamma}_{SM} = \max(x_{(n)}, 2\bar{x})$$

For $n = 5, 10, 20$ and 50 we obtained after 10 000 experiments $\hat{\gamma}_{ML} \approx 0.87, 0.91, 0.95$ and 0.98 , respectively, whereas $\hat{\gamma}_{SM} = 1$ with accuracy to three decimal points

Confidence intervals

for \hat{x}_{SM}^* can be established by the modification of the Rao score test or by the use of the distance

$$d(\hat{x}_{SM}^*, x_0) = \frac{|S(\hat{x}_{SM}^*) - S(x_0)|}{ES^2}$$

As

$$\omega^2 = \frac{1}{ES^2} = \frac{(x^*)^2}{ET^2}$$

$$\hat{\omega} = \frac{\hat{x}_{SM}^*}{\left[\frac{1}{n} \sum_{i=1}^n T^2(x_i; \hat{x}_{SM}^*)\right]^{1/2}}$$

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