

Generalized Linear Factor Models: a local EM estimation

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Motivations

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Social Sciences, Biology, Environment, ... →

Quantitative measures
Qualitative characteristics
Counts
Life times

= Miscellaneous types of variables

$B(1, p); B(n, p)$
 $M(1; p_1, p_k); M(n; p_1, p_k)$
 $P(\lambda); \gamma(k, \lambda); etc.$

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Abundant

& related

⇒ Dimension reduction

⇒ Correlation modeling

Model & notations

Data:

Observed on n observation units $\{1, \dots, t, \dots, n\}$:

p variables $\{y_1, \dots, y_p\}$

→

$$y_t = (y_{it})_{i=1, p} \\ (p, 1)$$

underlying

q latent factors $\{f_1, \dots, f_q\}$

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$$f_t = (f_{jt})_{j=1, q} \\ (q, 1)$$

$q < p$

Observation units are independent

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Factor Model:

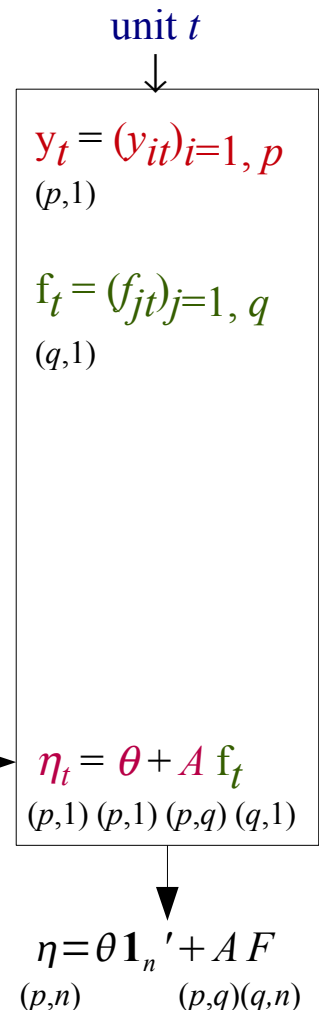
$$\forall t, \mathbf{f}_t \sim N(0; I_q)$$

Factors f_j generate linear predictors of variables y_i

\rightarrow linear predictor of $y_{it} | \mathbf{f}_t$: $\eta_{it} = \theta_i + a_i' \mathbf{f}_t$

$$A = (a_1, \dots, a_p)' ; \boldsymbol{\theta} = (\theta_i)_i ; F = (\mathbf{f}_1, \dots, \mathbf{f}_t, \dots, \mathbf{f}_n) ;$$

$$\boldsymbol{\eta}_t = (\eta_{it})_i ; \boldsymbol{\eta} = (\eta_{it})_{i,t} = (\boldsymbol{\eta}_1, \dots, \boldsymbol{\eta}_t, \dots, \boldsymbol{\eta}_n)$$



Model & notations

Model of y conditional to F :

$\forall t, \mathbf{y}_t | \mathbf{f}_t \sim \wp_t \in$ Exponential family (Nelder & Wedderburn): $l_i(y_{it} | \delta_{it}, \phi) = \exp\left(\frac{y_{it} \delta_{it} - b_i(\delta_{it})}{a_{it}(\phi)} + c_i(y_{it}, \phi)\right)$

$\forall t, (y_{it})_i | \mathbf{f}_t$ are \perp

$$\begin{aligned} \mu_{it} &= E(y_{it}) = b_i'(\delta_{it}) \\ \text{Var}(y_{it}) &= a_{it}(\phi) b_i''(\delta_{it}) \\ &= a_{it}(\phi) \underbrace{b_i''(b_i'^{-1}(\mu_{it}))}_{v_i(\mu_{it})} \end{aligned}$$

Conditional variance matrix: $\text{Var}(y_t) = \text{diag}\{a_{it}(\phi) v_i(\mu_{it})\}_{i=1,p}$

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Link with linear predictor:

$$\forall i, t: \eta_{it} = g_i(\mu_{it})$$

link
function

$$\delta_{it} = \text{canonical parameter} ; g_i = b_i'^{-1} \Rightarrow \eta_{it} = \delta_{it}$$

canonical
link

The classical Gaussian Linear Factor Model: $y_{it} | \mathbf{f}_t \sim N(\mu_{it}; \sigma^2)$ with $\mu_{it} = \eta_{it}$

Factor Models: available estimation techniques

The classical Gaussian Linear Factor Model:

EM algorithm estimation:

A is estimated by maximizing the expectation, conditional to observations, of the derivative of the completed log-likelihood (EDLCO), integrated with respect to the factors:

⇒ taking the conditional expectation of the 1st order conditions: $\sum_t E(\nabla \log l(y_t, f_t) | y_t) = 0$

= possible because EDLCO is analytically determined

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Generalized Linear Factor Models:

Expectation of EDLCO not analytically determined → Direct EM impossible

Computationally intensive

[Moustaki, I., & Knott, M. (2000)] → Max of the expected completed log- Likelihood, single factor; Gauss-Hermite quadrature used to approximate integral.

[Wedel, M. & Kamakura, W.A. (2001)] → Monte Carlo approach

[Moustaki, I & Victoria-Feser, M.P.(2006)] → Iterative estimation method inspired from the indirect inference technique [Gourieroux (1993)].

Looking back at GLM's

GLM:

GLM of one variable y , depending on predictors $X = (x_j)_{j=1,q}$

$$\mu = E(y)$$

Linear predictor: $\eta = X\beta \quad \forall t, \eta_t = g(\mu_t) \Rightarrow x_t'\beta = g(b'(\delta_t))$

Log-likelihood: $L(\delta; y) = \sum_{t=1}^n L_t(\delta_t; y_t) = \sum_{t=1}^n \left(\frac{y_t \delta_t - b(\delta_t)}{a_t(\phi)} + c(y_t, \phi) \right)$

Derivation / β : $\frac{\partial L_t}{\partial \beta_j} = \frac{\partial \eta_t}{\partial \beta_j} \frac{\partial \mu_t}{\partial \eta_t} \frac{\partial \delta_t}{\partial \mu_t} \frac{\partial L_t}{\partial \delta_t} = x_{tj} \frac{1}{g'(\mu_t)} \frac{1}{b''(\delta_t)} \frac{y_t - \mu_t}{a_t(\phi)} \rightarrow = V(y_t) = a_t(\phi)v(\mu_t)$

Let: $W_\beta = \text{diag} \left(g'(\mu_t)^2 V(y_t) \right)_{t=1,n} = \text{diag} \left(g'(\mu_t)^2 a_t(\phi)v(\mu_t) \right)_{t=1,n}$;

$$\frac{\partial \eta}{\partial \mu} = \text{diag} \left(\frac{\partial \eta_t}{\partial \mu_t} \right)_{t=1,n} = \text{diag} \left(g'(\mu_t) \right)_{t=1,n}$$

Then: $\nabla_{\beta} L = 0 \Leftrightarrow X'W_\beta^{-1} \frac{\partial \eta}{\partial \mu} (y - \mu) = 0$ **non linear / β**

interpretable as normal equations of a linear model

Looking back at GLM's

Fisher's scores algorithm:

$$\beta^{[k+1]} = \beta_{\uparrow}^{[k]} - \left(E \left[\frac{\partial^2 L}{\partial \beta \partial \beta'} \right]^{[k]} \right)^{-1} \left(\frac{\partial L}{\partial \beta} \right)^{[k]} = \beta^{[k]} - \left(X' W_{\beta^{[k]}}^{-1} X \right)^{-1} X' W_{\beta^{[k]}}^{-1} \left(\frac{\partial \eta}{\partial \mu} \right)^{[k]} (y - \mu^{[k]})$$

$$= \left(X' W_{\beta^{[k]}}^{-1} X \right)^{-1} X' W_{\beta^{[k]}}^{-1} \underbrace{\left(X \beta^{[k]} + \left(\frac{\partial \eta}{\partial \mu} \right)^{[k]} (y - \mu^{[k]}) \right)}_{z^{[k]} = \text{working variable}}$$

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$$\Leftrightarrow X' W_{\beta}^{-1} (z - X \beta) = 0 \quad \text{normal equations of lin. model } M: z_{\beta} = X \beta + \zeta ; E(\zeta) = 0$$

$$V(\zeta_t) = V(z_{\beta,t}) = g'^2(\mu_t) V(y_t) : V(\zeta) = W_{\beta}$$

$$\text{Current linearized model: } M^{[k]} : z_{\beta} = X \beta + \zeta^{[k]} ; E(\zeta^{[k]}) = 0, V(\zeta^{[k]}) = W_{\beta^{[k]}}$$

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iteration nr. \uparrow

$$= \beta^{[k]} - \left(X' W_{\beta^{[k]}}^{-1} X \right)^{-1} X' W_{\beta^{[k]}}^{-1} \left(\frac{\partial \eta}{\partial \mu} \right)^{[k]} (y - \mu^{[k]})$$

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Current linearized model: $M^{[k]}: z_{\beta} = X \beta + \zeta^{[k]} ; E(\zeta^{[k]}) = 0, V(\zeta^{[k]}) = W_{\beta^{[k]}}$

Iterative GLS estimation:

0) Initializing $M^{[0]}$ with OLS of $g(y)$ on $X \rightarrow \beta^{[0]}$

$$g(y) \approx g(\mu) + g'(\mu) (y - \mu) = X \beta + \left(\frac{\partial \eta}{\partial \mu} \right) (y - \mu) = z$$

i) $\beta^{[k]} \rightarrow W_{\beta^{[k]}} ; z_{\beta^{[k]}}$

Repeat until convergence

ii) GLS on $M^{[k]} \rightarrow \beta^{[k]}$

= Quasi-Likelihood Estimation (QLE) = mimics MLE on each step, under a normality and independence assumption of the $z_{\beta,t}$'s with a fixed covariance structure.

The Local EM algorithm

The idea: GLFM = GLM model conditional to F
 = FM model within the linearized model locally mimicking this GLM

Local QLE of GLM mimics MLE of a *gaussian linear model*
Gaussian linear factor models may be estimated through EM

EM used on the linearized model
 in Fisher's scores algorithm

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The algorithm:

► (i) Conditional to θ, A, F , calculate:

$$\varepsilon_{i,F} = y_i - \mu_{i,F} \quad \zeta_{i,F} = g'(\mu_{i,F}) \varepsilon_{i,F} \quad z_{i,F} = \theta_i \mathbf{1}_n + F a_i + \zeta_{i,F}$$

(ii) Given Z and $V(\zeta)$, we have the linearized *marginal* model:

$\forall t=1, n: z_t = \theta + A f_t + \zeta_t$ viewed as a non-standard FM estimated through an **EM step, yielding F** :

$$f_t \sim N(0, I_k) \Rightarrow V(z_t) = \Sigma_t = A A' + \Psi_t \text{ with } \Psi_t = \text{diag}(g'^2(\mu_{i,f_t}) V(\varepsilon_{it} | f_t))_{i=1,p}$$

$$\begin{aligned} \text{If } g = \text{canonical link: } \text{Var}(\varepsilon_{it}) = \text{Var}(y_{it}) &= a_{it}(\phi) b_i''([b_i^{-1}(\mu_{it})]) = a_{it}(\phi) g_i^{-1}([g_i(\mu_{it})]) = a_{it}(\phi) / g_i'(\mu_{it}) \\ &\Rightarrow \Psi_t = \text{diag}(a_{it}(\phi) g'(\mu_{i,f_t}))_{i=1,p} \quad \rightarrow \text{EM uses } \Sigma_t \end{aligned}$$

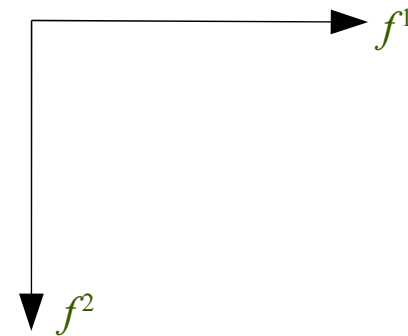
(iii) Given F , we have the linearized *conditional* model, viewed as a GLM \rightarrow FSA updates θ and A using variance matrix: $V(z_t | F_t) = V(\zeta_t) = \Psi_t$

A quick review of performances on simulated data

Model : Poisson

$\forall t = 1 \text{ to } 400, \forall i = 1, 40: y_{it} | \mathbf{f}_t \sim \wp(e^{\eta_{it}})$ independently

Simulation using 2 $\mathcal{N}(0;1)$ factors: $\mathbf{f}_t = (f_t^1, f_t^2): \eta_{it} = \theta_i + a_{i1} f_t^1 + a_{i2} f_t^2$



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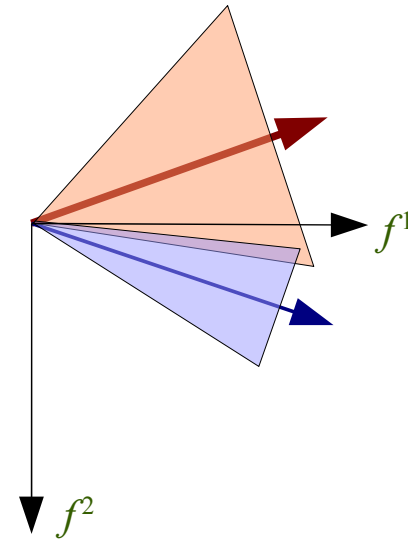
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40 “observed” variables y^i structured in 2 bundles + noise:

Bundle 1: y^1 to y^{25}

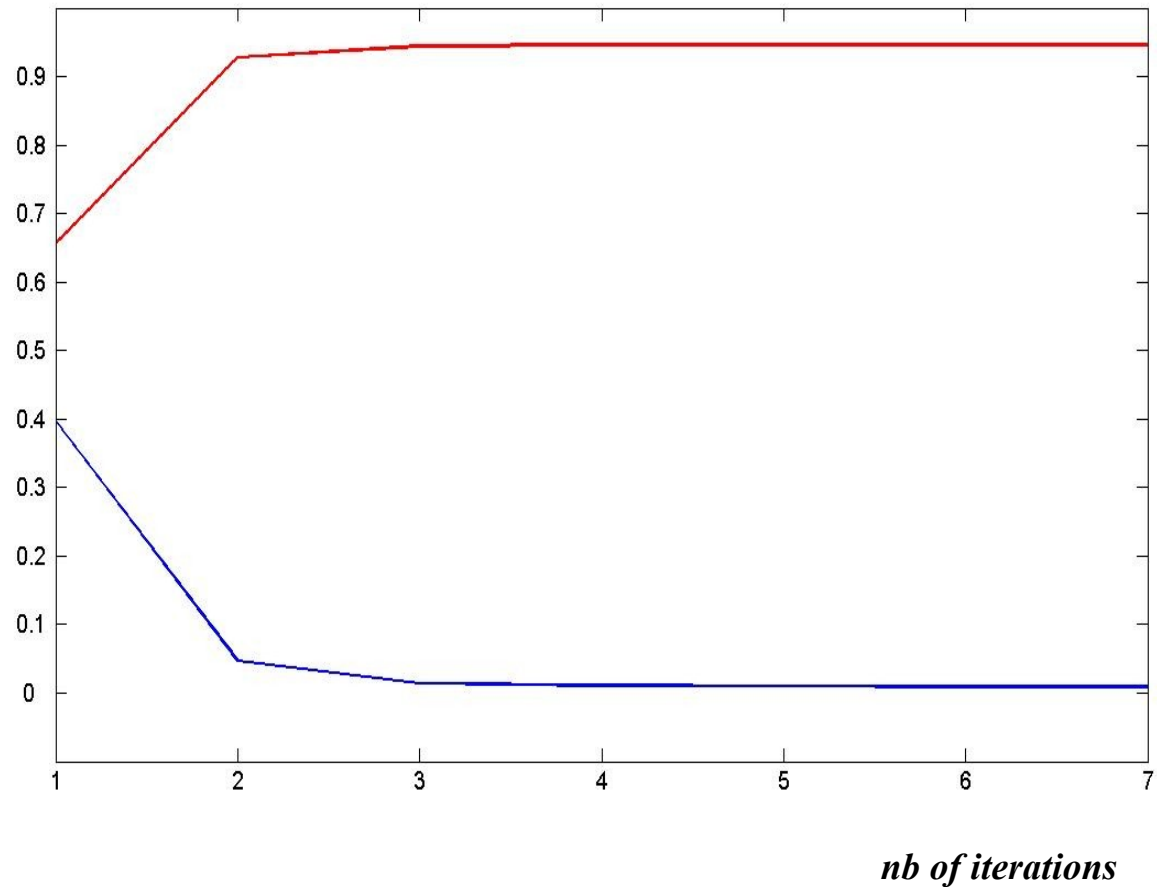
Bundle 2: y^{26} to y^{40}



A quick review of performances on simulated data

Convergence facts:

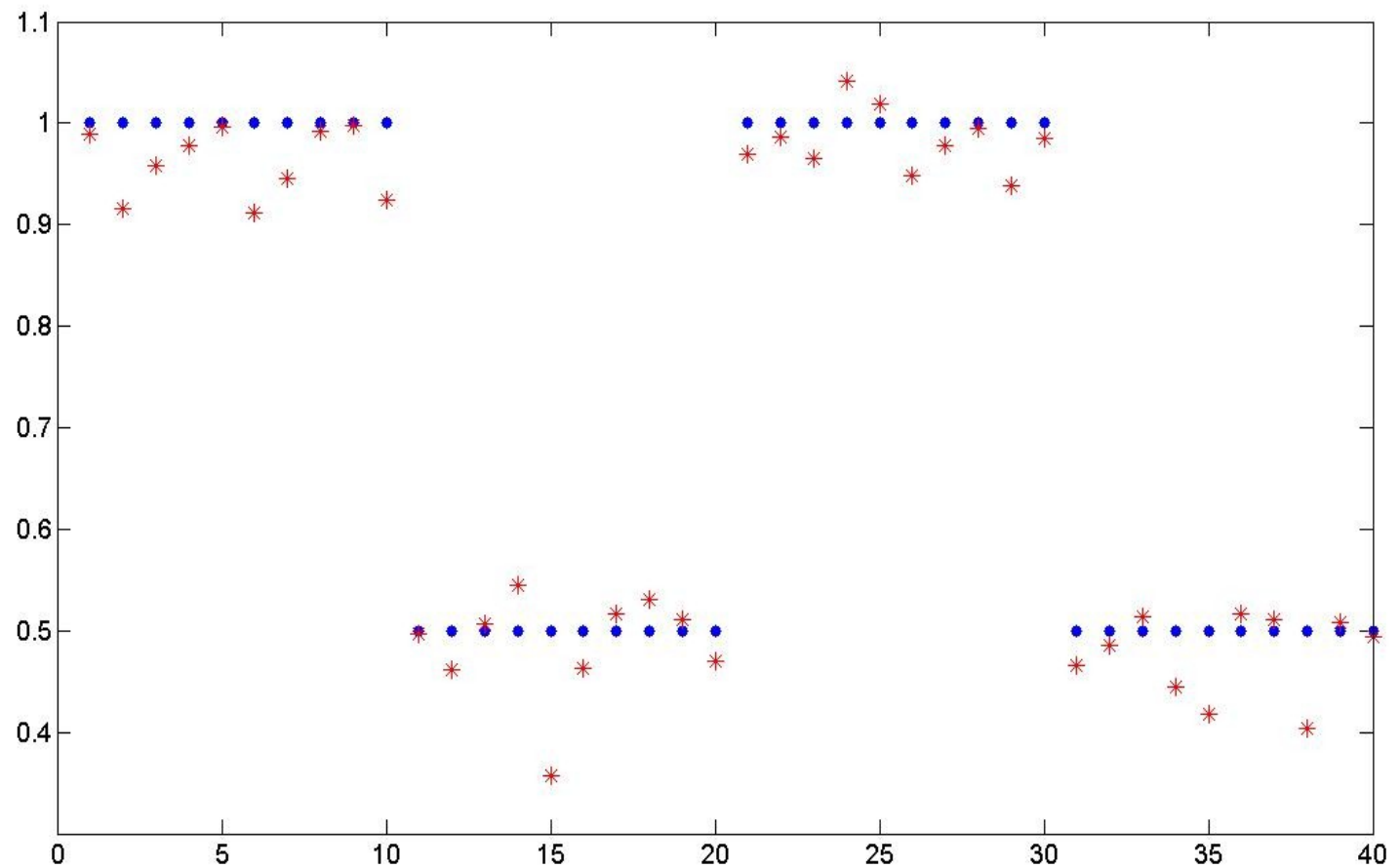
Average correlation between real factors and estimated ones:



A quick review of performances on simulated data

Estimation accuracy:

*Means: real values
vs estimates:*

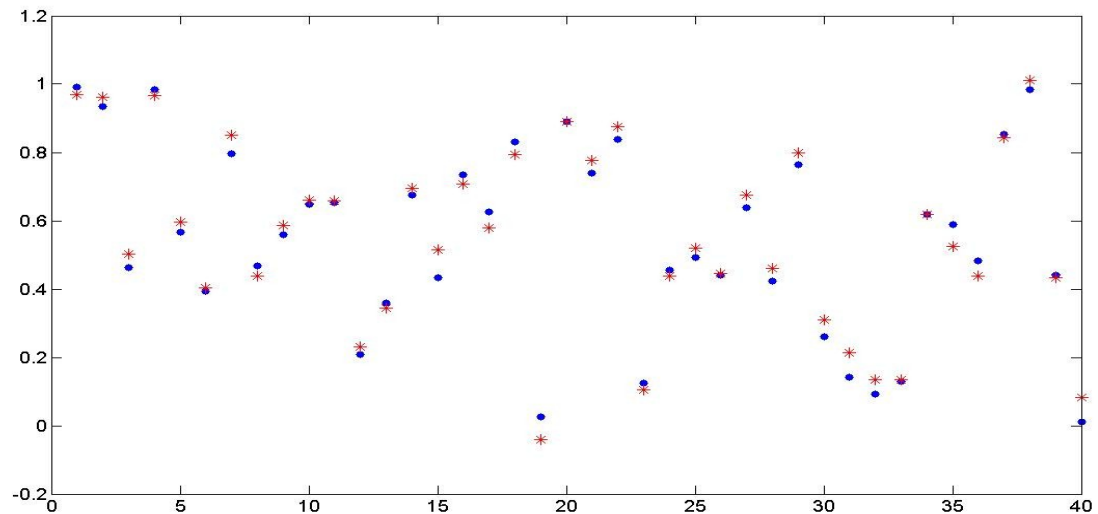


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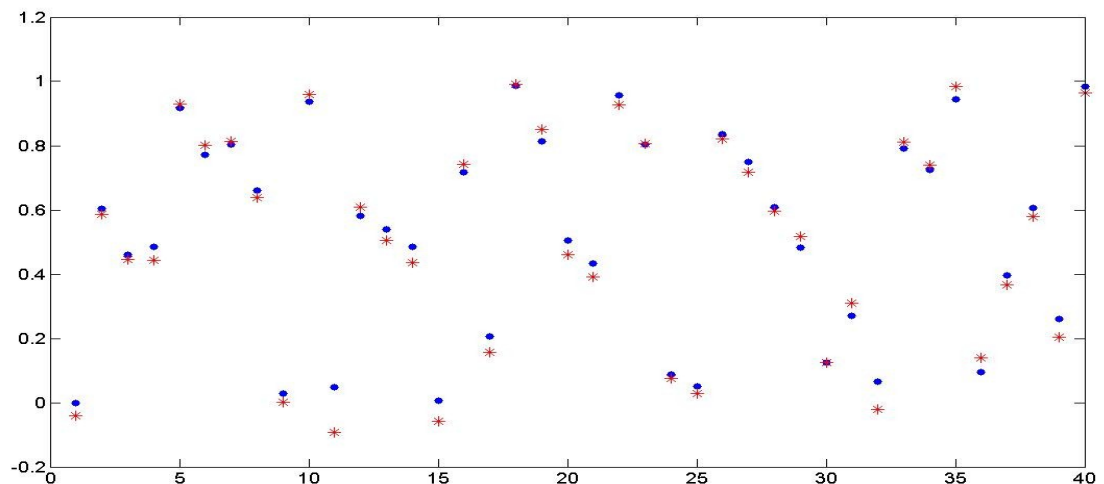
Estimation accuracy:

Coefficients a_{ij} : real values vs estimates:

Factor 1:



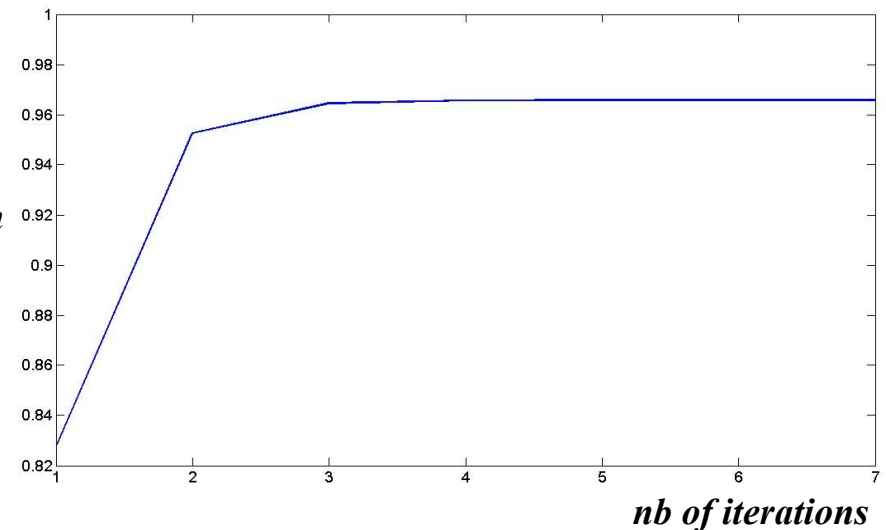
Factor 2:



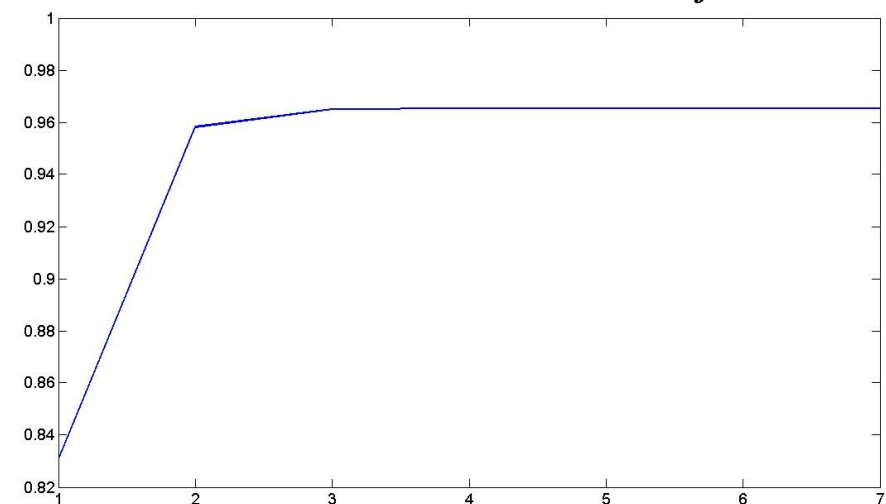
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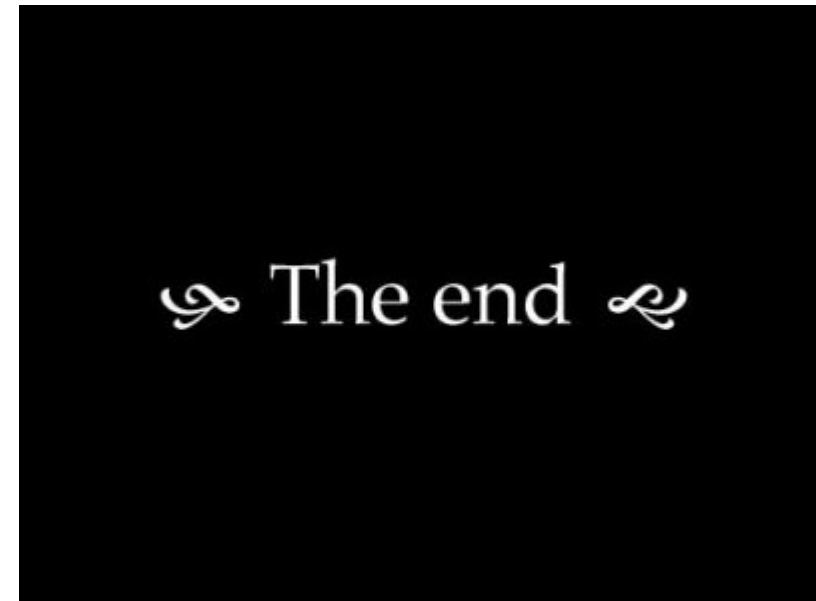
When simulation coefficients do not meet identification constraints...

R^2 of real factor f_1 on estimated $\langle f_1, f_2 \rangle$:



R^2 of real factor f_2 on estimated $\langle f_1, f_2 \rangle$:





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