## Determining the Direction of the Path Using a Bayesian Semiparametric Model

Kei Miyazaki Nagoya University JSPS Research Fellow

> Takahiro Hoshino Nagoya University

> Kazuo Shigemasu Teikyo University

## Outline

- 1. Introduction
  - 1-1 parameter estimation methods when the error variables are nonnormal
  - 1-2 semiparametric Bayesian estimation methods
- 2. Research purpose
- Determining the direction of the path using a Bayesian semiparametric model —an application of Dirichlet process priors—
- 3. Simulation studies
  - 3-1 Simulation 1 when the explanatory variables are normal —
  - 3-2 Simulation 2 when the explanatory variables are nonnormal —
  - 3-3 Simulation 3 when the nonlinear regression model is assumed —
- 4. Conclusion

## Introduction

- In behavioral sciences, we face a situation where the observed variables do not follow normal distributions
- $\rightarrow$ when the data are obtained from heterogeneous populations
- the methods that do not require normality for the error variables are required
- Asymptotic distribution free method (Browne, 1984) → used only when the sample size is large
- Estimation method when the error variables follow the elliptical distributions (Kano, Berkane & Bentler, 1993)→ it is necessary to assume symmetric distributions

## Introduction

 An estimation method that uses a higher-order moment structure sparked interest among researchers in this field (Bentler, 1983; Shimizu & Kano, 2008)

 $\rightarrow$ This method can be applied to data that are generated from very skewed distributions

 $\rightarrow$ this method makes it possible to determine the direction of path among the models that have the same values of goodness of fit (that is, equivalent models)

## **Bayesian estimation**

- Several features are pointed out
- 1. Not based on asymptotic theory
- 2. Derivation of theoretically correct predictive distributions
- 3. We can assume any complex models
- 4. we can compare several models accurately by using marginal likelihoods

## Marginal likelihood

- Chib (1995) suggested a calculation method for the marginal likelihood from the Gibbs output
- The following identity is used

$$m(\mathbf{y}) = \frac{f(\mathbf{y}|\theta)\pi(\theta)}{\pi(\theta|\mathbf{y})}$$

Substituting the posterior means for the parameter, and taking logarithms,

$$\log \hat{m}(\mathbf{y}) = \log f(\mathbf{y}|\theta^*) + \log \pi(\theta^*) - \log \hat{\pi}(\theta^*|\mathbf{y})$$

The terms in the right side of the above equation are to be calculated

The problem is to calculate  $\,\widehat{\pi}( heta^*|\mathbf{y})\,$ 

## Marginal likelihood

• The posterior distributions is expressed as follows

$$\pi(\theta^*|\mathbf{y}) = \pi(\theta_1^*|\mathbf{y}) \times \pi(\theta_2^*|\mathbf{y}, \theta_1^*) \times \cdots \times \pi(\theta_B^*|\mathbf{y}, \theta_1^*, \cdots, \theta_{B-1}^*)$$

Each term in the right side of the above equation is calculated as follows

$$\widehat{\pi}(\theta_r^* \mid \mathbf{y}, \theta_s^*(s < r)) = G^{-1} \sum_{j=1}^G \pi(\theta_r^* \mid \mathbf{y}, \theta_1^*, \theta_2^*, \cdots, \theta_{r-1}^*, \theta_l^{(j)}(l > r))$$

Marginal likelihood is calculated using the following equation

$$\log \hat{m}(\mathbf{y}) = \log f(\mathbf{y}|\theta^*) + \log \pi(\theta^*) - \sum_{r=1}^{B} \log \hat{\pi}(\theta^*_r|\mathbf{y}, \theta^*_s(s < r))$$
<sup>7</sup>

## **Bayesian estimation**

- Several features are pointed out
- 1. Not based on asymptotic theory
- 2. Derivation of theoretically correct predictive distributions
- 3. We can assume any complex models
- 4. we can compare several models accurately by using marginal likelihoods
- it is necessary to make a distributional assumption for random variables in existing general Bayesian estimation method
- $\rightarrow\,$  is it impossible to perform estimation for any assumed shape of distributions for the parameters

#### Solution approach: Dirichlet process priors

- Ferguson(1973, 1974) proposed
- Assuming Dirichlet prior distribution  $DP(\gamma, G_0)$

for  $\theta$  that is the parameter of the distribution of random variable  $U_{i}$ 

 $\infty$ 

$$egin{aligned} U &\sim \sum\limits_{l=1} p_l f(\cdot| heta_l) \ \end{aligned}$$
 where  $p_l = \prod_{m=1}^{l-1} (1-V_m) V_l, \ V_l \sim \mathsf{Be}(1,\gamma) \end{aligned}$ 

(definition by Sethuraman(1994))

→Any distributions can be expressed as mixture distributions of conventional distributions such as normal distributions

# Finite Dirichlet process prior distribution

- Using L-dimensional finite Dirichlet process prior distribution  $DP_L(\gamma,G_0)$  ,

$$\boldsymbol{U} \sim \sum_{l=1}^{L} p_l f(\cdot | \theta_l)$$

which approximates Dirichlet process prior distributions with satisfactory accuracy when *L* is large (Ishwaran & Zarepour, 2000)

 Ishwaran & James (2001) proposed Blocked Gibbs Sampler as a parameter estimation algorithm when finite Dirichlet process prior distribution is assumed

### Research purposes

- We show Bayesian solution method for analyzing nonnormal data using Dirichlet process priors and calculation method of marginal likelihood
- We set two Dirichlet process mixture models wherein the explanatory and dependent variables are alternated with each other, calculate the marginal likelihoods and compare the resulting values
- We evaluate the performance of marginal likelihoods for determining the direction of the path

## Model Assumption

- We consider two simple single regression models wherein the explanatory and dependent variables are alternated with each other
  - *yi*: dependent variable of *i*-th observation *xi*: explanatory variable of *i*-th observation

$$y_i = \beta x_i + e_i \qquad x_i = \beta' y_i + e'_i$$

#### **Graphical explanation**

the same data



#### Priors

## $e \sim DP_L(\gamma, N(\mu, \sigma))$

## $\beta \sim N(\beta_0, \sigma_\beta^2)$

## $p = (p_1, \cdots, p_L) \sim \mathsf{Dirichlet}(a, b)$

- The values of hyperparameters are fixed
- γ : the parameter that indicates ease of transition to other components (fixed)

#### **Blocked Gibbs Sampler**

- Blocked Gibbs Sampler is the parameter estimation method for the models in which finite Dirichlet process prior distributions are assumed
- '•••' represents that the other parameters are given

(a) Generate 
$$eta$$
  
 $p(eta|\cdots) \propto \prod_{i}^{N} p(y_i | k_i = l, eta, \mu_l, \sigma_l^2) p(eta)$ 

% For the components which no subjects belong to, parameters are generated only from prior distribution:  $p(\beta)$ 

(b) Generate  $\mu$  (the mean of the error variables)

$$p(\mu_l|\cdots) \propto \prod_i^N p(y_i|k_i = l, \mu_l, \sigma_l^2, \beta) p(\mu_l)$$

(c) Generate 
$$\sigma$$
 (variance for the error variables)  
 $p(\sigma_l | \cdots) \propto \prod_i^N p(y_i | k_i = l, \mu_l, \sigma_l^2, \beta) p(\sigma_l^2)$ 

(d) Generate *k* (component to which each observation belongs)  $p(k_i|\cdots) \sim \sum_{l=1}^{L} \pi_{li} \delta_l(\cdot)$ 

$$\pi_{li} \propto \frac{p_l \sigma_l^{-1} \exp\left[-\frac{1}{2\sigma_l^2} (e_i - \mu_l)^2\right]}{\sum_l^L p_l \sigma_l^{-1} \exp\left[-\frac{1}{2\sigma_l^2} (e_i - \mu_l)^2\right]}$$

where 
$$e_i = y_i - \beta x_i$$

(e) generate *p* (estimation of the probability of each component membership)

$$p_{l} = \prod_{m=1}^{l-1} (1 - V_{m}) V_{l}$$
$$V_{l} \sim \text{Be}(a_{l} + M_{l}, b_{l} + \sum_{m=l+1}^{L} M_{m})$$

*M<sub>m</sub>* : the number of subjects assigned to *m*-th component

a,b : hyperparameters

This part is the core of Dirichlet process priors and largely different from normal finite mixture models

## Marginal likelihood when Dirichlet process priors are used

 Basu & Chib (2003) proposed the calculation method of marginal likelihood when Dirichlet process priors are used

$$\log p(\boldsymbol{y}) = \log p(\boldsymbol{y}|\beta^*) + \log p(\beta^*) - \log p(\beta^*|\boldsymbol{y})$$

This term is rather difficult to calculate

Chib (1995)

• We used Sequential Importance Sampling (Kong, Liu & Wong, 1994). Let  $\theta = (\mu^t, \sigma^t)^t$ 

(a) generate 
$$\boldsymbol{\theta}_1^{(g)}, \dots, \boldsymbol{\theta}_N^{(g)}$$
 from  $p(\boldsymbol{\theta}_1, \dots, \boldsymbol{\theta}_N | \boldsymbol{y}, \beta^*)$ 

$$p(\boldsymbol{\theta}_1, \cdots, \boldsymbol{\theta}_N | \boldsymbol{y}, \beta^*) = \prod_{i=1}^N p(\boldsymbol{\theta}_i | \boldsymbol{y}_{(i)}, \boldsymbol{\theta}_{(i-1)}, \beta^*)$$

$$\frac{p(\boldsymbol{\theta}_i|\boldsymbol{y}_{(i)},\boldsymbol{\theta}_{(i-1)},\beta^*)}{\sum_{j=1}^{m_{i-1}} \sum_{j=1}^{\gamma} p(y_i|\boldsymbol{\theta}_i,\beta^*)p(\boldsymbol{\theta}_i|\boldsymbol{\tau})} + \sum_{j=1}^{m_{i-1}} \frac{n_{j,i-1}}{\gamma+i-1} p(y_i|\boldsymbol{\theta}_i,\beta^*)\delta_{\boldsymbol{\theta}_j}(\boldsymbol{\theta}_i)$$

where 
$$\boldsymbol{y}_{(i)} = (y_1, \cdots, y_i)^t \ \boldsymbol{\theta}_{(i)} = (\boldsymbol{\theta}_1, \cdots, \boldsymbol{\theta}_i)^t$$

- $m_{i-1}$ : The number of patterns of different parameter values within  $(\theta_1, \cdots, \theta_{i-1})$
- $n_{j,i-1}$  : the frequency of observations that have *j*-th parameter value

#### (b) calculate ${\cal W}$

$$w = w(\boldsymbol{\theta}_{1}^{(g)}, \dots, \boldsymbol{\theta}_{N}^{(g)}) = \prod_{i=1}^{N} p(y_{i}|\boldsymbol{y}_{(i-1)}, \boldsymbol{\theta}_{i-1}^{(g)}, \beta^{*})$$
$$p(y_{i}|\boldsymbol{y}_{(i-1)}, \boldsymbol{\theta}_{(i-1)}, \beta^{*}) = \frac{\gamma}{\gamma + i - 1} \int p(y_{i}|\boldsymbol{\theta}_{i}, \beta^{*}) p(\boldsymbol{\theta}_{i}|\boldsymbol{\tau}) d\boldsymbol{\theta}_{i}$$
$$+ \sum_{j=1}^{m_{i-1}} \frac{n_{j,i-1}}{\gamma + i - 1} p(y_{i}|\boldsymbol{\theta}_{j}, \beta^{*})$$

The above integration is approximated by Monte Carlo method

(c) Calculate the mean of  ${\cal W}$ 

$$\bar{w} = \frac{1}{G} \sum_{g=1}^{G} w(\boldsymbol{\theta}_1^{(g)}, \cdots, \boldsymbol{\theta}_N^{(g)})$$

## Simulation studies

- We considered a simple single regression model, generated 100 data set, analyzed each data set and calculated the marginal likelihood
- Sample size=100,  $\mu$  = (-2.0,2.0)',  $\sigma$  = (0.5,2.0)', p=(0.5,0.5)',  $\beta$  = 0.5,  $\gamma$  =3.0, L=10
- We considered two cases about the explanatory variables (X).

 $x_i \sim N(0, 10.0) \text{ (normal)}$  $x_i \sim 0.3 \cdot N(-2.0, 1.0) \text{ (nonnormal)} + 0.7 \cdot N(2.0, 2.0) \text{ (nonnormal)}_2$ 

## Model comparison via the joint distribution

 In determining the direction of the path, it is necessary to compare the joint distribution of x and y:

We compare

$$\begin{array}{c} \log m(y|x) + \log m(x) \\ & \text{and} \\ \log m(x|y) + \log m(y) \end{array}$$

#### Simulation results

Data	Y=βX+e	Y=βX+e	$V = \beta V^{3} + \alpha$
generating	X is normal	X is nonnormal	
	(1-a)	(2-a)	(3-a)
	Y=βX+e ( <b>87</b> )	Y=βX+e ( <b>78</b> )	Y=βX <sup>3</sup> +e ( <b>85</b> )
	Y=βX <sup>3</sup> +e ( <b>13</b> )	Y=β'X <sup>3</sup> +e' ( <b>22</b> )	Y=β'X+e' ( <b>15</b> )
Data			
analysis	(1-b)	(2-b)	(3-b)
	Y=βX+e ( <b>92</b> )	Y=βX+e ( <b>72</b> )	Y=βX+e ( <b>42</b> )
	X=β 'Y+e' ( <b>8</b> )	X=β 'Y+e' ( <b>28</b> )	X= $\beta$ Y+e' (58)

\* parentheses: the number of times that the model is adopted via marginal likelihood

## Discussion

- We illustrated Bayesian approach from parameter estimation to model comparison for nonnormal data
- true models are not always adopted in determining the direction of the path
- Naturally, the direction of the path does not relate to the direction of causation
- At least, it is meaningless to identify the causation by determining the direction of the path using nonnormal error variables

Thank you very much ! miyazaki.behaviormetrics@gmail.com