

[Help](#)

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#include "bs2d_std2d.h"
#include "error_msg.h"
#include "enums.h"
#define PRECISION 1.0e-7 /*Precision for the localization of FD methods*/

/*Compress Diagonal Storage*/
static void cds(int n, double a, double b, double c, double d, double e, double f, double g)
{
    int j, nsr;

    nsr = (int)sqrt(n);

    for (j = nsr + 2; j <= n; j++)
        if (((j - 1) % (nsr)) != 0)
            band[1][j] = j2;

    for (j = nsr + 1; j <= n; j++)band[2][j] = d;

    for (j = nsr + 1; j <= n; j++)
        if (((j) % (nsr)) != 0)
            band[3][j] = f;

    for (j = 2; j <= n; j++)
        if (((j - 1) % (nsr)) != 0)
            band[4][j] = c;

    for (j = 1; j <= n; j++) band[5][j] = a;

    for (j = 1; j <= n; j++)
        if (((j) % (nsr)) != 0)
            band[6][j] = b;

    for (j = 2; j <= n - nsr; j++)
        if (((j - 1) % (nsr)) != 0)
            band[7][j] = g;

    for (j = 1; j <= n - nsr; j++) band[8][j] = e;
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    for (j = 1; j <= n - nsr; j++)
        if ((j % (nsr)) != 0)
            band[9][j] = i2;

    return;
}

/*Dirichlet Boundary Conditions*/
static void Dirichlet(int N, double a2, double b2, double c2, double d2, double
{
    int i, j, N1, Ns;

    N1 = N - 1;
    Ns = SQR(N1);

    for (i = 1; i < Ns; i++) bound[i] = 0.;

    bound[1] = j2 * (p->Compute)(p->Par, exp(x1 - limit1), exp(x2 + limit2)) +
        d2 * (p->Compute)(p->Par, exp(x1 - limit1 + h1), exp(x2 + limit2))
        f2 * (p->Compute)(p->Par, exp(x1 - limit1 + 2.*h1),
            exp(x2 + limit2)) + c2 * (p->Compute)(p->Par, exp
        g2 * (p->Compute)(p->Par, exp(x1 - limit1 + h1), exp(x2 + limit2 -

    for (i = 2; i < N - 1; i++)
        bound[i] = j2 * (p->Compute)(p->Par, exp(x1 - limit1 + h1 * (double)(i - 1))
            d2 * (p->Compute)(p->Par, exp(x1 - limit1 + h1 * (double)i), exp(
            f2 * (p->Compute)(p->Par, exp(x1 - limit1 + h1 * (double)(i + 1))

    bound[N - 1] = j2 * (p->Compute)(p->Par, exp(x1 - limit1 + h1 * (double)(N - 2)
        d2 * (p->Compute)(p->Par, exp(x1 - limit1 + h1 * (double)(N - 1)
        f2 * (p->Compute)(p->Par, exp(x1 - limit1 + h1 * (double)N), ex
        b2 * (p->Compute)(p->Par, exp(x1 - limit1 + h1 * (double)N), ex
        i2 * (p->Compute)(p->Par, exp(x1 - limit1 + h1 * (double)N), ex

    N1 = N - 1;
    j = 1;
    for (i = N; i < Ns - N1; i = i + N1)
    {
        bound[i] = j2 * (p->Compute)(p->Par, exp(x1 - limit1), exp(x2 + limit2 - h
            c2 * (p->Compute)(p->Par, exp(x1 - limit1), exp(x2 + limit2 - (

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        g2 * (p->Compute)(p->Par, exp(x1 - limit1), exp(x2 + limit2 - h1))
    }
    j++;
}

j = 1;
for (i = 2 * N1; i < Ns - N1; i = i + N1)
{
    bound[i] = f2 * (p->Compute)(p->Par, exp(x1 + limit1), exp(x2 + limit2 - h1))
        + b2 * (p->Compute)(p->Par, exp(x1 + limit1), exp(x2 + limit2 - h2))
        + i2 * (p->Compute)(p->Par, exp(x1 + limit1), exp(x2 + limit2 - h2))
    j++;
}

bound[Ns - N1 + 1] = j2 * (p->Compute)(p->Par, exp(x1 - limit1), exp(x2 - limit2))
    + c2 * (p->Compute)(p->Par, exp(x1 - limit1), exp(x2 - limit2))
    + g2 * (p->Compute)(p->Par, exp(x1 - limit1), exp(x2 - limit2))
    + e2 * (p->Compute)(p->Par, exp(x1 - limit1 + h1), exp(x2 - limit2))
    + i2 * (p->Compute)(p->Par, exp(x1 - limit1 + 2.*h1), exp(x2 - limit2))

for (i = 1; i < N - 1; i++)
    bound[Ns - N1 + 1 + i] = g2 * (p->Compute)(p->Par, exp(x1 - limit1 + h1 * (double)i), exp(x2 - limit2))
        + e2 * (p->Compute)(p->Par, exp(x1 - limit1 + h1 * (double)i), exp(x2 - limit2))
        + i2 * (p->Compute)(p->Par, exp(x1 - limit1 + h1 * (double)i), exp(x2 - limit2))

bound[Ns] = g2 * (p->Compute)(p->Par, exp(x1 + limit1 - h1 * (double)N2), exp(x2 - limit2))
    + e2 * (p->Compute)(p->Par, exp(x1 + limit1 + h1), exp(x2 - limit2))
    + i2 * (p->Compute)(p->Par, exp(x1 + limit1), exp(x2 - limit2)) +
    b2 * (p->Compute)(p->Par, exp(x1 + limit1), exp(x2 + limit2 - h2))
    + f2 * (p->Compute)(p->Par, exp(x1 + limit1), exp(x2 + limit2 - 2.*h1))

return;
}

static int BCGStab(int am, double s1, double s2, NumFunc_2 *p, double t, double s)
{
    int TimeIndex, j, i, Index;
    int N2;
    double x1, x2, m1, m2, cov;
    double limit1, limit2, h1, h2;
    double a2, b2, c2, d2, e2, f2, g2, i2, j2;
    double k;

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double *P, *b, *Obst, *bound, **band, *pivots;

/*Memory Allocation*/
N2 = (N - 1) * (N - 1);

P = (double *)calloc(N2 + 1, sizeof(double));
if (P == NULL)
    return MEMORY_ALLOCATION_FAILURE;

b = (double *)calloc(N2 + 1, sizeof(double));
if (b == NULL)
    return MEMORY_ALLOCATION_FAILURE;

Obst = (double *)calloc(N2 + 1, sizeof(double));
if (Obst == NULL)
    return MEMORY_ALLOCATION_FAILURE;

bound = (double *)calloc(N2 + 1, sizeof(double));
if (bound == NULL)
    return MEMORY_ALLOCATION_FAILURE;

pivots = (double *)calloc(N2 + 1, sizeof(double));
if (pivots == NULL)
    return MEMORY_ALLOCATION_FAILURE;

band = (double **)calloc(10, sizeof(double *));
if (band == NULL)
    return MEMORY_ALLOCATION_FAILURE;
for (i = 0; i < 10; i++)
{
    band[i] = (double *)calloc(N2 + 1, sizeof(double));
    if (band[i] == NULL)
        return MEMORY_ALLOCATION_FAILURE;
}

m1 = (r - divid1) - SQR(sigma1) / 2.0;
m2 = (r - divid2) - SQR(sigma2) / 2.0;
cov = rho * sigma1 * sigma2;

/*Space Localisation*/
limit1 = sigma1 * sqrt(t) * sqrt(log(1 / PRECISION)) + fabs(m1) * t;

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limit2 = sigma2 * sqrt(t) * sqrt(log(1 / PRECISION)) + fabs(m2) * t;

/*Space Step*/
h1 = 2.*limit1 / (double) N;
h2 = 2.*limit2 / (double)N;

/*Time Step*/
k = t / (double)M;

/*Lhs factor*/
a2 = 1. + k * (r + SQR(sigma1) / SQR(h1) + SQR(sigma2) / SQR(h2));

b2 = -k * (SQR(sigma1) / (2.*SQR(h1)) + m1 / (2.*h1));

c2 = -k * (SQR(sigma1) / (2.*SQR(h1)) - m1 / (2.*h1));
d2 = -k * (SQR(sigma2) / (2.*SQR(h2)) + m2 / (2.*h2));

e2 = -k * (SQR(sigma2) / (2.*SQR(h2)) - m2 / (2.*h2));

f2 = -k * cov / (4.*h1 * h2);
g2 = -k * cov / (4.*h1 * h2);
i2 = k * cov / (4.*h1 * h2);
j2 = k * cov / (4.*h1 * h2);

/*Cds format*/
cds(N2, a2, b2, c2, d2, e2, f2, g2, i2, j2, band);

/*Preconditioners*/
if (precond == 1)
    Diagonal_Precond(band, N2, pivots);
else
    ILU_Precond(band, N2, pivots);

/*Terminal Values*/
x1 = log(s1);
x2 = log(s2);

for (i = 1; i < N; i++)
{
    for (j = 1; j < N; j++)
    {

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        P[(i - 1) * (N - 1) + j] = (p->Compute)(p->Par, exp(x1 - limit1 + h1 *
                                                    exp(x2 + limit2 - h2 * (double)
Obst[(i - 1) * (N - 1) + j] = P[(i - 1) * (N - 1) + j];
    }
}

/*Dirichlet Boundary Conditions*/
Dirichlet(N, a2, b2, c2, d2, e2, f2, g2, i2, j2, x1, x2, limit1, limit2, h1, h2);

/*Finite Difference Cycle */
for (TimeIndex = 1; TimeIndex <= M; TimeIndex++)
{
    /*Rhs Term*/
    for (i = 1; i <= N2; i++)
        b[i] = P[i] - bound[i];

    /*BCGStab Algorithm*/
    bicgstab(band, P, b, N2, max_iter, tol, precondition, pivots);

    /*Splitting for American case*/
    if (am)
        for (i = 1; i <= N2; i++)
            P[i] = MAX(P[i], Obst[i]);
}

Index = (int)((double)(N - 1) / 2.0);
Index = Index * (N - 1) + (Index + 1);

/*Price*/
*ptprice = P[Index];

/*Deltas*/
*ptdelta1 = (P[Index + 1] - P[Index - 1]) / (2.*s1 * h1);
*ptdelta2 = (P[Index - (N - 1)] - P[Index + (N - 1)]) / (2.*s2 * h2);

/*Memory desallocation*/
free(P);
free(b);
free(Obst);
free(bound);
free(pivots);

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    for (i = 0; i < 10; i++)
        free(band[i]);
    free(band);
    return OK;
}

int CALC(FD_BCGStab)(void *Opt, void *Mod, PricingMethod *Met)
{
    TYPEOPT *ptOpt = (TYPEOPT *)Opt;
    TYPEMOD *ptMod = (TYPEMOD *)Mod;
    double r, divid1, divid2;

    r = log(1. + ptMod->R.Val.V_DOUBLE / 100.);
    divid1 = log(1. + ptMod->Divid1.Val.V_DOUBLE / 100.);
    divid2 = log(1. + ptMod->Divid2.Val.V_DOUBLE / 100.);

    return BCGStab(ptOpt->EuOrAm.Val.V_BOOL, ptMod->S01.Val.V_PDOUBLE,
                  ptMod->S02.Val.V_PDOUBLE, ptOpt->PayOff.Val.V_NUMFUNC_2,
                  ptOpt->Maturity.Val.V_DATE - ptMod->T.Val.V_DATE,
                  r, divid1, divid2, ptMod->Sigma1.Val.V_PDOUBLE, ptMod->Sigma2.Val.V_PDOUBLE,
                  Met->Par[0].Val.V_INT, Met->Par[1].Val.V_INT, Met->Par[2].Val.V_INT,
                  &(Met->Res[0].Val.V_DOUBLE), &(Met->Res[1].Val.V_DOUBLE), &(Met->Res[2].Val.V_DOUBLE));
}

static int CHK_OPT(FD_BCGStab)(void *Opt, void *Mod)
{
    return OK;
}

static int MET(Init)(PricingMethod *Met, Option *Opt)
{
    if (Met->init == 0)
    {
        Met->init = 1;

        Met->Par[0].Val.V_INT2 = 100;
        Met->Par[1].Val.V_INT2 = 100;
        Met->Par[2].Val.V_INT2 = 50;
        Met->Par[3].Val.V_PDOUBLE = 0.000001;
        Met->Par[4].Val.V_ENUM.value = 1;
    }
}

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        Met->Par[4].Val.V_ENUM.members = &PremiaEnumPrecond;

    }

    return OK;
}

PricingMethod MET(FD_BCGStab) =
{
    "FD_BCGStab",
    { {"SpaceStepNumber", INT2, {100}, ALLOW}, {"TimeStepNumber", INT2, {100}, ALL
        , {"Max Iter", INT2, {100}, ALLOW}, {"Tol", PDOUBLE, {100}, ALLOW},
        {"Precondtioner", ENUM, {100}, ALLOW}, {" " , PREMIA_NULLTYPE, {0}, FORBID}
    },
    CALC(FD_BCGStab),
    { {"Price", DOUBLE, {100}, FORBID}, {"Delta1", DOUBLE, {100}, FORBID} ,
        {"Delta2", DOUBLE, {100}, FORBID} ,
        {" " , PREMIA_NULLTYPE, {0}, FORBID}
    },
    CHK_OPT(FD_BCGStab),
    CHK_ok,
    MET(Init)
};

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