

[Source](#) | [Model](#) | [Option](#)  
[| Model\\_Option](#) | [Help on fd methods](#) | [Archived Tests](#)

## fd\_explicit\_mer

Input parameters:

- SpaceStepNumber  $N$

Output parameters:

- Price
- Delta

**/\*Memory Allocation\*/**

**/\*Space localization\*/**

Define the integration domain  $D = [x_{min}, x_{max}]$  using inequality [there](#).

**/\*Space Step\*/**

Define the space step  $h = \frac{x_{max} - x_{min}}{N}$ .

**/\* Integration formula \*/**

**/\*"Probabilities" associated to point/\***

cf. [there](#)

**/\*Terminal Values/\***

Put the value of the payoff saved in *Obst* into a vector  $P$  which will be used to save the option value.

**/\*Finite difference Cycle/\***

At any time step, described by the loop in the variable *TimeIndex*, we have to explicitly the equation cf. [there](#)

**/\*Price\*/**

**/\*Delta\*/**

**/\*Memory Deallocation\*/**