

Help

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#if defined(PremiaCurrentVersion) && PremiaCurrentVersion < (2008+2) //The "#els
#else
/*****
/*                                     mlsolv.c                                     */
/*****
/*                                     */
/* Multi-Level SOLVers                                     */
/*                                     */
/* Copyright (C) 1992-1995 Tomas Skalicky. All rights reserved.               */
/*                                     */
/*****
/*                                     */
/*      ANY USE OF THIS CODE CONSTITUTES ACCEPTANCE OF THE TERMS               */
/*      OF THE COPYRIGHT NOTICE (SEE FILE COPYRGHT.H)                         */
/*                                     */
/*****

#include <math.h>
#include <stdio.h>
#include <string.h>

#include "laspack/mlsolv.h"
#include "laspack/errhandl.h"
#include "laspack/operats.h"
#include "laspack/rtc.h"
#include "laspack/copyright.h"

Vector *MGStep(int NoLevels, QMatrix *A, Vector *x, Vector *b,
               Matrix *R, Matrix *P, int Level, int Gamma,
               IterProcType SmoothProc, int Nu1, int Nu2,
               PrecondProcType PrecondProc, double Omega,
               IterProcType SolvProc, int NuC,
               PrecondProcType PrecondProcC, double OmegaC)
/* one multigrid iteration */
{
    int CoarseMGIter; /* multi grid iteration counter for coarser grid */

    if (Level == 0)
    {

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        /* solving of system of equations for the residual on the coarsest grid */
        (*SolvProc)(&A[Level], &x[Level], &b[Level], NuC, PrecondProcC, OmegaC);
    }
    else
    {
        /* pre-smoothing - Nu1 iterations */
        (*SmoothProc)(&A[Level], &x[Level], &b[Level], Nu1, PrecondProc, Omega);
        /* restriction of the residual to the coarser grid */
        Asgn_VV(&b[Level - 1], Mul_MV(&R[Level - 1],
                                     Sub_VV(&b[Level], Mul_QV(&A[Level], &x[Level])),
                                     &x[Level - 1]));
        /* initialisation of vector of unknowns on the coarser grid */
        V_SetAllCmp(&x[Level - 1], 0.0);
        /* solving of system of equations for the residual on the coarser grid */
        for (CoarseMGIter = 1; CoarseMGIter <= Gamma; CoarseMGIter++)
            MGStep(NoLevels, A, x, b, R, P, Level - 1, Gamma,
                  SmoothProc, Nu1, Nu2, PrecondProc, Omega,
                  SolvProc, NuC, PrecondProcC, OmegaC);
        /* interpolation of the solution from the coarser grid */
        if (P != NULL)
            AddAsgn_VV(&x[Level], Mul_MV(&P[Level], &x[Level - 1]));
        else
            AddAsgn_VV(&x[Level], Mul_MV(Transp_M(&R[Level - 1]), &x[Level - 1]));
        /* post-smoothing - Nu2 iterations */
        (*SmoothProc)(&A[Level], &x[Level], &b[Level], Nu2, PrecondProc, Omega);
    }

    return (&x[Level]);
}

Vector *MGIter(int NoLevels, QMatrix *A, Vector *x, Vector *b,
               Matrix *R, Matrix *P, int MaxIter, int Gamma,
               IterProcType SmoothProc, int Nu1, int Nu2,
               PrecondProcType PrecondProc, double Omega,
               IterProcType SolvProc, int NuC,
               PrecondProcType PrecondProcC, double OmegaC)
/* multigrid method with residual termination control */
{
    int Iter;
    double bNorm;
    size_t Dim;
    Vector r;

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Dim = Q_GetDim(&A[NoLevels - 1]);
V_Constr(&r, "r", Dim, Normal, True);

if (LASResult() == LASOK)
{
    bNorm = l2Norm_V(&b[NoLevels - 1]);

    Iter = 0;
    /* r = b - A x(i) at NoLevels - 1 */
    Asgn_VV(&r, Sub_VV(&b[NoLevels - 1], Mul_QV(&A[NoLevels - 1], &x[NoLevels - 1])),
    while (!RTCResult(Iter, l2Norm_V(&r), bNorm, MGIterId)
        && Iter < MaxIter)
    {
        Iter++;
        /* one multigrid step */
        MGStep(NoLevels, A, x, b, R, P, NoLevels - 1, Gamma,
            SmoothProc, Nu1, Nu2, PrecondProc, Omega,
            SolvProc, NuC, PrecondProcC, OmegaC);
        /* r = b - A x(i) at NoLevels - 1 */
        Asgn_VV(&r, Sub_VV(&b[NoLevels - 1], Mul_QV(&A[NoLevels - 1], &x[NoLevels - 1])),
    }
}

V_Destr(&r);

return (&x[NoLevels - 1]);
}

Vector *NestedMGIter(int NoLevels, QMatrix *A, Vector *x, Vector *b,
    Matrix *R, Matrix *P, int Gamma,
    IterProcType SmoothProc, int Nu1, int Nu2,
    PrecondProcType PrecondProc, double Omega,
    IterProcType SolvProc, int NuC,
    PrecondProcType PrecondProcC, double OmegaC)
/* nested multigrid method */
{
    int Level;

    /* solution of system of equations on coarsest grid */
    V_SetAllCmp(&x[0], 0.0);

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MGStep(NoLevels, A, x, b, R, P, 0, Gamma,
       SmoothProc, Nu1, Nu2, PrecondProc, Omega,
       SolvProc, NuC, PrecondProcC, OmegaC);

for (Level = 1; Level < NoLevels; Level++)
{
    /* prolongation of solution to finer grid */
    if (P != NULL)
        Asgn_VV(&x[Level], Mul_MV(&P[Level], &x[Level - 1]));
    else
        Asgn_VV(&x[Level], Mul_MV(Transp_M(&R[Level - 1]), &x[Level - 1]));
    /* solution of system of equations on finer grid with
       multigrid method */
    MGStep(NoLevels, A, x, b, R, P, Level, Gamma,
           SmoothProc, Nu1, Nu2, PrecondProc, Omega,
           SolvProc, NuC, PrecondProcC, OmegaC);
}

/* submission of reached accuracy to RTC */
RTCResult(1, l2Norm_V(Sub_VV(&b[NoLevels - 1],
                             Mul_QV(&A[NoLevels - 1], &x[NoLevels - 1]))),
          l2Norm_V(&b[NoLevels - 1]), NestedMGIterId);

return (&x[NoLevels - 1]);
}

Vector *MGPCGIter(int NoLevels, QMatrix *A, Vector *z, Vector *r,
                  Matrix *R, Matrix *P, int MaxIter, int NoMGIter, int Gamma,
                  IterProcType SmoothProc, int Nu1, int Nu2,
                  PrecondProcType PrecondProc, double Omega,
                  IterProcType SolvProc, int NuC,
                  PrecondProcType PrecondProcC, double OmegaC)/* multigrid preco
{
    int Iter, MGIter;
    double Alpha, Beta, Rho, RhoOld = 0.0;
    double bNorm;
    size_t Dim;
    Vector x, p, q, b;

    Dim = Q_GetDim(&A[NoLevels - 1]);
    V_Constr(&x, "x", Dim, Normal, True);

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V_Constr(&p, "p", Dim, Normal, True);
V_Constr(&q, "q", Dim, Normal, True);
V_Constr(&b, "b", Dim, Normal, True);

if (LASResult() == LASOK)
{
    /* copy solution and right hand side stored in parameters z and r */
    Asgn_VV(&x, &z[NoLevels - 1]);
    Asgn_VV(&b, &r[NoLevels - 1]);

    bNorm = l2Norm_V(&b);

    Iter = 0;
    Asgn_VV(&r[NoLevels - 1], Sub_VV(&b, Mul_QV(&A[NoLevels - 1], &x)));
    while (!RTCResult(Iter, l2Norm_V(&r[NoLevels - 1]), bNorm, MGPCGIterId)
        && Iter < MaxIter)
    {
        Iter++;
        /* multigrid preconditioner */
        V_SetAllCmp(&z[NoLevels - 1], 0.0);
        for (MGIter = 1; MGIter <= NoMGIter; MGIter++)
            MGStep(NoLevels, A, z, r, R, P, NoLevels - 1, Gamma,
                SmoothProc, Nu1, Nu2, PrecondProc, Omega,
                SolvProc, NuC, PrecondProcC, OmegaC);
        Rho = Mul_VV(&r[NoLevels - 1], &z[NoLevels - 1]);
        if (Iter == 1)
        {
            Asgn_VV(&p, &z[NoLevels - 1]);
        }
        else
        {
            Beta = Rho / RhoOld;
            Asgn_VV(&p, Add_VV(&z[NoLevels - 1], Mul_SV(Beta, &p)));
        }
        Asgn_VV(&q, Mul_QV(&A[NoLevels - 1], &p));
        Alpha = Rho / Mul_VV(&p, &q);
        AddAsgn_VV(&x, Mul_SV(Alpha, &p));
        SubAsgn_VV(&r[NoLevels - 1], Mul_SV(Alpha, &q));
        RhoOld = Rho;
    }
}

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        /* put solution and right hand side vectors back */
        Asgn_VV(&z[NoLevels - 1], &x);
        Asgn_VV(&r[NoLevels - 1], &b);
    }

    V_Destr(&x);
    V_Destr(&p);
    V_Destr(&q);
    V_Destr(&b);

    return (&z[NoLevels - 1]);
}

Vector *BPXPrecond(int NoLevels, QMatrix *A, Vector *y, Vector *c,
                  Matrix *R, Matrix *P, int Level,
                  IterProcType SmoothProc, int Nu,
                  PrecondProcType PrecondProc, double Omega,
                  IterProcType SmoothProcC, int NuC,
                  PrecondProcType PrecondProcC, double OmegaC)
/* BPX preconditioner (recursively defined) */
{
    if (Level == 0)
    {
        /* smoothing on the coarsest grid - NuC iterations */
        V_SetAllCmp(&y[Level], 0.0);
        (*SmoothProcC)(&A[Level], &y[Level], &c[Level], NuC, PrecondProcC, OmegaC);
    }
    else
    {
        /* smoothing - Nu iterations */
        V_SetAllCmp(&y[Level], 0.0);
        (*SmoothProc)(&A[Level], &y[Level], &c[Level], Nu, PrecondProc, Omega);
        /* restriction of the residual to the coarser grid */
        Asgn_VV(&c[Level - 1], Mul_MV(&R[Level - 1], &c[Level]));
        /* smoothing on the coarser grid */
        BPXPrecond(NoLevels, A, y, c, R, P, Level - 1,
                  SmoothProc, Nu, PrecondProc, Omega, SmoothProcC, NuC, PrecondPr
        /* interpolation of the solution from coarser grid */
        if (P != NULL)
            AddAsgn_VV(&y[Level], Mul_MV(&P[Level], &y[Level - 1]));
        else
    }
}

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        AddAsgn_VV(&y[Level], Mul_MV(Transp_M(&R[Level - 1]), &y[Level - 1]));
    }

    return (&y[Level]);
}

Vector *BPXPCGIter(int NoLevels, QMatrix *A, Vector *z, Vector *r,
                  Matrix *R, Matrix *P, int MaxIter,
                  IterProcType SmoothProc, int Nu,
                  PrecondProcType PrecondProc, double Omega,
                  IterProcType SmoothProcC, int NuC,
                  PrecondProcType PrecondProcC, double OmegaC)
/* BPX preconditioned CG method */
{
    int Iter;
    double Alpha, Beta, Rho, RhoOld = 0.0;
    double bNorm;
    size_t Dim;
    Vector x, p, q, b;

    Dim = Q_GetDim(&A[NoLevels - 1]);
    V_Constr(&x, "x", Dim, Normal, True);
    V_Constr(&p, "p", Dim, Normal, True);
    V_Constr(&q, "q", Dim, Normal, True);
    V_Constr(&b, "b", Dim, Normal, True);

    if (LASResult() == LASOK)
    {
        /* copy solution and right hand side stored in parameters z and r */
        Asgn_VV(&x, &z[NoLevels - 1]);
        Asgn_VV(&b, &r[NoLevels - 1]);

        bNorm = l2Norm_V(&b);

        Iter = 0;
        Asgn_VV(&r[NoLevels - 1], Sub_VV(&b, Mul_QV(&A[NoLevels - 1], &x)));
        while (!RTCResult(Iter, l2Norm_V(&r[NoLevels - 1]), bNorm, BPXPCGIterId)
            && Iter < MaxIter)
        {
            Iter++;
            /* BPX preconditioner */

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        BPXPrecond(NoLevels, A, z, r, R, P, NoLevels - 1,
                    SmoothProc, Nu, PrecondProc, Omega, SmoothProcC, NuC, Preco
Rho = Mul_VV(&r[NoLevels - 1], &z[NoLevels - 1]);
if (Iter == 1)
{
    Asgn_VV(&p, &z[NoLevels - 1]);
}
else
{
    Beta = Rho / RhoOld;
    Asgn_VV(&p, Add_VV(&z[NoLevels - 1], Mul_SV(Beta, &p)));
}
Asgn_VV(&q, Mul_QV(&A[NoLevels - 1], &p));
Alpha = Rho / Mul_VV(&p, &q);
AddAsgn_VV(&x, Mul_SV(Alpha, &p));
SubAsgn_VV(&r[NoLevels - 1], Mul_SV(Alpha, &q));
RhoOld = Rho;
}

/* put solution and right hand side vectors back */
Asgn_VV(&z[NoLevels - 1], &x);
Asgn_VV(&r[NoLevels - 1], &b);
}

V_Destr(&x);
V_Destr(&p);
V_Destr(&q);
V_Destr(&b);

return (&z[NoLevels - 1]);
}

#endif //PremiaCurrentVersion

```