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```
#include <stdlib.h>
#include "solversyslin.h"

void multiplytridiag(double **M, double *u, double *r, int n)
{
    int i;

    r[0] = M[0][0] * u[0] + M[0][1] * u[1];

    for (i = 1; i < n - 1; i++)
    {
        r[i] = M[i][i] * u[i] + M[i][i - 1] * u[i - 1] + M[i][i + 1] * u[i + 1];
    }

    r[n - 1] = M[n - 1][n - 1] * u[n - 1] + M[n - 1][n - 2] * u[n - 2];
}

void tridiagsolve(double **M, double *u, double *r, int n)
{
    int i, j;
    double *diagd;
    double *diagm;
    double *diagu;

    double *a;
    double *b;
    double *c;

    /* double bet, *gam; */
    diagd = malloc((n - 1) * sizeof(double));
    diagu = malloc((n - 1) * sizeof(double));
    diagm = malloc((n) * sizeof(double));

    a = malloc((n - 1) * sizeof(double));
    b = malloc((n) * sizeof(double));
    c = malloc((n - 1) * sizeof(double));

    diagm[0] = M[0][0];
```

```
for (j = 1; j < n; j++)
{
    diagm[j] = M[j][j];
    diagd[j - 1] = M[j][j - 1];
    diagu[j - 1] = M[j - 1][j];
}

a[0] = diagd[0] / diagm[0];
b[0] = diagm[0];
c[0] = diagu[0];
if (b[0] == 0)
{
    printf("FATALE ERREUR, DIVISION PAR ZERO LORS DE L'INVERSION DE LA MATRICE P
}

for (i = 1; i < n - 1; i++)
{
    b[i] = diagm[i] - a[i - 1] * c[i - 1];
    a[i] = diagd[i] / b[i];
    c[i] = diagu[i];
    if (b[i] == 0)
    {
        printf("FATALE ERREUR, DIVISION PAR ZERO LORS DE L'INVERSION DE LA MATRI
    }

}

b[n - 1] = diagm[n - 1] - a[n - 2] * c[n - 2];
if (b[n - 1] == 0)
{
    printf("FATALE ERREUR, DIVISION PAR ZERO LORS DE L'INVERSION DE LA MATRICE P
}

u[0] = r[0];
for (i = 1; i < n; i++)
{
    u[i] = r[i] - a[i - 1] * u[i - 1];
}
u[n - 1] = u[n - 1] / b[n - 1];
for (i = n - 2; i >= 0; i--)
```

```
    {  
        u[i] = (u[i] - c[i] * u[i + 1]) / b[i];  
    }  
  
    free(diagd);  
    free(diagm);  
    free(diagu);  
    free(a);  
    free(b);  
    free(c);  
  
}
```