

Help

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extern "C" {
#include "hes1d_std.h"

#include "math/highdim_solver/laspack/highdim_vector.h"
#include "math/highdim_solver/laspack/qmatrix.h"
#include "math/highdim_solver/laspack/highdim_matrix.h"
#include "math/highdim_solver/laspack/operats.h"

#include "math/highdim_solver/fd_solver.h"
#include "math/highdim_solver/fd_operators.h"
#include "math/highdim_solver/fd_operators_easy.h"
#include "math/highdim_solver/error.h"
}
#include <cmath>
using namespace std;

#if defined(PremiaCurrentVersion) && PremiaCurrentVersion < (2008+2) //The "#els
#else

typedef struct _Model
{
    // Independent model parameters
    double kappa, theta, sigma, rho, r, V0, S0, K, T;
    unsigned N1, N2;    // Number of grid points per dimension

    // Solution domain definition
    double xL, xR;
    double yL, yR;

    // Offset
    int offx, offy;

    // Payoff
    double (*boundary)(struct _Model *, double, double);

} HestonModel;

static HestonModel M_Heston;

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static void setup(HestonModel *m)
{
    m->xL = 1;
    m->xR = 800;
    m->yL = 0.000001;
    m->yR = m->yL + 8.0 * m->V0;

    m->offx = (int)floor((m->S0 - m->xL) * (m->N1 - 1) / (m->xR - m->xL));
    m->offy = (int)floor((m->V0 - m->yL) * (m->N2 - 1) / (m->yR - m->yL));

    m->xR = (m->N1 - 1) * (m->S0 - m->xL) / m->offx + m->xL;
    m->yR = (m->N2 - 1) * (m->V0 - m->yL) / m->offy + m->yL;
}

// Model to solution space
//
/*static void c_m2s(HestonModel *m, double v1, double v2, double *w1, double *w2)
{
    if(w1) *w1 = (v1-m->xL)/(m->xR-m->xL);
    if(w2) *w2 = (v2-m->yL)/(m->yR-m->yL);
}*/

static void v_m2s(HestonModel *m, double t, double V, double *W)
{
    *W = exp(m->r * (m->T - t)) * V;
}

/*static void m2s(HestonModel *m, double t, double v1, double v2, double V,
                 double *w1, double *w2, double *W)
{
    c_m2s(m,v1,v2,w1,w2);
    v_m2s(m,t,V,W);
}*/

// Solution to model space

static void c_s2m(HestonModel *m, double w1, double w2, double *v1, double *v2)
{
    if (v1) *v1 = (m->xR - m->xL) * w1 + m->xL;
    if (v2) *v2 = (m->yR - m->yL) * w2 + m->yL;
}

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static void v_s2m(HestonModel *m, double tau, double W, double *V)
{
    *V = exp(-1.0 * m->r * tau) * W;
}
/*
static void s2m(HestonModel *m, double tau, double w1, double w2, double W,
                double *v1, double *v2, double *V)
{
    c_s2m(m,w1,w2,v1,v2);
    v_s2m(m,tau,W,V);
}*/

static double call_boundary(HestonModel *m, double t, double S)
{
    // Call artificial boundary condition
    double v = S - m->K * exp(-m->r * (m->T - t));

    return v > 0 ? v : 0;
}

static double put_boundary(HestonModel *m, double t, double S)
{
    // Call artificial boundary condition
    double v = m->K * exp(-m->r * (m->T - t)) - S;

    return v > 0 ? v : 0;
}

static double payoff(HestonModel *m, double S)
{
    return m->boundary(m, m->T, S);
}

////////////////////////////////////
// Initial & boundary conditions
//
static int ic_f_next_elem(struct _FDSolver *s, FDSolverVectorFiller *f,

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                                unsigned *c, double *v)
{
    double S;

    c_s2m(&M_Heston, (double)c[0] / (s->size[0] - 1), 0, &S, NULL);
    v_m2s(&M_Heston, M_Heston.T - s->t, payoff(&M_Heston, S), v);

    return 0;
}

static int b_f_next_elem(struct _FDSolver *s, FDSolverVectorFiller *f,
                        unsigned *c, double *v)
{
    double S;

    c_s2m(&M_Heston, (double)c[0] / (s->size[0] - 1), 0, &S, NULL);
    v_m2s(&M_Heston, M_Heston.T - s->t, M_Heston.boundary(&M_Heston, M_Heston.T -

    return 0;
}

//////////////////////////////////////////
// Equation definition
//

static void eq_first_def(FDOperatorJam *j)
{
    unsigned k;

    for (k = 0; k < j->dim; k++)
        FIRST_SPATIAL_DERIVATIVE_CENTERED_MASK(j, k);
}

static int eq_first_apply(FDSolver *s, FDOperatorJam *j, unsigned *c, void *d,
                        double factor)
{
    double x, y;
    double wx, wy;

    wx = M_Heston.xR - M_Heston.xL;
    wy = M_Heston.yR - M_Heston.yL;

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    c_s2m(&M_Heston, (double)c[0] / (s->size[0] - 1), (double)c[1] / (s->size[1] - 1),
    FIRST_SPATIAL_DERIVATIVE_CENTERED_SET(j, 0, factor * x * M_Heston.r / wx * (M_Heston.N1 - 1), 2)*s->deltaT);
    FIRST_SPATIAL_DERIVATIVE_CENTERED_SET(j, 1, factor * M_Heston.kappa * (M_Heston.N2 - 1), 2)*s->deltaT);

    return 0;
}

static void eq_second_def(FDOperatorJam *j)
{
    unsigned k, h;

    for (k = 0; k < j->dim; k++)
        UNIFORM_SECOND_SPATIAL_DERIVATIVE_CENTERED_MASK(j, k);

    for (h = 1; h < j->dim; h++)
        for (k = 0; k < h; k++)
            MIXED_SECOND_SPATIAL_DERIVATIVE_CENTERED_BOUCHUT_MASK(j, h, k);
}

static int eq_second_apply(FDSolver *s, FDOperatorJam *j, unsigned *c, void *d,
                           double factor)
{
    double x, y;
    double wx, wy;

    wx = M_Heston.xR - M_Heston.xL;
    wy = M_Heston.yR - M_Heston.yL;

    c_s2m(&M_Heston, (double)c[0] / (s->size[0] - 1), (double)c[1] / (s->size[1] - 1),
    UNIFORM_SECOND_SPATIAL_DERIVATIVE_CENTERED_SET(j, 0,
        factor * 0.5 * y * pow(x / wx * (M_Heston.N1 - 1), 2)*s->deltaT);

    UNIFORM_SECOND_SPATIAL_DERIVATIVE_CENTERED_SET(j, 1,
        factor * 0.5 * y * pow(M_Heston.sigma / wy * (M_Heston.N2 - 1), 2)*s->deltaT);

    MIXED_SECOND_SPATIAL_DERIVATIVE_CENTERED_BOUCHUT_SET(j, 1, 0,
        factor * M_Heston.rho * M_Heston.sigma * x * y / (wx * wy) * (M_Heston.N1

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    return 0;
}

////////////////////////////////////
// Explicit scheme
//
static int ex_eq_def_c(FDOperatorJam *j, void *d)
{
    FIRST_TIME_DERIVATIVE_FORWARD_MASK(j);

    eq_first_def(j);
    eq_second_def(j);

    return 0;
}

static int ex_eq_apply_c(FDSolver *s, FDOperatorJam *j, unsigned *c, void *d)
{
    FIRST_TIME_DERIVATIVE_FORWARD_SET(j, 1.);

    eq_first_apply(s, j, c, d, 1.0);
    eq_second_apply(s, j, c, d, 1.0);

    return 0;
}

static int ex_eq_def_n(FDOperatorJam *j, void *d)
{
    FIRST_TIME_DERIVATIVE_FORWARD_MASK(j);

    return 0;
}

static int ex_eq_apply_n(FDSolver *s, FDOperatorJam *j, unsigned *c, void *d)
{
    FIRST_TIME_DERIVATIVE_FORWARD_SET(j, 1.);

    return 0;
}

////////////////////////////////////
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```
// Crank-Nicolson scheme
//
static int cn_eq_def_c(FDOperatorJam *j, void *d)
{
    FIRST_TIME_DERIVATIVE_FORWARD_MASK(j);

    eq_first_def(j);
    eq_second_def(j);

    return 0;
}

static int cn_eq_apply_c(FDSolver *s, FDOperatorJam *j, unsigned *c, void *d)
{
    FIRST_TIME_DERIVATIVE_FORWARD_SET(j, 1.);

    eq_first_apply(s, j, c, d, 1.0);
    eq_second_apply(s, j, c, d, 0.5);

    return 0;
}

static int cn_eq_def_n(FDOperatorJam *j, void *d)
{
    FIRST_TIME_DERIVATIVE_FORWARD_MASK(j);

    eq_second_def(j);

    return 0;
}

static int cn_eq_apply_n(FDSolver *s, FDOperatorJam *j, unsigned *c, void *d)
{
    FIRST_TIME_DERIVATIVE_FORWARD_SET(j, 1.);

    eq_second_apply(s, j, c, d, -0.5);

    return 0;
}
```

```

static int FDHeston(double S0, double V0, NumFunc_1 *p, double T, double r, dou
{
    double K;
    int k, h, offset, call_or_put;
    double Vleft, Vright;

    K = p->Par[0].Val.V_DOUBLE;
    if ((p->Compute) == &Call)
        call_or_put = 1;
    else
        call_or_put = 0;

    M_Heston.boundary = call_or_put ? call_boundary : put_boundary;

    FDSolver s;
    FDSolverVectorFiller ic_f, b_f;
    FDSolverCoMatricesFiller AcBcf, AnBnf;
    FDOperatorJamCoMatricesFillerData jfdc_ex, jfdn_ex;
    FDOperatorJamCoMatricesFillerData jfdc_cn, jfdn_cn;

    M_Heston.kappa = kappa;
    M_Heston.theta = theta;
    M_Heston.sigma = sigma;
    M_Heston.rho = rho;
    M_Heston.r = r - divid;
    M_Heston.V0 = V0;
    M_Heston.S0 = S0;
    M_Heston.K = K;
    M_Heston.T = T;

    M_Heston.N1 = N1 % 2 ? N1 : N1 + 1;
    M_Heston.N2 = N2 % 2 ? N2 : N2 + 1;

    setup(&M_Heston);

    offset = (N1 - 2) * (M_Heston.offy - 1) + M_Heston.offx;

    s.dim = 2;
    s.is_A_symmetric = FALSE;

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// Evaluate CFL for explicit part
s.deltaT = pow(M_Heston.xR - M_Heston.xL, 2) / (0.5 * M_Heston.yR * (pow((M_He

if (pow(M_Heston.yR - M_Heston.yL, 2) / (0.5 * M_Heston.yR * pow((M_Heston.N2
    s.deltaT = pow(M_Heston.yR - M_Heston.yL, 2) / (0.5 * M_Heston.yR * pow((M_H

s.deltaT *= 0.1;

s.size[0] = M_Heston.N1;
s.size[1] = M_Heston.N2;

ic_f.init = NULL;
ic_f.next_elem = ic_f_next_elem;
ic_f.finish = NULL;
ic_f.free = NULL;

b_f.init = NULL;
b_f.next_elem = b_f_next_elem;
b_f.finish = NULL;
b_f.free = NULL;

s.b_filler = &b_f;

// Explicit

s.is_fully_explicit = TRUE;
s.is_fully_implicit = FALSE;

FDOperatorJamCoMatricesFillerSet(&AcBcf, &jfdc_ex, ex_eq_def_c,
                                ex_eq_apply_c, NULL);
FDOperatorJamCoMatricesFillerSet(&AnBnf, &jfdn_ex, ex_eq_def_n,
                                ex_eq_apply_n, NULL);

if (FDSolverInit(&s, &ic_f, &AcBcf, &AnBnf)) return 1;

for (k = 1; k <= 20; k++) FDSolverStep(&s);

// Crank-Nicolson

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s.is_fully_explicit = FALSE;
s.is_fully_implicit = FALSE;

h = (int)ceil((1.0 - s.t) / (sqrt(s.deltaT)));
s.deltaT = (1.0 - s.t) / h;

FDOperatorJamCoMatricesFillerSet(&AcBcf, &jfdc_cn, cn_eq_def_c,
                                   cn_eq_apply_c, NULL);
FDOperatorJamCoMatricesFillerSet(&AnBnf, &jfdn_cn, cn_eq_def_n,
                                   cn_eq_apply_n, NULL);

if (FDSolverResetMatrices(&s, &AcBcf, &AnBnf)) return 1;

for (; k <= h + 20; k++) FDSolverStep(&s);

/*Price*/
v_s2m(&M_Heston, s.t, V_GetCmp(s.xc, offset), ptprice);
v_s2m(&M_Heston, s.t, V_GetCmp(s.xc, offset - 1), &Vleft);
v_s2m(&M_Heston, s.t, V_GetCmp(s.xc, offset + 1), &Vright);

/*Delta*/
*ptdelta = (M_Heston.N1 - 1) * (Vright - Vleft) / (2.0 * (M_Heston.xR - M_Heston.xL));

return OK;
}
#endif //PremiaCurrentVersion

extern "C" {
#if defined(PremiaCurrentVersion) && PremiaCurrentVersion < (2008+2) //The "#els
static int CHK_OPT(FD_Heston1)(void *Opt, void *Mod)
{
    return NONACTIVE;
}
int CALC(FD_Heston1)(void *Opt, void *Mod, PricingMethod *Met)
{
    return AVAILABLE_IN_FULL_PREMIA;
}
#else
int CALC(FD_Heston1)(void *Opt, void *Mod, PricingMethod *Met)
{

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TYPEOPT *ptOpt = (TYPEOPT *)Opt;
TYPEMOD *ptMod = (TYPEMOD *)Mod;
double r, divid;

if (ptMod->Sigma.Val.V_PDOUBLE == 0.0)
{
    Fprintf(TOSCREEN, "BLACK-SCHOLES MODEL\ n\ n\ n");
    return WRONG;
}
else
{
    r = log(1. + ptMod->R.Val.V_DOUBLE / 100.);
    divid = log(1. + ptMod->Divid.Val.V_DOUBLE / 100.);

    return FDHeston(ptMod->S0.Val.V_PDOUBLE,
                    ptMod->Sigma0.Val.V_PDOUBLE,
                    ptOpt->PayOff.Val.V_NUMFUNC_1,
                    ptOpt->Maturity.Val.V_DATE - ptMod->T.Val.V_DATE,
                    r,
                    divid, ptMod->Sigma.Val.V_PDOUBLE,
                    ptMod->Rho.Val.V_PDOUBLE,
                    ptMod->MeanReversion.Val.V_PDOUBLE,
                    ptMod->LongRunVariance.Val.V_PDOUBLE,
                    Met->Par[0].Val.V_INT, Met->Par[1].Val.V_INT,
                    &(Met->Res[0].Val.V_DOUBLE),
                    &(Met->Res[1].Val.V_DOUBLE)
    );
}
}

static int CHK_OPT(FD_Heston1)(void *Opt, void *Mod)
{
    if ((strcmp(((Option *)Opt)->Name, "CallEuro") == 0) || (strcmp(((Option *)Opt)->Name, "PutEuro") == 0))
        return OK;

    return WRONG;
}

#endif //PremiaCurrentVersion
static int MET(Init)(PricingMethod *Met, Option *Opt)

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{
  if (Met->init == 0)
  {
    Met->init = 1;

    Met->Par[0].Val.V_INT2 = 201;
    Met->Par[1].Val.V_INT2 = 51;
  }

  return OK;
}

PricingMethod MET(FD_Heston1) =
{
  "FD_NataliniBriani_Heston",
  { {"SpaceStepNumber S", INT2, {100}, ALLOW}, {"SpaceStepNumber V", INT2, {100},
    , {" ", PREMIA_NULLTYPE, {0}, FORBID}
  },
  CALC(FD_Heston1),
  { {"Price", DOUBLE, {100}, FORBID},
    {"Delta", DOUBLE, {100}, FORBID} ,
    {" ", PREMIA_NULLTYPE, {0}, FORBID}
  },
  CHK_OPT(FD_Heston1),
  CHK_ok,
  MET(Init)
};
}

```