Stream Ciphers Using a Random Update Function: Study of the Entropy of the Inner State

Andrea Röck
INRIA Paris-Rocquencourt, Team SECRET
France

Africacrypt, June 12, 2008



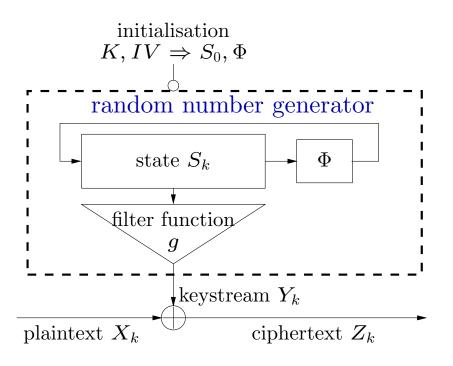
Outline

- ► Stream Cipher Model
- ► Entropy Estimation
 - Previous Results
 - New Entropy Estimator
- ► Collision Attacks
- ► Conclusion



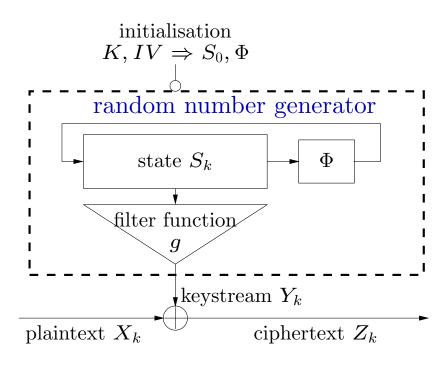
Part 1 Stream Cipher Model

Stream Cipher Model



- ▶ Initial State : S_0
- ▶ Update Function : $S_{k+1} = \Phi(S_k)$ for $k \ge 0$
- \blacktriangleright Keystream : $Y_k = g(S_k)$
- ightharpoonup Ciphertext : $Z_k = X_k \oplus Y_k$

Probabilistic Model (Information of an adversary)



- ► State space :
- Initial distribution :
- ► Random update function :

$$\Omega_n = \{\omega_1, \omega_2, \dots \omega_n\}$$

$$\{p_i\}_{i=1}^n$$
 with $p_i = Pr[S_0 = \omega_i]$

$$Pr[\Phi = \varphi] = 1/n^n$$
 for all $\varphi \in \mathcal{F}_n = \{\varphi : \Omega_n \to \Omega_n\}$

State Entropy

Probability that the state has the value ω_i after k iterations of Φ :

$$p_i^{\Phi}(k) = Pr[S_k = \omega_i] = Pr[\Phi^k(S_0) = \omega_i]$$

► Shannon's entropy *H*: is a measure of the information contained in a random variable. It must hold that:

$$H \le \log_2(n)$$

State entropy after k iterations of Φ :

$$H_k^{\Phi} = \sum_{i=1}^n p_i^{\Phi}(k) \log_2 \left(\frac{1}{p_i^{\Phi}(k)}\right)$$

▶ Average state entropy after k iterations, taken over all functions $\varphi \in \mathcal{F}_n$:

$$\mathbf{H_k} = \mathbf{E}(H_k^{\Phi})$$



Motivation

- ▶ A random function allows us to study some interesting properties of our stream cipher model, on average over all function $\varphi \in \mathcal{F}_n$.
- ▶ Some new stream ciphers use an update function which behaves almost like a random function. (e.g.: the eSTREAM candidate MICKEY (version 1) [Babbage et Dodd 05])
- ▶ The image size of Φ^k is smaller than n, thus we *loose entropy*.

Questions:

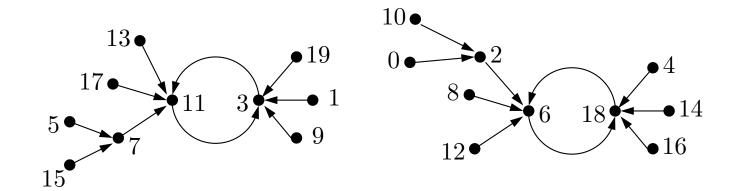
- ▶ How much entropy do we loose in the internal state?
- ► Can this loss be efficiently exploited into a collision attack?



Part 2 Entropy Estimation

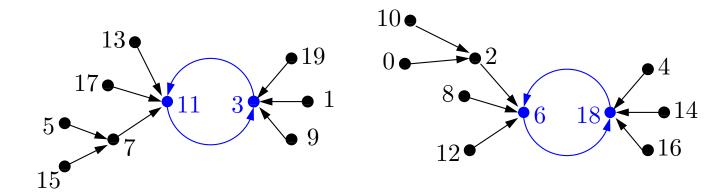
Previous Results

Example of a Functional Graph



$$\varphi: x \to x^2 + 2 \pmod{20}$$

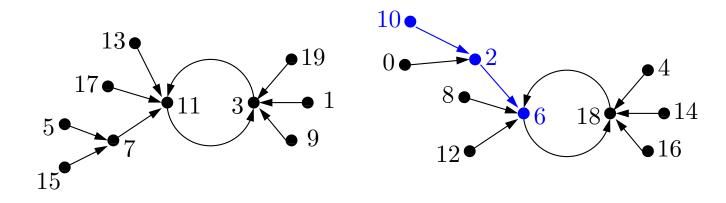




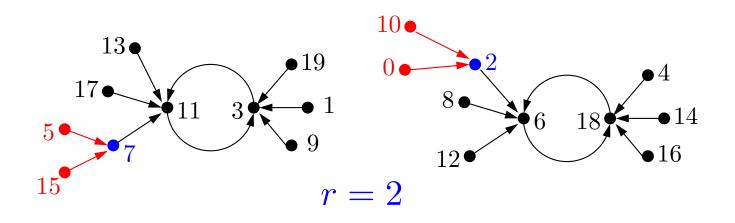
Asymptotic values for $n \to \infty$:

Expected number of cycle points : $\mathbf{cp}(n) \sim \sqrt{\pi n/2}$

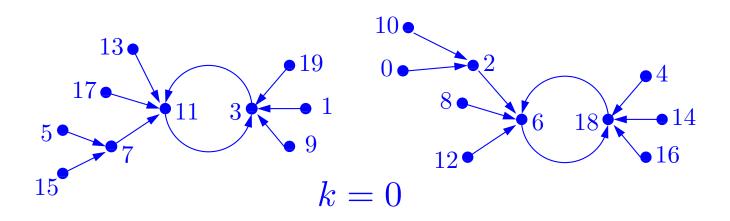




- ► Expected number of cycle points : $\mathbf{cp}(n) \sim \sqrt{\pi n/2}$
- **Expected maximal tail length** : $\mathbf{mt}(n) \sim \sqrt{\pi n/8}$

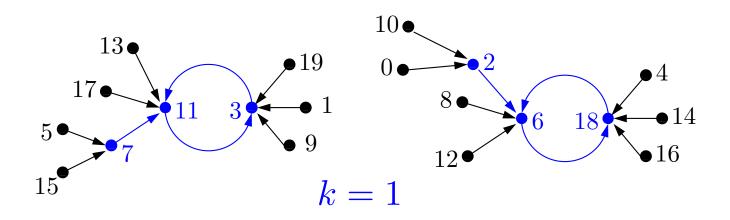


- **Expected number of cycle points** : $\mathbf{cp}(n) \sim \sqrt{\pi n/2}$
- ► Expected maximal tail length : $\mathbf{mt}(n) \sim \sqrt{\pi n/8}$
- **Expected** number of r-nodes : $\mathbf{rn}(n,r) \sim \frac{n}{r!e}$



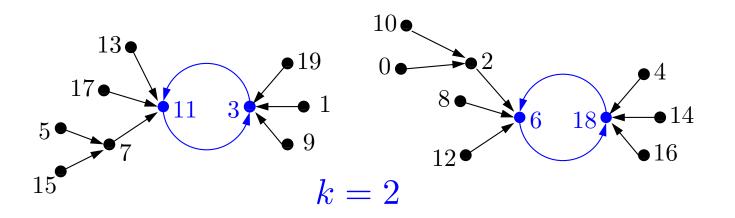
- **Expected number of cycle points** : $\mathbf{cp}(n) \sim \sqrt{\pi n/2}$
- ► Expected maximal tail length : $\mathbf{mt}(n) \sim \sqrt{\pi n/8}$
- **Expected number of** r**-nodes** : $\mathbf{rn}(n,r) \sim \frac{n}{r!e}$
- **Expected** number of image points : $\mathbf{ip}(n,k) \sim n(1-\tau_k)$ where $\tau_0=0$ and $\tau_{k+1}=e^{-1+\tau_k}$





- ► Expected number of cycle points : $\mathbf{cp}(n) \sim \sqrt{\pi n/2}$
- lacksquare Expected maximal tail length : $\mathbf{mt}(n) \sim \sqrt{\pi n/8}$
- **Expected** number of r-nodes : $\mathbf{rn}(n,r) \sim \frac{n}{r!e}$
- Expected number of image points : $\mathbf{ip}(n,k) \sim n(1-\tau_k)$ where $\tau_0=0$ and $\tau_{k+1}=e^{-1+\tau_k}$





- ► Expected number of cycle points : $\mathbf{cp}(n) \sim \sqrt{\pi n/2}$
- ► Expected maximal tail length : $\mathbf{mt}(n) \sim \sqrt{\pi n/8}$
- **Expected** number of r-nodes : $\mathbf{rn}(n,r) \sim \frac{n}{r!e}$
- Expected number of image points : $\mathbf{ip}(n,k) \sim n(1-\tau_k)$ where $\tau_0=0$ and $\tau_{k+1}=e^{-1+\tau_k}$



Bounding Entropy with Image Points

▶ Upper bound given by number of image points [Hong Kim 05] :

$$\mathbf{H_k} \le log_2(n) + log_2(1 - \tau_k)$$

 \blacktriangleright Example for $n=2^{16}$

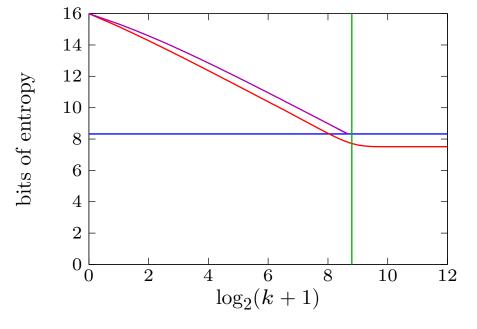


image size (\log_2) — cycle points (\log_2) — maximal tail length — empirical entropy —



New Entropy Estimator

New Entropy Estimator (1)

Motivation:

► Find an entropy estimator which is more precise than the upper bound given by the number of image points.

Ideas:

- ▶ We assume a uniform initial distribution.
- ▶ If a state can be produced by exactly r other states after one iteration, it has probability r/n.



New Entropy Estimator (2)

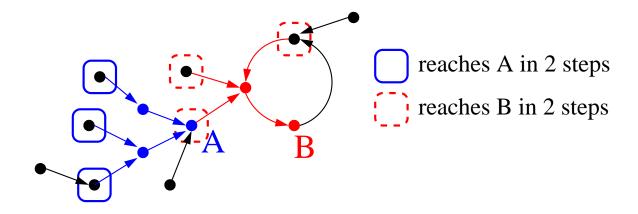
Definition:

Number of points which are reached by r points after k iterations.

$$\varphi \in \mathcal{F}_n : \operatorname{rn}_k^{\varphi}(r) = \#\{i | |\varphi^{-k}(i)| = r\}$$

Average:
$$\mathbf{rn_k}(n,r) = \frac{1}{n^n} \sum_{\varphi \in \mathcal{F}_n} \mathrm{rn}_k^{\varphi}(r)$$

Example for k=2 and r=3:





New Entropy Estimator (3)

Theorem :

For a uniform initial distribution the expected entropy of the inner state after k iterations is :

$$\mathbf{H_k} = \log_2(n) - \sum_{r=1}^{n} \mathbf{rn_k}(n, r) \frac{r}{n} \log_2(r)$$

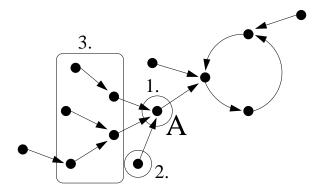
► Theorem:

For an arbitrary initial distribution $P = \{p_1, p_2, \dots, p_n\}$ the expected entropy of the inner state after k iterations is :

$$\mathbf{H}_{\mathbf{k}}^{\mathbf{P}} = \sum_{r=1}^{n} \mathbf{rn}_{\mathbf{k}}(n, r) \frac{1}{\binom{n}{r}} \sum_{1 \le j_1 < \dots < j_r \le n} (p_{j_1} + \dots + p_{j_r}) \log_2 \frac{1}{p_{j_1} + \dots + p_{j_r}}$$

Computation of $\mathbf{rn}_{\mathbf{k}}(n,r)$ (1)

- ▶ k=1 : Use directly the asymptotic value $\mathbf{rn}(n,r)\sim \frac{n}{r!e}$
- $\triangleright k > 1$: Use the fact that such a tree node consists of :
 - 1. A node.
 - 2. A *SET* of *trees* with a depth < k 1.
 - 3. A *CONCATENATION* of j trees of depth $\geq k-1$ and $1 \leq j \leq r$. Their roots are reached by respectively i_1, \ldots, i_j nodes after k-1 iterations such that $i_1 + \cdots + i_j = r$.





Computation of $\mathbf{rn}_{\mathbf{k}}(n,r)$ (2)

▶ By analyzing the generating function of our property we find a $c_k(r)$ such that for $n \to \infty$:

$$\mathbf{rn}_{\mathbf{k}}(n,r) \sim n \ c_k(r)$$

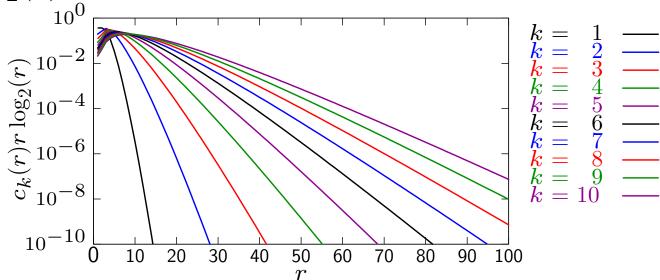
- ▶ We can compute $c_k(r)$ in $O\left(k \ r^2 \log(r)\right)$.
- For a uniform initial distribution we can write :

$$\mathbf{H_k} \sim \log(n) - \sum_{r=1}^{R} c_k(r) r \log_2(r) - \sum_{r=R+1}^{n} c_k(r) r \log_2(r)$$



Remarks

 $ightharpoonup c_k(r)r\log_2(r)$ decreases very fast.



► Approximation :

$$H_k(R) = \log_2(n) - \sum_{r=1}^{R} c_k(r) \ r \ \log_2(r)$$

▶ We ignore the incoming cycle nodes.



Estimation of Entropy Loss with different Methods

| k | | 1 | 2 | 3 | 10 | 50 | 100 |
|----------------|----------|--------|--------|--------|--------|--------|--------|
| empirical data | | 0.8273 | 1.3458 | 1.7254 | 3.1130 | 5.2937 | 6.2529 |
| $n = 2^{16}$ | | | | | | | |
| image points | | 0.6617 | 1.0938 | 1.4186 | 2.6599 | 4.7312 | 5.6913 |
| | R = 50 | 0.8272 | 1.3457 | 1.7254 | 3.1084 | 2.6894 | 1.2524 |
| $H_k(R)$ | R = 200 | 0.8272 | 1.3457 | 1.7254 | 3.1129 | 5.2661 | 5.5172 |
| | R = 1000 | 0.8272 | 1.3457 | 1.7254 | 3.1129 | 5.2918 | 6.2729 |

- ightharpoonup For small k our new estimator is more precise than the upper bound given by the number of image points.
- \blacktriangleright For larger k we need a bigger R to have a small error.



Part 4 Collision Attacks

Collision Attacks (1)

► Collision :

- Different initial states S_0 , S_0' and k,k'>=0 such that $S_k=S_{k'}'$.
- A given S_0 , k, k' >= 0 and $k \neq k'$ such that $S_k = S_{k'}$.
- We compare the attack with a direct search for a collision in the initial state.

Three criteria :

- Number of initial states.
- Space complexity.
- Query complexity.



Collision Attacks (2)

Ideas:

- Using a random function leads to a loss of entropy.
- ► A reduced entropy leads to higher probability of a collision.
- ▶ If two states are the same, then the subsequent output sequences are identical.
- ► Two proposals for an attack on MICKEY in [Hong Kim 05] (no real attacks).



(Proposition [Hong Kim 05])

ightharpoonup Search for collision after k iterations.



(Proposition [Hong Kim 05])

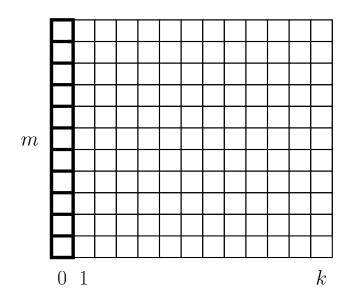
► Search for collision after k iterations.





(Proposition [Hong Kim 05])

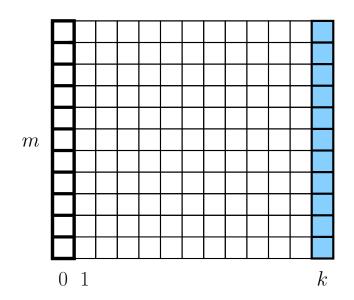
▶ Search for collision after k iterations.





(Proposition [Hong Kim 05])

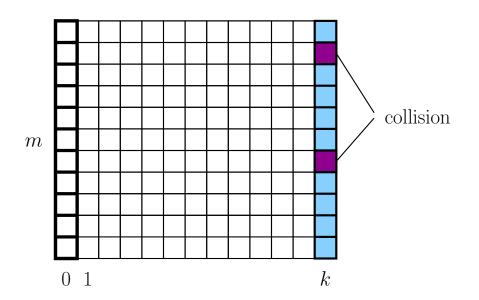
▶ Search for collision after k iterations.





(Proposition [Hong Kim 05])

ightharpoonup Search for collision after k iterations.





(Analysis)

- ▶ Upper bound: $\mathbf{H_k} \leq \log_2(n) \log_2(k) + 1$
- ▶ Birthday paradox: Need $\sim \sqrt{2n/k}$ values in the last row.

| | Attack 1 |
|--------------------------------|---------------------------|
| # initial states | $\sim \sqrt{rac{2n}{k}}$ |
| space complexity [Hong Kim 05] | $\sim \sqrt{rac{2n}{k}}$ |
| query complexity (new) | $\sim \sqrt{2kn}$ |



(Remark)

Under which circumstances is the attack effective?

▶ If we have functions which loose on average more than $2 \log_2(k)$ bits after k iterations.

This means that we don't use a random function, but the principle of the attack stays the same.



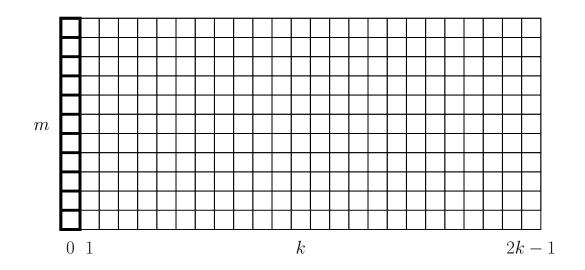
(Proposition [Hong Kim 05])

▶ Iterate 2k times and search for collision in the second half of the intermediate states.



(Proposition [Hong Kim 05])

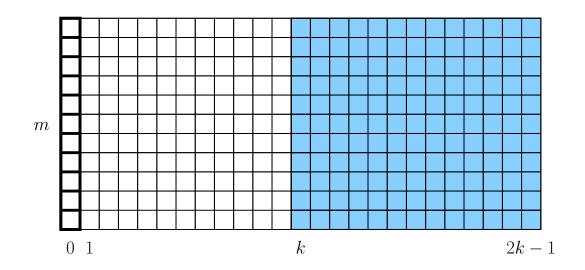
▶ Iterate 2k times and search for collision in the second half of the intermediate states.





(Proposition [Hong Kim 05])

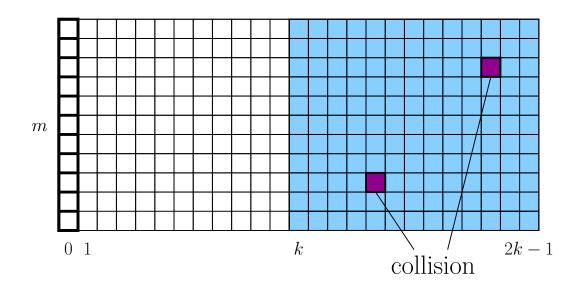
▶ Iterate 2k times and search for collision in the second half of the intermediate states.





(Proposition [Hong Kim 05])

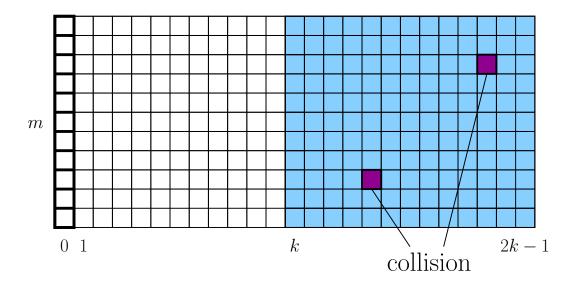
▶ Iterate 2k times and search for collision in the second half of the intermediate states.





(Proposition [Hong Kim 05])

▶ Iterate 2k times and search for collision in the second half of the intermediate states.



▶ [Hong Kim 05]: Magnitude of m such that $m k \sim \sqrt{n/k}$.



(Analysis (new))

- ▶ Let Pr[A] be the probability of no collision in the 2km points.
- ▶ Probability of collision in km points is smaller than 1 Pr[A].
- ▶ By counting arguments : $Pr[A] = \frac{n(n-1)\cdots(n-2km+1)}{n^{2km}}$
- ▶ Birthday Paradox: We need $2mk \approx \sqrt{n}$

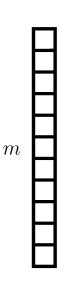
| | Attack 1 | Attack 2 |
|------------------|---------------------------|---------------------------|
| # initial states | $\sim \sqrt{rac{2n}{k}}$ | $\sim rac{\sqrt{n}}{2k}$ |
| space complexity | $\sim \sqrt{rac{2n}{k}}$ | $\sim \frac{\sqrt{n}}{2}$ |
| query complexity | $\sim \sqrt{2kn}$ | $\sim \sqrt{n}$ |



(Distinguished Points)

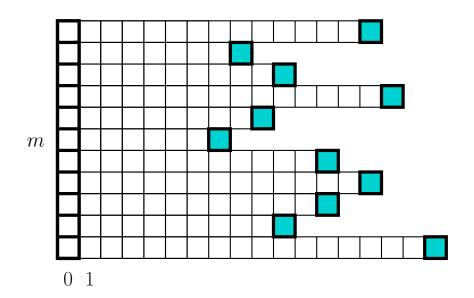


(Distinguished Points)



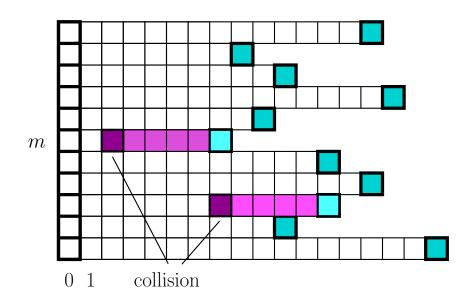


(Distinguished Points)





(Distinguished Points)





(Analysis)

- \blacktriangleright We assume that in total we need again about \sqrt{n} data points.
- ▶ Let c = d/n be the ratio of distinguished points, 0 < c < 1.
- We assume that like for random points the average length of a row is about 1/c.
- ► E.g. $n=2^{20}$, $k_{max}=\sqrt{n}$, and $0.7 \leq \frac{\log_2(d)}{\log_2(n)} \leq 1$ (i.e. $2^{-6} \leq c \leq 1$).

| | Attack 1 | Attack 2 | Attack 3 |
|------------------|---------------------------|---------------------------|------------------|
| # initial states | $\sim \sqrt{rac{2n}{k}}$ | $\sim rac{\sqrt{n}}{2k}$ | $\sim c\sqrt{n}$ |
| space complexity | $\sim \sqrt{rac{2n}{k}}$ | $\sim \frac{\sqrt{n}}{2}$ | $\sim c\sqrt{n}$ |
| query complexity | $\sim \sqrt{2kn}$ | $\sim \sqrt{n}$ | $\sim \sqrt{n}$ |



Part 5 Conclusion

Conclusion

Entropy Estimator:

- ▶ We studied a stream cipher model with a random update function.
- ► We introduced a new estimator which can be iteratively computed.
- \blacktriangleright For small k it is more precise than the previous upper bound.



Conclusion

Collision Attacks:

- Using a random update function introduces an entropy loss.
- ► Till now it was not well studied if this introduce a real threat for our stream cipher model.
- ▶ We showed that the proposed attacks are less effective than expected.

