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/*
//Functions for Broadie-Kaya and Smith Exact simulation in
//the Heston model
*/

#include <
href../../common/math/cdo/cdo_math_h_src.pdfmath.h>
#include <stdio.h>

#include "pnl/pnl_root.h"
#include "
href../../common/math/ESM_func_h_src.pdfESM_func.h"
#include "pnl/pnl_complex.h"
#include "pnl/pnl_specfun.h"
#include "pnl/pnl_mathtools.h"

struct cumulative_function_params
{
    double h;
    int N;
    double *val;
    double u;
};

static double f, g_noV, derivlnf, deriv2lnf, derivg_noV , deriv2g_noV;
static double nu, SK1, SK2, SK3;

// the models constants required everytime we need th compute the characteristic

/*
** in this function we will compute  $f(K)=0.5K/\sinh(0.5K\delta)$ , and  $g(K)= K/\tanh(0.5K\delta)$ 
** and the following quantities  $\text{derivlnf}=f'(K)/f(K)$ ,  $\text{deriv2lnf} = f''(K)/f(K)$ ,  $\text{derivg\_noV}=g'(K)/g(K)$ 
**  $\text{deriv2g\_noV}=g''(K)/g(K)$ . we don't bother to compute the approximation of these quantities
**  $K\delta \ll 1$ , because for our values of  $K$  and  $\delta$ , we'll never get singularities
*/

void ESM_update_const_char(double Kappa, double sigma, double delta, double d)
{

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double tanhk;
double sinh2k;

tanhk = 1. / tanh(0.5 * Kappa * delta);
sinh2k = 1. / pow(sinh(0.5 * Kappa * delta), 2.);
f = 0.5 * Kappa / sinh(0.5 * Kappa * delta);
deriv1nf = 1. / Kappa - 0.5 * delta * tanhk;
deriv2lnf = -1. / (Kappa * Kappa) + pow(0.5 * delta, 2.) * sinh2k + pow(deriv1nf, 2.);

g_noV = Kappa * tanhk;
derivg_noV = tanhk - 0.5 * delta * Kappa * sinh2k;
deriv2g_noV = - 1.*delta * sinh2k + 2.*Kappa * pow(0.5 * delta, 2.) * sinh2k *
nu = 0.5 * d - 1.;
SK1 = sigma * sigma / Kappa;
SK2 = SK1 * SK1;
SK3 = SK2 / Kappa;
}

// |x| <= |v|, CF1_ik converges rapidly
// |x| > |v|, CF1_ik needs O(|x|) iterations to converge

//Gautschi (Euler) equivalent series was proposed by gerard
//Jungman "GSL", and I've implemented another method
// modified Lentz's method, see
// Lentz, Applied Optics, vol 15, 668 (1976)
/*
 * using Gautschi (Euler) equivalent series.
 */

static int
bessel_I_CF1_ser_real(const double x, double *ratio)
{
    const int maxk = 20000;
    double tk    = 1.0;
    double sum   = 1.0;
    double rhok  = 0.0;
    int k;
    double ak;

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for (k = 1; k < maxk; k++)
{
    ak = 0.25 * (x / (nu + k)) * x / (nu + k + 1.0);
    rhok = -ak * (1.0 + rhok) / (1.0 + ak * (1.0 + rhok));
    tk *= rhok;
    sum += tk;
    if (fabs(tk / sum) < DBL_EPSILON) break;
}

*ratio = x / (2.0 * (nu + 1.0)) * sum;

return 0;
}

/*
 * this function compute the ratio Inu'(x)/Inu(x) & Inu''(x)/Inu(x)
 * x!=0;
 */

static int
bessel_Inu_real_ratios(double x, double *ratio1, double *ratio2)
{
    double ratio;
    int stat_I;

    stat_I = bessel_I_CF1_ser_real(x, &ratio);
    *ratio1 = nu / x + ratio;
    *ratio2 = 1. + (nu / x) * (nu / x) - nu / (x * x) - ratio / x;
    return stat_I;
}

/*
 * compute the mean and the variance by derivating the characteristic functions!
 */

void Moments_ESM(double Vs, double Vt, double Kappa, double sigma, double delta,
               double d, double *mean, double *variance)
{
    double b1, b2;
    double V_V;
    double VV;

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double derivg;
double deriv2g;
double phiR;
double deriv_phiR, derivh, deriv2h, mean2;

V_V = (Vs + Vt) / (sigma * sigma);
VV = sqrt(Vs * Vt) / (sigma * sigma);
derivg = - V_V * derivg_noV;
deriv2g = - V_V * deriv2g_noV + derivg * derivg;
phiR = 4.*VV * f;
bessel_Inu_real_ratios(phiR, &b1, &b2);
deriv_phiR = phiR * derivlnf;
derivh = deriv_phiR * b1;
deriv2h = phiR * deriv2lnf * b1 + pow(deriv_phiR, 2.) * b2;

mean2 = - SK3 * (derivlnf + derivg + derivh) + SK2 *
        (deriv2lnf + deriv2g + deriv2h + 2.*(derivlnf * derivg + derivlnf * de

*mean = -SK1 * (derivlnf + derivg + derivh);
*variance = mean2 - pow(*mean, 2.);
}

/*
 * for a given Vt and Vs, we compute all the values required in order to compute
 */

void values_all_ESM(int M, double Vs, double Vt, double Kappa, double sigma, dou
        double d, double epsilon, double h, int *N, double *values)
{

double a;
double module;
int sign_arg;
dcomplex y, g, gd;

double V_V;
double VV;
double phiR;
double bessel_0;
int j, m, signe;
dcomplex Phi, Phi1, Phi2, phiC, besselC, Phi3, char_func;

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V_V = (Vt + Vs) / (sigma * sigma);
VV = sqrt(Vt * Vs) / (sigma * sigma);
phiR = 4.*VV * f;
j = 0;
m = 0;
signe = 1;
bessel_0 = pnl_bessel_i_scaled(nu, phiR);
do
{
    a = h * (j + 1);
    y = Complex(Kappa * Kappa, -2.*sigma * sigma * a);
    g = Csqrt(y);
    gd = RCmul(0.5 * delta, g);

    Phi = Cdiv(g, Csinh(gd));
    Phi = RCmul(0.5, Phi);
    Phi1 = CRdiv(Phi, f);

    Phi2 = Cdiv(g, Ctanh(gd));
    Phi2 = Cminus(Phi2);
    Phi2 = CRadd(Phi2, g_noV);
    Phi2 = RCmul(V_V, Phi2);
    Phi2 = Cexp(Phi2);

    phiC = RCmul(4.*VV, Phi);

    /*
     * continuite de la fonction de bessel, on determine l'argument non princi
     * Arg(phiC) is increasing from 0 when a=0 to +infinity when a is infinite
     * we need to keep track on arg(phiC) and change the branch every time we
     * pass from a positive argument to a negative argument by subtracting 2*
     */
    sign_arg = (Carg(phiC) > 0) ? 1 : -1;
    if (sign_arg - signe == -2) m++; // change the branch
    signe = sign_arg;

    besselC = pnl_complex_bessel_i_scaled(nu, phiC);

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    bessellC = Cmul(bessellC, Complex_polar(1., -2 * m * M_PI * nu)); // analyti

    Phi3 = CRdiv(bessellC, bessell_0);
    Phi3 = RCmul(exp(Creal(phiC) - phiR), Phi3); // the non scaled versions

    char_func = Cmul(Cmul(Phi1, Phi2) , Phi3);

    values[j] = Creal(char_func) / (j + 1);
    module = Cabs(char_func) / (j + 1);
    j++;
}
while (module > M_PI * epsilon / 2 && j < M);
*N = j - 1;
}

/*
 * we gonna find all the values required to compute all the cumulative
 * functions and their invrerses, in the AESM model(Smith algorithm). z is of th
 * z_i=i*Vmax/N_z_grid i=1...NS
 */
void values_all_AESM(int M, double Vmax, int NS , double Kappa, double sigma, do
    double *mean, double *variance, double *h, int *N, double *
{
    int i;
    double z_i;

    for (i = 0; i < NS ; i++)
    {

        //NS for number of slices
        z_i = Vmax * (i + 1) / NS; //so z_i goes from Vmax/NS to Vmax;
        Moments_ESM(z_i, z_i, Kappa, sigma, delta, d, &mean[i], &variance[i]);
        h[i] = M_PI / (mean[i] + 5.*sqrt(variance[i]));
        values_all_ESM(M, z_i, z_i, Kappa, sigma, delta, d, epsilon, h[i], &N[i],

    }
}

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static double cumulative_function_ESM(double x, double h, int N, double *val)
{
    int j;
    double sum;

    sum = h * x / 2.;
    for (j = 0; j < N + 1 ; j++)
    {
        sum += sin(h * (j + 1) * x) * val[j];
    }
    return 2.*sum / M_PI;
}

static double cumulative_function_ESM2(double x, void *params)
{
    struct cumulative_function_params *p = (struct cumulative_function_params *) p
    double h;
    int N;
    double u;

    double *val = p->val;

    h = p->h;
    N = p->N;
    u = p->u;

    return cumulative_function_ESM(x, h, N, val) - u;
}

double inverse_ESM(double u, double h, int N, double *val)
{
    PnlFunc F;
    double x_lo, x_hi; // x_hi=Ueps  ~~ the upper bond for the sampling by \ int_u
    double tol;

    struct cumulative_function_params params = { h, N, val, u};
    x_lo = 0.0;
    x_hi = M_PI / h;

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tol = 1.e-6;
F.F = &cumulative_function_ESM2;
F.params = &params;

return pnl_root_brent(&F, x_lo, x_hi, &tol);
}
```