

[Help](#)

```
extern "C" {
#include "
href../../../../mod/doublehes1d/doublehes1d_std/doublehes1d_std_h_src.pdfhes1d_std.
#include "
href../../../../common/enums_h_src.pdfenums.h"
#include "
href../../../../common/math/clustering_h_src.pdfmath/clustering.h"
}

#include "pnl/pnl_mathtools.h"
#include "pnl/pnl_random.h"
#include "pnl/pnl_basis.h"
#include "pnl/pnl_vector.h"
#include "pnl/pnl_matrix.h"
#include <cstdlib>
#include <cmath>
using namespace std;

#if defined(PremiaCurrentVersion) && PremiaCurrentVersion < (2016+2) //The "#els
extern "C" {
static int CHK_OPT(MC_JainOosterlee_Heston)(void *Opt, void *Mod)
{
    return NONACTIVE;
}
int CALC(MC_JainOosterlee_Heston)(void *Opt, void *Mod, PricingMethod *Met)
{
    return AVAILABLE_IN_FULL_PREMIA;
}
}
#else

typedef enum {
    KMEANS = 1,
    RB      = 2,
} ClusteringMethods;

/**
```

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    * @brief Option types.
    */
typedef enum {
    CALL = 1,
    PUT  = 2,
} OptionTypes;

/**
 * @brief Option styles.
 */
typedef enum {
    EUROPEAN = 1,
    AMERICAN = 2,
} ExerciseTypes;

/**
 * @brief Possible means for payoffs.
 */
typedef enum {
    GEOMETRIC = 1,
    ARITHMETIC = 2,
} OptionMeanTypes;

// generic instrument
static ExerciseTypes    ExerciseType = EUROPEAN;
int                     dim = 1;
double                  T = 1.;
int   NumExerciseDates = 0;
double* ExerciseDates = NULL;
double*   CDividendR = NULL;

// vanilla
OptionMeanTypes OptionMeanType = GEOMETRIC;
OptionTypes    OptionType = PUT;
double Strike = 40.;
double* S0 = NULL;
double* V0 = NULL;
double r=0.;
double kappa ; // mean reversion speed
double theta ; // long mean run

```

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double xi    ; // volatility of volatility
double discount = 0.;

// basket
double rho = 0.;
PnlMat* rhoMat    = NULL;
PnlMat* CholRhoMat = NULL;

// model
int  NRepl = 5;
int  Nsteps = 4;
double* DiscretDates = NULL;
int numDates  = 0;
double* Dates = NULL;

// pricer
int ClustMethod = KMEANS;
int K = 2;
int H = 3;

void (*getRegressionMatrix) (PnlMat*, int, int, int, const PnlMat*);

/**
 * @brief Set exercise dates.
 *
 * @param [in] numED Indicate time step between exercise dates : T/numED.
 */
static void setExerciseDates(int numED)
{
    int i;
    ExerciseDates = (double*) malloc((numED+1)*sizeof(double));
    if (ExerciseDates == NULL)
        abort();
    for (i = 0; i <= numED; i++)
        ExerciseDates[i] = i*(T/numED);
}

/**
 * @brief Create the correlation matrix.

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```

    */
static void setRhoMat()
{
    rhoMat = pnl_mat_create_from_scalar(2*dim, 2*dim, rho);
    pnl_mat_set_diag(rhoMat, 1., 0);

    if (dim > 1)
    {
        // add all correlations between assets and volatilities
        PnlMat* assets_assets_Corr = pnl_mat_create_from_scalar(dim, dim, rho);
        PnlMat* vol_vol_Corr       = pnl_mat_create_from_scalar(dim, dim, rho);

        pnl_mat_set_subblock(rhoMat, assets_assets_Corr, 0, 0);
        pnl_mat_set_subblock(rhoMat, vol_vol_Corr, dim, dim);

        pnl_mat_set_diag(rhoMat, 1., 0);
        pnl_mat_set_diag(rhoMat, 1., -dim);
        pnl_mat_set_diag(rhoMat, 1., dim);

        pnl_mat_free(&assets_assets_Corr);
        pnl_mat_free(&vol_vol_Corr);
    }
}

/**
 * @brief Create Sigma matrix by doing Cholesky decomposition.
 */
static void setCholRhoMat()
{
    CholRhoMat = pnl_mat_copy(rhoMat);

    if (pnl_mat_chol(CholRhoMat) == FAIL)
        abort();
}

/**
 * @brief Free the correlation and Sigma matrices.
 */
static void freeRhoCholRhoMats()

```

```

{
    if (rhoMat != NULL)
        pnl_mat_free(&rhoMat);
    if (CholRhoMat != NULL)
        pnl_mat_free(&CholRhoMat);
}

/**
 * @brief Compute the exercise value.
 *
 * @param [in] SPaths Simulated stochastic paths.
 * @param [in] step Time step in which it is computed the exercise value.
 * @param [in, out] ExerciseValue Computed exercise value.
 *
 * Memory must be previously reserved.
 */
static void getExerciseValue(PnlMat** SPaths, int step, PnlVect* ExerciseValue)
{
    PnlMat* SPathsAux2;
    PnlMat* SPathsAux;
    int i;
    double aux;
    assert(SPaths != NULL);
    assert(ExerciseValue != NULL);

    // Simulated stochastic paths at time step 'step'
    SPathsAux2 = pnl_mat_copy(SPaths[step]);
    SPathsAux = pnl_mat_create(NRepl, dim);
    pnl_mat_extract_subblock(SPathsAux, SPathsAux2, 0, NRepl, 0, dim);

    if (dim > 1)
    {
        if (OptionMeanType == GEOMETRIC)
            pnl_mat_cumprod(SPathsAux, 'c');
        else if (OptionMeanType == ARITHMETIC)
            pnl_mat_cumsum(SPathsAux, 'c');
    }
    pnl_mat_get_col(ExerciseValue, SPathsAux, (SPathsAux->n)-1);

    if (OptionType == CALL) // Call payoff
    {

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    for (i = 0; i < ExerciseValue->size; i++)
    {
        if (OptionMeanType == GEOMETRIC)
            aux = pow(GET(ExerciseValue, i), 1. / ((double) SPathsAux->n))
                - Strike;
        else
            aux = GET(ExerciseValue, i)/((double) SPathsAux->n) - Strike;
        if (aux < 0)
            LET(ExerciseValue, i) = 0.;
        else
            LET(ExerciseValue, i) = aux;
    }
}
else if (OptionType == PUT) // Put payoff
{
    for (i = 0; i < ExerciseValue->size; i++)
    {
        if (OptionMeanType == GEOMETRIC)
            aux = Strike -
                pow(GET(ExerciseValue, i), 1. / ((double) SPathsAux->n));
        else
            aux = Strike - GET(ExerciseValue, i)/((double) SPathsAux->n);
        if (aux < 0)
            LET(ExerciseValue, i) = 0.;
        else
            LET(ExerciseValue, i) = aux;
    }
}
else
    printf("\ nOption type not recognised.\ n\ n");

pnl_mat_free(&SPathsAux);
pnl_mat_free(&SPathsAux2);

return;
}

/**
 * @brief Compute the continuation value.
 *

```

```

* @param [in] SPaths Simulated stochastic paths.
* @param [in] i Time step to which we actualise.
* @param [in, out] CashFlows At entry, value at time step j.
*                               At exit, continuation value.
* @param [in] j Time step from which we actualise.
* @param [in] dat Dates.
*/
static void getContinuationValue(PnlMat** SPaths, int i, PnlVect* CashFlows,
                                int j, const double* dat)
{
    assert(SPaths != NULL);
    assert(CashFlows != NULL);

    discount = exp(-r*(dat[j] - dat[i]));
    pnl_vect_mult_scalar(CashFlows, discount);

    return;
}

/**
* @brief Set discretization dates.
*
* @param [in] numDD Indicate time step between discretization dates : T/numDD.
*/
static void setDiscretDates(int numDD)
{
    int i;
    DiscretDates = (double*) malloc((numDD+1)*sizeof(double));
    for (i = 0; i <= numDD; i++)
        DiscretDates[i] = i*(T/numDD);
}

/**
* @brief Compare two objects.
*
* @param [in] arg1 Object 1.
* @param [in] arg2 Object 2.
*
* @retval -1 Second object bigger.

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    * @retval 1 First object bigger.
    * @retval 0 Objects are equals.
    */
int comparer(const void *arg1, const void *arg2)
{
    if (*(double*) arg1 < *(double*) arg2)
        return -1;
    else if (*(double*) arg1 > *(double*) arg2)
        return 1;
    else
        return 0;
}

/**
 * @brief Compose the ensemble of exercise and discretization dates without
 *        repetitions.
 */
static void setDates()
{
    setDiscretDates(Nsteps);
    if (NumExerciseDates != 0)
    {
        setExerciseDates(NumExerciseDates);
        numDates = Nsteps + NumExerciseDates;
    }
    else
        numDates = Nsteps + 1;

    Dates = (double*) malloc(numDates*sizeof(double));
    if (Dates == NULL)
        abort();
    memcpy(Dates, DiscretDates, (Nsteps+1)*sizeof(double));
    if (NumExerciseDates != 0)
    {
        int i;
        int count = 1;
        memcpy(&Dates[Nsteps+1], &ExerciseDates[1],
            (NumExerciseDates-1)*sizeof(double));

        // Quick-Sort

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        qsort(Dates, numDates, sizeof(double), comparer);
        // remove repetitions
        for (i = 1; i < numDates; i++)
        {
            if (Dates[i] != Dates[i-1])
            {
                Dates[count] = Dates[i];
                count++;
            }
        }
        numDates = count;
    }

    return;
}

/**
 * @brief Generate the stochastic paths.
 *
 * @param [out] SPaths Simulated stochastic paths.
 * @param [in] generator Random generator.
 */
static void getTrajectories(PnlMat** SPaths, PnlRng* generator)
{
    int i, j;
    double dt;
    int k, l;
    double depBrowS, depBrowV;
    double prev_var;
    double alfonsiAux = 0.0;
    PnlMat* SPathsAux;
    PnlMat* NormalMat = NULL;

    assert(SPaths != NULL);
    assert(generator != NULL);

    /// STEP I : Generating grid points (sample paths)
    SPathsAux = pnl_mat_create(2*dim, numDates);

    for (j = 0; j < NRepl; j++)

```

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{
    for (l = 0; l < dim; l++)
    {
        MLET(SPathsAux, l, 0) = log(S0[l]);
        MLET(SPathsAux, l+dim, 0) = V0[l];
    }
    NormalMat = pnl_mat_new();
    pnl_mat_rng_normal(NormalMat, 2*dim, numDates, generator);

    for (i = 1; i < numDates; i++)
    {
        dt = Dates[i] - Dates[i-1];

        for (k = 0; k < dim; k++)
        {
            depBrowS = 0.0;
            depBrowV = 0.0;

            for (l = 0; l < 2*dim; l++)
            {
                depBrowS += MGET(CholRhoMat, k, l) * MGET(NormalMat, l, i);
                depBrowV += MGET(CholRhoMat, k+dim, l) * MGET(NormalMat, l, i);
            }
            prev_var = MGET(SPathsAux, k+dim, i-1);

            MLET(SPathsAux, k, i) = MGET(SPathsAux, k, i-1) +
                                   (r - CDividendR[k] - 0.5*prev_var)*dt +
                                   sqrt(fabs(prev_var)*dt)*depBrowS;

            // Euler scheme with abs inside the sqrt function
            MLET(SPathsAux, k+dim, i) = prev_var + kappa*(theta - prev_var)*
                                         xi*sqrt(fabs(prev_var)*dt)*depBrowV;
            // Alfonsi scheme, must have theta*kappa - 0.5*nu^2 > 0
            alfonsiAux = xi*sqrt(dt)*depBrowV +
                         sqrt(SQR(xi*sqrt(dt)*depBrowV) +
                              4.*(prev_var + (kappa*theta - 0.5*SQR(xi))*dt)
                              (1. + kappa*dt));
            alfonsiAux = alfonsiAux / (2.*(1. + kappa*dt));
            MLET(SPathsAux, k+dim, i) = SQR(alfonsiAux);
        }
    }
}

```

```

        for (i = 0; i < numDates; i++)
        {
            if (j == 0)
                pnl_mat_resize(SPaths[i], NRepl, 2*dim);
            for (k = 0; k < dim; k++)
            {
                MLET(SPaths[i], j, k) = exp(MGET(SPathsAux, k, i));
                MLET(SPaths[i], j, k+dim) = MGET(SPathsAux, k+dim, i);
            }
        }

        pnl_mat_free(&NormalMat);
    }

    pnl_mat_free(&SPathsAux);

    return;
}

/**
 * @brief Compute a clustering with a chosen method.
 *
 * @param [in] SPaths Matrix to cluster.
 * @param [out] SPaths_Clusterized Vector indicating which cluster correspond to
 * each row of SPaths.
 * @param [in, out] KMctrs Centres for k-means clustering algorithm.
 * Optional, can be NULL.
 * @param [in] rng Random generator.
 *
 * @retval OK Clustering done correctly.
 * @retval ERR An error occurred.
 */
static int clustering(const PnlMat* SPaths, int* SPaths_Clusterized,
                    PnlMat** KMctrs, PnlRng* rng)
{
    assert(SPaths != NULL);
    assert(SPaths_Clusterized != NULL);
    assert(rng != NULL);

```

```

if (ClustMethod == KMEANS)
{
    Model_kmeans mod;
    if (*KMctrs == NULL)
    {
        if (kmeans(SPaths->array, SPaths->m, SPaths->n, K, SPaths_Clusterize
                    &mod, NULL, MAX_ITERATIONS, rng) == ERR)
        {
            freeModel_kmeans(&mod);
            return ERR;
        }
        *KMctrs = pnl_mat_create_from_ptr(K, SPaths->n, mod.centroids);
    }
    else
    {
        if (kmeans(SPaths->array, SPaths->m, SPaths->n, K, SPaths_Clusterize
                    &mod, (*KMctrs)->array, 1, rng) == ERR)
        {
            freeModel_kmeans(&mod);
            return ERR;
        }
    }
    freeModel_kmeans(&mod);
}
else if (ClustMethod == RB)
{
    // 2^(Ncols*p) number of clusters for recursive bifurcation
    int p1 = (int) (log(K)/(log(2.)*(SPaths->n)));
    if (recursiveBifurcation(SPaths, p1, SPaths_Clusterized) == ERR)
        return ERR;
}
else // It is not a valid clustering method
    return ERR;

return OK;
}

/**
 * @brief Search the index of an integer vector which values are equal to value.
 *

```

```

* @param [out] index Pointer to the array with index found.
* @param [in] value Integer value to compare with.
* @param [in] vect Integer vector.
* @param [in] len Vector length.
*
* @return Number of index found.
*/
static int findIndex_EqualValueInt(int** index, int value, const int* vect, int
{
    int i;
    int count = 0;
    int allocatedTam = 0;
    int futurTam = 400;
    int* indexAux;
    assert(vect != NULL);

    for (i = 0; i < len; i++)
    {
        if (vect[i] == value)
        {
            if (count >= allocatedTam)
            {
                allocatedTam = futurTam;
                indexAux = (int*) realloc(*index, allocatedTam*sizeof(int));
                if (indexAux == NULL)
                    abort();
                *index = indexAux;
                futurTam = futurTam*2;
            }
            (*index)[count] = i;
            count++;
        }
    }

    return count;
}

/**
* @brief Search the index corresponding to vector1 values greater than vector2

```

```

*
* @param [out] index Pointer to the array with index found.
* @param [in] vect1 Vector 1.
* @param [in] vect2 Vector 2.
*
* @return Number of index found.
*/
static int findIndex_GreaterValue(int** index, const PnlVect* vect1,
                                   const PnlVect* vect2)
{
    int i;
    int count = 0;
    int allocatedTam = 0;
    int futurTam = 100;
    int* indexAux;
    assert(vect1 != NULL);
    assert(vect2 != NULL);

    for (i = 0; i < vect1->size; i++)
    {
        if (GET(vect1, i) > GET(vect2, i))
        {
            if (count >= allocatedTam)
            {
                allocatedTam = futurTam;
                indexAux = (int*) realloc(*index, allocatedTam*sizeof(int));
                if (indexAux == NULL)
                    abort();
                *index = indexAux;
                futurTam = futurTam*2;
            }
            (*index)[count] = i;
            count++;
        }
    }

    return count;
}

```

```

/**
 * @brief Set the value of Expected Positive Exposure, Expected Negative Exposure
 *        and Mark To Market Forward vectors in a given time step.
 *
 * @param [in] CashFlows Data.
 * @param [in] ExerciseTime Exercise dates information at time step 'step'.
 * @param [in] step Time step.
 * @param [in, out] EPE Expected Positive Exposure vector.
 * @param [in, out] ENE Expected Negative Exposure vector.
 * @param [in, out] MtMFwd Mark To Market Forward vector.
 */
static void getExposures(const PnlVect* CashFlows, const PnlVect* ExerciseTime,
                        int step, PnlVect* EPE, PnlVect* ENE, PnlVect* MtMFwd)
{
    PnlVect* AuxPE = pnl_vect_copy(CashFlows);
    PnlVect* AuxNE = pnl_vect_copy(CashFlows);
    PnlVect* AuxMtMFwd = pnl_vect_copy(CashFlows);

    int i;
    for (i = 0; i < CashFlows->size; i++)
    {
        if (step > GET(ExerciseTime, i))
        {
            LET(AuxPE, i) = 0.;
            LET(AuxNE, i) = 0.;
        }
        else
        {
            LET(AuxPE, i) = GET(AuxPE, i) * exp(-r*(Dates[step]-Dates[0]));
            LET(AuxNE, i) = GET(AuxNE, i) * exp(-r*(Dates[step]-Dates[0]));
            LET(AuxMtMFwd, i) = GET(AuxMtMFwd, i) * exp(-r*(Dates[step]-Dates[0]));
            if (GET(CashFlows, i) < 0.)
                LET(AuxPE, i) = 0.;
            else
                LET(AuxNE, i) = 0.;
        }
    }

    LET(EPE, step) = pnl_vect_sum(AuxPE) / ((double) AuxPE->size);
    LET(ENE, step) = pnl_vect_sum(AuxNE) / ((double) AuxNE->size);
    LET(MtMFwd, step) = pnl_vect_sum(AuxMtMFwd) / ((double) AuxMtMFwd->size);
}

```

```

    pnl_vect_free(&AuxPE);
    pnl_vect_free(&AuxNE);
    pnl_vect_free(&AuxMtMFwd);

    return;
}

/**
 * @brief Generate the regression matrix of monomials.
 *
 * @param [in, out] RegrMat Regression matrix to fill.
 * @param [in] Nrows Number of rows of RegrMat.
 * @param [in] dataDim Dimension of regression matrix basis.
 * @param [in] maxDegree Maximum degree of regression matrix basis.
 * @param [in] XData Data with which generate matrix columns.
 */
void regressMatMonos(PnlMat* RegrMat, int Nrows, int dataDim, int maxDegree,
                    const PnlMat* XData)
{
    int i, j, k;
    double XDataValue;
    int basisValue;
    int maxDegreeAux;

    PnlVect* Maxs = pnl_vect_create(2*dim);
    PnlVect* mins = pnl_vect_create(2*dim);
    PnlBasis* basis;
    basis = pnl_basis_create_from_degree(PNL_BASIS_CANONICAL, maxDegree, dataDim);

    pnl_mat_resize(RegrMat, Nrows, basis->T->m);

    pnl_mat_minmax(mins, Maxs, XData, 'r');

    for (i = 0; i < basis->T->m; i++)
    {
        for (k = 0; k < Nrows; k++)
        {
            XDataValue = 1.;

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        maxDegreeAux = 0;
        for (j = 0; j < basis->T->n; j++)
        {
            basisValue = basis->T->array[i*(basis->T->n) + j];
            if (basisValue != 0)
                XDataValue *= pow(MGET(XData, k, j) / GET(Maxs, j),
                                   (double) basisValue);
            maxDegreeAux += basisValue;
            if (maxDegreeAux == maxDegree)
                break;
        }
        MLET(RegrMat, k, i) = XDataValue;
    }
}

pnl_basis_free(&basis);
pnl_vect_free(&mins);
pnl_vect_free(&Maxs);

return;
}

/**
 * @brief Compute calibration of a model.
 *
 * @param [in] SPaths Simulated stochastic paths.
 * @param [out] a Coefficients found in each time step for each cluster.
 * @param [out] KMctrs Centres for k-means clustering algorithm for each time
 *                step. (numDates-2) matrices of Kxdim.
 * @param [out] ExerciseTime Early-exercise policy for each path.
 * @param [in, out] EPE Expected Positive Exposure vector.
 * @param [in, out] ENE Expected Negative Exposure vector.
 * @param [in, out] MtMFwd Mark To Market Forward vector.
 * @param [in] rng Random generator.
 *
 * @retval OK Calibration done correctly.
 * @retval ERR An error occurred.
 */
static int calibration(PnlMat** SPaths, PnlMat** a, PnlMat** KMctrs,
                      PnlVect** ExerciseTime, PnlVect* EPE, PnlVect* ENE,

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        PnlVect* MtMFwd, PnlRng* rng)
{
    assert(rng != NULL);

    if ( (SPaths == NULL) || (a == NULL) || (EPE == NULL) || (ENE == NULL) ||
        (MtMFwd == NULL) )
        return ERR;
    // There must be allocated memory for centroids in k-means
    if ( (ClustMethod == KMEANS) && (KMctrs == NULL) )
        return ERR;
    // Approximation dimension must be greater than 0
    if (H <= 0)
        return ERR;

    int* SPaths_Clusterized = (int*) malloc(NRepl*sizeof(int));
    int* ExerciseIdx = NULL;
    int* bundlePaths = NULL;
    // First set exercise time at expiration for convenience
    *ExerciseTime = pnl_vect_create_from_scalar(NRepl, numDates-1);

    // STEP II : Option value at terminal time
    PnlVect* CashFlows = pnl_vect_create(NRepl);
    getExerciseValue(SPaths, numDates-1, CashFlows);

    int i, j;
    int cluster;
    int step;
    int nbundlePaths; // number of paths in a bundle
    int nExerciseIdx; // number of Exercise Index
    PnlMat* RegrMat = pnl_mat_new();
    PnlMat* XData = pnl_mat_new();
    PnlMat* KMctrs_i = NULL;
    PnlVect* ContinuationValue = pnl_vect_create(NRepl);
    PnlVect* ExerciseValue = pnl_vect_create(NRepl);
    PnlVect* auxCashFlows = pnl_vect_new();
    PnlVect* auxCashFlows2;

    getExposures(CashFlows, *ExerciseTime, numDates-1, EPE, ENE, MtMFwd);

    for (step = numDates-2; step > 0; step--)
    {

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// update the price
getContinuationValue(SPaths, step, CashFlows, step+1, Dates);

// STEP III : Bundling
// we do the clustering of the paths with the indicated method
if (clustering(SPaths[step], SPaths_Clusterized, &KMctrs_i, rng) == ERR)
{
    pnl_mat_free(&RegrMat);
    pnl_mat_free(&XData);
    pnl_vect_free(&ContinuationValue);
    pnl_vect_free(&ExerciseValue);
    pnl_vect_free(&auxCashFlows);
    pnl_vect_free(&CashFlows);
    free(SPaths_Clusterized);
    free(ExerciseIdx);
    free(bundlePaths);
    if (ClustMethod == KMEANS) pnl_mat_free(&KMctrs_i);
    return ERR;
}
if (ClustMethod == KMEANS)
{
    pnl_mat_clone(KMctrs[step-1], KMctrs_i);
    pnl_mat_free(&KMctrs_i);
}

for (cluster = 1; cluster <= K; cluster++)
{
    // STEP IV : Mapping high-dimesional state space to a
    //              low-dimensional space
    // We keep only the index of the paths of pertinent cluster
    nbundlePaths = findIndex_EqualValueInt(&bundlePaths, cluster,
                                           SPaths_Clusterized, NRepl);
    pnl_mat_resize(XData, nbundlePaths, 2*dim);
    pnl_vect_resize(auxCashFlows, nbundlePaths);

    for (i = 0; i < nbundlePaths; i++)
    {
        for (j = 0; j < dim; j++)
        {
            MLET(XData, i, j) = MGET(SPaths[step], bundlePaths[i], j);
            MLET(XData, i, j+dim) = MGET(SPaths[step], bundlePaths[i], j

```

```

    }
    LET(auxCashFlows, i) = GET(CashFlows, bundlePaths[i]);
}

//Begin computing continuation value
getRegressionMatrix(RegrMat, nbundlePaths, 2*dim, H-1, XData);

// a sont les betas et RegrMat les phi du papier
if (pnl_mat_ls(RegrMat, auxCashFlows) == FAIL)
    abort();
if (step == numDates-2)
    pnl_mat_resize(a[cluster-1], RegrMat->n, numDates-2);
pnl_mat_set_col(a[cluster-1], auxCashFlows, step-1);

// STEP V : Computing the continuation and option values at  $t_{m-1}$ 
// this is the Conditional expectation
auxCashFlows2 = pnl_mat_mult_vect(RegrMat, auxCashFlows);
for (i = 0; i < nbundlePaths; i++)
{
    LET(ContinuationValue, bundlePaths[i]) = GET(auxCashFlows2, i);
}
pnl_vect_free(&auxCashFlows2);
//End computing continuation value
}

// determining the exercise policy, not necessary for european options e
if (ExerciseType == AMERICAN)
{
    getExerciseValue(SPaths, step, ExerciseValue);

    // continuity condition to check at each step
    // we keep the index for which the continuity condition is satisfied
    nExerciseIdx = findIndex_GreaterValue(&ExerciseIdx, ExerciseValue,
                                         ContinuationValue);

    for (i = 0; i < nExerciseIdx; i++)
    {
        LET(CashFlows, ExerciseIdx[i]) = GET(ExerciseValue, ExerciseIdx[i])
        // tau* the optimal stopping time
        LET(*ExerciseTime, ExerciseIdx[i]) = step;
    }
}

```

```

    }

    getExposures(CashFlows, *ExerciseTime, step, EPE, ENE, MtMFwd);
}
getContinuationValue(SPaths, step, CashFlows, step+1, Dates);

getExposures(CashFlows, *ExerciseTime, step, EPE, ENE, MtMFwd);

pnl_mat_free(&RegrMat);
pnl_mat_free(&XData);
pnl_vect_free(&ContinuationValue);
pnl_vect_free(&ExerciseValue);
pnl_vect_free(&auxCashFlows);
pnl_vect_free(&CashFlows);
free(SPaths_Clusterized);
free(ExerciseIdx);
free(bundlePaths);

return OK;
}

/**
 * @brief Compute the direct estimator.
 *
 * @param [in] SPaths Simulated stochastic paths.
 * @param [in] a Regression parameters/coefficients (coordonates in the basis).
 *           H coefficients in each time step for each cluster.
 * @param [in] KMctrs Centres for k-means clustering algorithm for each time
 *           step. (numDates-2) matrices of Kxdim.
 * @param [in] ExerciseTime Early-exercise policy for each path.
 * @param [out] directEstimator Computed direct estimator.
 * @param [in] rng Random generator.
 *
 * @retval OK Direct estimator computed correctly.
 * @retval ERR An error occurred.
 */
static int getDirectEstimator(PnlMat** SPaths, PnlMat** a, PnlMat** KMctrs,
                             PnlVect* ExerciseTime, double* directEstimator,
                             PnlRng* rng)
{

```

```

assert(rng != NULL);

if ((SPaths == NULL) || (a == NULL) || (ExerciseTime == NULL) ||
    (directEstimator == NULL))
    return ERR;
// There must be centroids for k-means
if ( (ClustMethod == KMEANS) && (KMctrs == NULL) )
    return ERR;
// Approximation dimension must be greater than 0
if (H <= 0)
    return ERR;

int step = 1;
int* SPaths_Clusterized = (int*) malloc(NRepl*sizeof(int));
if (SPaths_Clusterized == NULL)
    return ERR;
PnlMat* KMctrs_i = NULL;
if (ClustMethod == KMEANS)
    KMctrs_i = pnl_mat_copy(KMctrs[step-1]);
// STEP III : Bundling, clustering of the paths with the indicated method
if (clustering(SPaths[step], SPaths_Clusterized, &KMctrs_i, rng) == ERR)
{
    free(SPaths_Clusterized);
    if (ClustMethod == KMEANS) pnl_mat_free(&KMctrs_i);
    return ERR;
}

int i, j;
int cluster;
int nbundlePaths; // number of paths in a bundle
int* bundlePaths = NULL;
PnlMat* XData = pnl_mat_new();
PnlMat* RegrMat = pnl_mat_new();
PnlVect* ContinuationValue = pnl_vect_create(NRepl);
PnlVect* auxContValue;
PnlVect* auxCoeff = pnl_vect_create(H);

for (cluster = 1; cluster <= K; cluster++)
{
    // STEP IV : Mapping high-dimesional state space to a low-dimensional sp
    // We keep only the index of the paths of pertinent cluster

```

```

        nbundlePaths = findIndex_EqualValueInt(&bundlePaths, cluster,
                                                SPaths_Clusterized, NRepl);
    pnl_mat_resize(XData, nbundlePaths, 2*dim);
    for (i = 0; i < nbundlePaths; i++)
    {
        for (j = 0; j < dim; j++)
        {
            MLET(XData, i, j) = MGET(SPaths[step], bundlePaths[i], j);
            MLET(XData, i, j+dim) = MGET(SPaths[step], bundlePaths[i], j+dim);
        }
    }

//Begin computing continuation value
    getRegressionMatrix(RegrMat, nbundlePaths, 2*dim, H-1, XData);

    // STEP V : Computing the continuation and option values at t_{m-1}
    // Conditional expectation
    pnl_mat_get_col(auxCoeff, a[cluster-1], step-1);
    auxContValue = pnl_mat_mult_vect(RegrMat, auxCoeff);
    for (i = 0; i < nbundlePaths; i++)
    {
        LET(ContinuationValue, bundlePaths[i]) = GET(auxContValue, i);
    }
    pnl_vect_free(&auxContValue);
//End computing continuation value
}

getContinuationValue(SPaths, step-1, ContinuationValue, step, Dates);
double ContValueMean = pnl_vect_sum(ContinuationValue) /
                        ((double) ContinuationValue->size);

PnlVect* initialPayoff = pnl_vect_create(NRepl);
getExerciseValue(SPaths, step-1, initialPayoff);

*directEstimator = MAX(ContValueMean, GET(initialPayoff, 0));

pnl_mat_free(&RegrMat);
pnl_mat_free(&XData);
if (SPaths_Clusterized != NULL)
{
    free(SPaths_Clusterized);
}

```

```

        SPaths_Clusterized = NULL;
    }
    if (bundlePaths != NULL)
    {
        free(bundlePaths);
        bundlePaths = NULL;
    }
    pnl_vect_free(&initialPayoff);
    pnl_vect_free(&ContinuationValue);
    pnl_vect_free(&auxCoeff);
    if (ClustMethod == KMEANS) pnl_mat_free(&KMctrs_i);

    return OK;
}

/**
 * @brief Compute the path estimator.
 *
 * @param [in] SPaths Simulated stochastic paths.
 * @param [in] a Regression parameters/coefficient (coordonates in the basis).
 *             H coefficients in each time step for each cluster.
 * @param [in] KMctrs Centres for k-means clustering algorithm for each time
 *                 step. (numDates-2) matrices of Kxdim.
 * @param [out] pathEstimator Computed path estimator.
 * @param [out] ExerciseTime Early-exercise policy for each path.
 * @param [in, out] EPE Expected Positive Exposure vector.
 * @param [in, out] ENE Expected Negative Exposure vector.
 * @param [in, out] MtMFwd Mark To Market Forward vector.
 * @param [in] rng Random generator.
 *
 * @retval OK Path estimator computed correctly.
 * @retval ERR An error occurred.
 */
static int getPathEstimator(PnlMat** SPaths, PnlMat** a, PnlMat** KMctrs,
                           double* pathEstimator, PnlVect** ExerciseTime,
                           PnlVect* EPE, PnlVect* ENE, PnlVect* MtMFwd, PnlRng*
{
    assert(rng != NULL);

    if ((SPaths == NULL) || (a == NULL) || (pathEstimator == NULL) ||

```

```

        (EPE == NULL) || (ENE == NULL) || (MtMFwd == NULL))
        return ERR;
// There must be centroids for k-means
if ( (ClustMethod == KMEANS) && (KMctrs == NULL) )
        return ERR;
// Approximation dimension must be greater than 0
if (H <= 0)
        return ERR;

int* SPaths_Clusterized = (int*) malloc(NRepl*sizeof(int));
if (SPaths_Clusterized == NULL)
        return ERR;
int* ExerciseIdx = NULL;
int* bundlePaths = NULL;
// First set exercise time at expiration for convenience
*ExerciseTime = pnl_vect_create_from_scalar(NRepl, numDates-1);

// STEP II : Option value at terminal time
PnlVect* CashFlows = pnl_vect_create(NRepl);
getExerciseValue(SPaths, numDates-1, CashFlows);

int i, j;
int cluster;
int step;
int nbundlePaths; // number of paths in a bundle
int nExerciseIdx; // number of Exercise Index
PnlMat* RegrMat = pnl_mat_new();
PnlMat* XData = pnl_mat_new();
PnlMat* KMctrs_i = NULL;
PnlVect* ContinuationValue = pnl_vect_create(NRepl);
PnlVect* ExerciseValue = pnl_vect_create(NRepl);
PnlVect* auxContValue;
PnlVect* auxCoeff = pnl_vect_new();

getExposures(CashFlows, *ExerciseTime, numDates-1, EPE, ENE, MtMFwd);

for (step = numDates-2; step > 0; step--)
{
        // update the price
        getContinuationValue(SPaths, step, CashFlows, step+1, Dates);

```

```

// STEP III : Bundling
if (ClustMethod == KMEANS)
    KMctrs_i = pnl_mat_copy(KMctrs[step-1]);
if (clustering(SPaths[step], SPaths_Clusterized, &KMctrs_i, rng) == ERR)
{
    free(SPaths_Clusterized);
    free(ExerciseIdx);
    free(bundlePaths);
    pnl_mat_free(&RegrMat);
    pnl_mat_free(&XData);
    pnl_vect_free(&CashFlows);
    pnl_vect_free(&ContinuationValue);
    pnl_vect_free(&ExerciseValue);
    pnl_vect_free(&auxCoeff);
    if (ClustMethod == KMEANS) pnl_mat_free(&KMctrs_i);
    return ERR;
}
if (ClustMethod == KMEANS) pnl_mat_free(&KMctrs_i);

for (cluster = 1; cluster <= K; cluster++)
{
    // STEP IV : Mapping high-dimensional state space to a
    //              low-dimensional space
    // We keep only the index of the paths of pertinent cluster
    nbundlePaths = findIndex_EqualValueInt(&bundlePaths, cluster,
                                           SPaths_Clusterized, NRepl);
    pnl_mat_resize(XData, nbundlePaths, 2*dim);
    for (i = 0; i < nbundlePaths; i++)
    {
        for (j = 0; j < dim; j++)
        {
            MLET(XData, i, j) = MGET(SPaths[step], bundlePaths[i], j);
            MLET(XData, i, j+dim) = MGET(SPaths[step], bundlePaths[i], j+dim);
        }
    }

    //Begin computing continuation value
    getRegressionMatrix(RegrMat, nbundlePaths, 2*dim, H-1, XData);

    // STEP V : Computing the continuation and option values at  $t_{m-1}$ 
    // Conditional expectation

```

```

        pnl_mat_get_col(auxCoeff, a[cluster-1], step-1);
        auxContValue = pnl_mat_mult_vect(RegrMat, auxCoeff);
        for (i = 0; i < nbundlePaths; i++)
        {
            LET(ContinuationValue, bundlePaths[i]) = GET(auxContValue, i);
        }
        pnl_vect_free(&auxContValue);
    //End computing continuation value
}

// determining exercise policy, not necessary for european options for e
if (ExerciseType == AMERICAN)
{
    getExerciseValue(SPaths, step, ExerciseValue);

    // continuity condition to check at each step
    // we keep the index for which the continuity condition is satisfied
    nExerciseIdx = findIndex_GreaterValue(&ExerciseIdx, ExerciseValue,
                                           ContinuationValue);

    for (i = 0; i < nExerciseIdx; i++)
    {
        LET(CashFlows, ExerciseIdx[i]) = GET(ExerciseValue, ExerciseIdx[i]);
        // tau* the optimal stopping time
        LET(*ExerciseTime, ExerciseIdx[i]) = step;
    }
}

getExposures(CashFlows, *ExerciseTime, step, EPE, ENE, MtMFwd);
}
getContinuationValue(SPaths, step, CashFlows, step+1, Dates);

getExposures(CashFlows, *ExerciseTime, step, EPE, ENE, MtMFwd);

*pathEstimator = pnl_vect_sum(CashFlows) / ((double) CashFlows->size);

if (SPaths_Clusterized != NULL)
{
    free(SPaths_Clusterized);
    SPaths_Clusterized = NULL;
}

```

```

    if (ExerciseIdx != NULL)
    {
        free(ExerciseIdx);
        ExerciseIdx = NULL;
    }
    if (bundlePaths != NULL)
    {
        free(bundlePaths);
        bundlePaths = NULL;
    }
    pnl_mat_free(&RegrMat);
    pnl_mat_free(&XData);
    pnl_vect_free(&CashFlows);
    pnl_vect_free(&ContinuationValue);
    pnl_vect_free(&ExerciseValue);
    pnl_vect_free(&auxCoeff);

    return OK;
}

/**
 * @brief Compute either CVA or DVA.
 *
 * @param [in] RR Recovery rate.
 * @param [in] lambda Intensité de défaut.
 * @param [in] EXE Expected Positive or Negative Exposure vector.
 * @param [out] XVA CVA or DVA computed value.
 */
static void getXVA(double RR, double lambda, const PnlVect* EXE, double* XVA)
{
    assert(EXE != NULL);

    int i;
    double auxV = 0.0;

    for (i = 1; i < EXE->size; i++)
        auxV += GET(EXE, i)*(exp((-lambda)*Dates[i-1]) - exp((-lambda)*Dates[i]))

    *XVA = (1. - RR)*auxV;
}

```

```

        return;
    }

/**
 * @brief Compute the Stochastic Grid Bundling Method for given values.
 *
 * @param [in] numAssets Number of assets.
 * @param [in] s_0 Spot.
 * @param [in] strike Strike.
 * @param [in] iir Instantaneous Interest Rate.
 * @param [in] v_0 Initial volatility.
 * @param [in] maturity Maturity.
 * @param [in] cdr Continuous Dividend Rate, q.
 * @param [in] corr Correlation, rho.
 * @param [in] Kappa Mean reversion speed.
 * @param [in] Theta Long mean run.
 * @param [in] Xi Volatility of volatility.
 * @param [in] NR Monte Carlo simulations to perform for path estimator.
 * @param [in] NRC Monte Carlo simulations to perform for calibration and direct
 * estimator.
 * @param [in] NumSteps Discretization steps to perform.
 * @param [in] appDim Approximation dimension.
 * @param [in] numClusters Number of clusters.
 * @param [in] clusteringMethod Method to do the paths clustering.
 * @param [in] generatorType Random generator type.
 * @param [out] directEstimator Computed direct estimator price.
 * @param [out] pathEstimator Computed path estimator price
 *
 * @retval OK SGBM computed correctly.
 * @retval ERR An error occurred.
 *
 * @see getTrajectories
 * @see calibration
 * @see getDirectEstimator
 * @see getPathEstima
 */
int MCJainOosterlee(double S_0, NumFunc_1 *p, double maturity, double strike, d
{
    dim=1;

```

```

    // Spot
    S0 = (double*) malloc(dim*sizeof(double));
    S0[0]=S_0;

// Volatility
    V0 = (double*) malloc(dim*sizeof(double));
    V0[0]=V_0;

    kappa = Kappa;
    theta = Theta;
    xi = Xi;

    // Instantaneous Interest Rate
    r = iir;
    // Continuous Dividend Rate
    CDividendR = (double*) malloc(dim*sizeof(double));
    CDividendR[0]=divid;

    // Correlation
    if ( (corr <= 1) && (corr >= -1) )
        rho = corr;
    else
    {
        printf("\nIt is not a correct correlation value\n\n");
        return ERR;
    }

setRhoMat();
    setCholRhoMat();
    // Maturity
    T = maturity;
    // Strike
    Strike = strike;

    // Monte Carlo simulations to perform
    NRepl = NRC;
    // Discretization steps to perform
    Nsteps = NumSteps;
    NumExerciseDates = 0;
    if ((p->Compute) == &Call)

```

```

OptionType = CALL;
if ((p->Compute) == &Put)
    OptionType = PUT;

    ExerciseType = AMERICAN; // EUROPEAN AMERICAN

    OptionMeanType = ARITHMETIC; // GEOMETRIC ARITHMETIC

    getRegressionMatrix = regressMatMonos;
    ClustMethod = clusteringMethod;
    // approximation dimension
    H = appDim;
    // number of clusters
    if (ClustMethod == KMEANS)
        K = numClusters;
    else if (ClustMethod == RB)
    {
        // 2^(Ncols*p) number of clusters for recursive bifurcation
        int p1 = (int) (log(numClusters)/(log(2.)*2.*dim));
        K = (int) pow(2., p1*2.*dim);
    }
    else // It is not a valid clustering method
        return ERR;

    PnlRng* generator;
    time_t tmp = time(NULL);
    if (generatorType == PNL_RNG_MERSENNE_RANDOM_SEED)
    {
        generator = pnl_rng_create(PNL_RNG_MERSENNE);
        pnl_rng_sseed(generator, tmp);
    }
    else
    {
        generator = pnl_rng_create(generatorType);
        pnl_rng_sseed(generator, 0);
    }

    int i;
    // vector with all dates creation
    setDates();
    PnlMat** SPaths = (PnlMat**) malloc(numDates*sizeof(PnlMat*));

```

```

if (SPaths == NULL)
    return ERR;
for (i = 0; i < numDates; i++)
    SPaths[i] = pnl_mat_new();
// paths generation
getTrajectories(SPaths, generator);

// memory allocation for regression coefficients and centers for kmeans
PnlMat** a = (PnlMat**) malloc(K*sizeof(PnlMat*));
if (a == NULL)
    return ERR;
for (i = 0; i < K; i++)
    a[i] = pnl_mat_create(H, numDates-2);
PnlMat** KMctrs = NULL;
if (ClustMethod == KMEANS)
{
    KMctrs = (PnlMat**) malloc((numDates-2)*sizeof(PnlMat*));
    if (KMctrs == NULL)
        return ERR;
    for (i = 0; i < numDates-2; i++)
        KMctrs[i] = pnl_mat_create(K, 2*dim);
}
PnlVect* ExerciseTime = NULL;
PnlVect* EPE_DE      = pnl_vect_create(numDates);
PnlVect* ENE_DE      = pnl_vect_create(numDates);
PnlVect* MtMFwd_DE   = pnl_vect_create(numDates);
PnlVect* ExerciseTime_PE = NULL;
PnlVect* EPE_PE      = pnl_vect_create(numDates);
PnlVect* ENE_PE      = pnl_vect_create(numDates);
PnlVect* MtMFwd_PE   = pnl_vect_create(numDates);

//BEGIN METHOD
if (calibration(SPaths, a, KMctrs, &ExerciseTime, EPE_DE, ENE_DE, MtMFwd_DE,
               generator) == ERR)
    return ERR;
if (getDirectEstimator(SPaths, a, KMctrs, ExerciseTime, directEstimator,
                      generator) == ERR)
    return ERR;
NRepl = NR;
if (generatorType == PNL_RNG_MERSENNE_RANDOM_SEED)

```

```

        pnl_rng_sseed(generator, tmp);
else
        pnl_rng_sseed(generator, 0);
getTrajectories(SPaths, generator);
if (getPathEstimator(SPaths, a, KMctrs, pathEstimator, &ExerciseTime_PE,
                    EPE_PE, ENE_PE, MtMFwd_PE, generator) == ERR)
        return ERR;

//END METHOD

pnl_rng_free(&generator);
if (ExerciseTime != NULL)
        pnl_vect_free(&ExerciseTime);
if (ExerciseTime_PE != NULL)
        pnl_vect_free(&ExerciseTime_PE);
pnl_vect_free(&EPE_DE);
pnl_vect_free(&ENE_DE);
pnl_vect_free(&MtMFwd_DE);
pnl_vect_free(&EPE_PE);
pnl_vect_free(&ENE_PE);
pnl_vect_free(&MtMFwd_PE);
for (i = 0; i < numDates; i++)
{
        pnl_mat_free(&SPaths[i]);
}
free(SPaths);
SPaths = NULL;
for (i = 0; i < K; i++)
        pnl_mat_free(&a[i]);
free(a);
a = NULL;
freeRhoCholRhoMats();
if (ClustMethod == KMEANS)
{
        for (i = 0; i < numDates-2; i++)
        {
                pnl_mat_free(&KMctrs[i]);
        }
        free(KMctrs);
        KMctrs = NULL;
}

```

```

    if (ExerciseDates != NULL)
    {
        free(ExerciseDates);
        ExerciseDates = NULL;
    }
    if (DiscretDates != NULL)
    {
        free(DiscretDates);
        DiscretDates = NULL;
    }
    if (Dates != NULL)
    {
        free(Dates);
        Dates = NULL;
    }
    if (S0 != NULL)
    {
        free(S0);
        S0 = NULL;
    }
    if (V0 != NULL)
    {
        free(V0);
        V0 = NULL;
    }
    if (CDividendR != NULL)
    {
        free(CDividendR);
        CDividendR = NULL;
    }
    return OK;
}

extern "C" {
int CALC(MC_JainOosterlee_Heston)(void *Opt, void *Mod, PricingMethod *Met)
{
    TYPEOPT *ptOpt = (TYPEOPT *)Opt;
    TYPEMOD *ptMod = (TYPEMOD *)Mod;
    double r, divid;

```

```

r = log(1. + ptMod->R.Val.V_DOUBLE / 100.);
divid = log(1. + ptMod->Divid.Val.V_DOUBLE / 100.);

return MCJainOosterlee(ptMod->S0.Val.V_PDOUBLE,
                        ptOpt->PayOff.Val.V_NUMFUNC_1,
                        ptOpt->Maturity.Val.V_DATE - ptMod->T.Val.V_DATE,
                        ptOpt->PayOff.Val.V_NUMFUNC_1->Par[0].Val.V_PDOUBLE,
                        r,
                        divid, ptMod->Sigma0.Val.V_PDOUBLE
                        , ptMod->MeanReversion.Val.V_PDOUBLE,
                        ptMod->LongRunVariance.Val.V_PDOUBLE,
                        ptMod->Sigma.Val.V_PDOUBLE,
                        ptMod->Rho.Val.V_PDOUBLE, Met->Par[0].Val.V_INT, Met->Par[1].
                        Met->Par[2].Val.V_LONG,
                        Met->Par[3].Val.V_ENUM.value,
                        Met->Par[4].Val.V_INT,
                        Met->Par[5].Val.V_ENUM.value,
                        Met->Par[6].Val.V_INT,
                        &(Met->Res[0].Val.V_DOUBLE), &(Met->Res[1].Val.V_DOUBLE)
);
}

static int CHK_OPT(MC_JainOosterlee_Heston)(void *Opt, void *Mod)
{
    if ((strcmp(((Option *)Opt)->Name, "CallAmer") == 0) || (strcmp(((Option *)Opt
        return OK;

    return WRONG;
}
}
#endif //PremiaCurrentVersion

extern "C" {
static int MET(Init)(PricingMethod *Met, Option *Opt)
{
    //int type_generator;
    if (Met->init == 0)

```

```

    {
        Met->init = 1;

Met->HelpFilenameHint = "MC_JainOosterlee1_ND";
Met->Par[0].Val.V_INT = 10;
    Met->Par[1].Val.V_LONG = 100000;
Met->Par[2].Val.V_LONG = 200000;
    Met->Par[3].Val.V_ENUM.value = 0;
    Met->Par[3].Val.V_ENUM.members = &PremiaEnumMCRNGs;
    Met->Par[4].Val.V_INT = 3;
Met->Par[5].Val.V_ENUM.value = 2;
    Met->Par[5].Val.V_ENUM.members = &PremiaEnumclusteringMethod1;
Met->Par[6].Val.V_INT = 8;

    }

    return OK;
}

PricingMethod MET(MC_JainOosterlee_Heston) =
{
    "MC_JainOosterlee_Heston",
    { { "Number of Exercise Dates", INT, {100}, ALLOW}, {"Number Replication Calibr
        {"Random Generator", ENUM, {0}, ALLOW},
        {"Approximation order", INT, {100}, ALLOW},
{"Clustering Method", ENUM, {0}, ALLOW},
        {"Number of Clusters", INT, {100}, ALLOW},
        {" ", PREMIA_NULLTYPE, {0}, FORBID}
    },
    CALC(MC_JainOosterlee_Heston),
    { {"Direct Estimator", DOUBLE, {100}, FORBID}, {"Path Estimator", DOUBLE, {10
        {" ", PREMIA_NULLTYPE, {0}, FORBID}
    },
    CHK_OPT(MC_JainOosterlee_Heston),
    CHK_mc,
    MET(Init)
};
}

```