

[Help](#)

```
#include "
href../../../../mod/bharchiarella1d/bharchiarella1d_std/bharchiarella1d_std_h_src
#include "
href../../../../common/error_msg_h_src.pdferror_msg.h"
static double *Pn, *Pnn, *Pnnn;

/*****/
static double f0(double t, double beta0, double beta1, double eta)

{

    return (beta0 + beta1 * (1 - exp(-eta * t)));

}

/*****/
/*static double f0_cf(double t,double beta0,double beta1,double eta)
{
    return(beta0+beta1*(1-exp(-eta*t)));
}*/
/*****/

static double f2(double t, double beta1, double eta)

{

    return (beta1 * eta * exp(-eta * t));

}

/*****/

static double D(double t, double beta0, double beta1, double eta, double lambda)

{

    return (f2(t, beta1, eta) + lambda * f0(t, beta0, beta1, eta));

}
```

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/*****/

/*static double alpha(double t, double tau_alpha,double lambda)
{
    return (exp(-lambda*t)/(exp(-lambda*tau_alpha)-exp(-lambda*t)));
}
*/
/*****/

static double psi(double t, double x, double y, double lambda, double tau, double beta0, double beta1)
{
    if (t > 0)
    {
        if (t < tau)
        {
            return (
                lambda * exp(-lambda * t) /
                (exp(-lambda * tau) - exp(-lambda * t)) * (x - f0(t, beta0, beta1)) +
                lambda * exp(lambda * (tau - t)) *
                exp(-lambda * t) /
                (exp(-lambda * tau) - exp(-lambda * t)) * (y - (beta0 + beta1 * (1 - exp(-lambda * tau))))
            );
            /*
            return(max(lambda*exp(-lambda*t)/(exp(-lambda*tau)-
            exp(-lambda*t))*(x-f0(t))-
            lambda*exp(lambda*(tau-t))*exp(-lambda*t)/(exp(-lambda*tau)-
            exp(-lambda*t))*(y-(beta0+beta1*(1-exp(-lambda*tau)))) ,0));
            */
        }
        else
        {
            return (0.0);
        }
    }
    else
    {
        return (0.0);
    }
}

```

```

/*****/
static double mur(double t, double x, double y, double lambda, double beta0, double beta1, double eta)
{
    return (D(t, beta0, beta1, eta, lambda) + psi(t, x, y, lambda, tau, beta0, beta1, eta));
}

/*****/
static double sigmar(double x, double y, double gamma0, double alpha0, double alphas, double alphaf)
{
    return (exp(gamma0 * log(alpha0 + alphas * x + alphaf * y)));
}

/*****/
static double sigma1(double t, double x, double y, double lambda, double tau, double gamma0, double alpha0, double alphas, double alphaf)
{
    return (exp(-lambda * tau + lambda * t) * sigmar(x, y, gamma0, alpha0, alphas, alphaf));
}

/*****/
static double mu1(double t, double x, double y, double tau, double lambda, double gamma0, double alpha0, double alphas, double alphaf)
{
    return (sigma1(t, x, y, lambda, tau, gamma0, alpha0, alphas, alphaf) * sigma1(
        (exp(lambda * (tau - t)) - 1) / lambda);
}

```

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}

/*****/
/*static double beta(double t,double T,double lambda)
{

    return(1/lambda*(1-exp(-lambda*(T-t))));
}
*/
/*resolution of LUx=B*/
/*****/
static void soLU(int ndr, double **A, double *B)
{
    double *Y;
    int i, N;

    N = ndr * ndr;

    if ((Y = (double *)calloc(N, sizeof(double))) == NULL)
    {
        printf("Impossible d'allouer le tableau Y\ n");
        exit(1);
    }

    /* resolution de LUx=B ou L et U sont issues de la facto incomp ILU(0) de A */
    /* et stockées dans A sauf la diago de 1 de L */

    /* initialisation */

    for (i = 0; i < N; i++)
    {

        Y[i] = 0;
    }

    /* resoudre LUX=B */

    /* Resoudre LY=B par descente triangulaire */

    Y[0] = B[0];

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for (i = 1; i < ndr - 1; i++)
{
    Y[i] = B[i];

    Y[i] -= A[i][1] * Y[i - 1];

}

i = ndr - 1;

Y[i] = B[i];

Y[i] -= A[i][1] * Y[i - 1];

i = ndr;

Y[i] = B[i];

Y[i] -= A[i][3] * Y[i - ndr] + A[i][1] * Y[i - 1];

for (i = ndr + 1; i < N; i++)
{

    Y[i] = B[i];

    Y[i] -= A[i][5] * Y[i - ndr - 1] + A[i][3] * Y[i - ndr] + A[i][1] * Y[i -

}

/* Resoudre UX=Y par remontée triangulaire */

/* X est remplacé par B */

B[N - 1] = Y[N - 1] / A[N - 1][0];

for (i = N - 2; i > N - ndr; i--)
{

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        B[i] = Y[i] - A[i][2] * B[i + 1];

        B[i] /= A[i][0];
    }

    i = N - ndr;

    B[i] = Y[i] - A[i][2] * B[i + 1];

    B[i] /= A[i][0];
    i = N - ndr - 1;

    B[i] = Y[i] - A[i][4] * B[i + ndr] - A[i][2] * B[i + 1];

    B[i] /= A[i][0];

    for (i = N - ndr - 2; i > -1; i--)
    {

        B[i] = Y[i] - A[i][6] * B[i + ndr + 1] - A[i][4] * B[i + ndr] - A[i][2] *

        B[i] /= A[i][0];

    }

    free(Y);

    return;
}

/*Preconditioner GMRES Solver*/
static int resolution(int ndr, double **m, double *Pn, double *Pnn, double *Pnnn)
{
    int ip, I, J, I1, I2, I3, I4;
    double tem, dem, hii, hipi, gamm, coss, sinn, hipj, res, hij, raux, som;
    int it, i, i1, k, j, j11, nk, nit, nkrMax, nkr, N;
    double erreur;
    double **A, *aux, *aux1, **v, **hh, *rr, *vec, *x;
    int iterr ;

```

```

N = ndr * ndr;
iterr = 0;

nk = 1;
nit = 3;
nkrMax = 1;
nkr = 1;

if ((aux = (double *)calloc(N + 1, sizeof(double))) == NULL)
{
    printf("Impossible d'allouer le tableau aux\ n");
    exit(1);
}

if ((aux1 = (double *)calloc(N + 1, sizeof(double))) == NULL)
{
    printf("Impossible d'allouer le tableau aux1\ n");
    exit(1);
}
v = (double **)calloc(N + 1, sizeof(double *));
for (i = 0; i < N + 1; i++)
{
    if ((v[i] = (double *)calloc(nkrMax + 1, sizeof(double))) == NULL)
    {
        printf("Impossible d'allouer le tableau v\ n");
        exit(1);
    }
}

hh = (double **)calloc(nkrMax + 1, sizeof(double *));
for (i = 0; i < nkrMax + 1; i++)
{
    if ((hh[i] = (double *)calloc(nkrMax + 1, sizeof(double))) == NULL)
    {
        printf("Impossible d'allouer le tableau h\ n");
        exit(1);
    }
}
if ((rr = (double *)calloc(nkrMax + 1, sizeof(double))) == NULL)
{
    printf("Impossible d'allouer le tableau rr\ n");
}

```

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        exit(1);
    }
    if ((vec = (double *)calloc(N + 1, sizeof(double))) == NULL)
    {
        printf("Impossible d'allouer le tableau vec\ n");
        exit(1);
    }

    if ((x = (double *)calloc(N + 1, sizeof(double))) == NULL)
    {
        printf("Impossible d'allouer le tableau x\ n");
        exit(1);
    }

    A = (double **)calloc(N + 1, sizeof(double *));
    for (i = 0; i < N + 1; i++)
    {
        if ((A[i] = (double *)calloc(7, sizeof(double))) == NULL)
        {
            printf("Impossible d'allouer le tableau A\ n");
            exit(1);
        }
    }

    /* résolution du systeme linéaire mx=S par GMRES */

    /* précision de la solution */

    erreur = 0.001;

    /* factorisation incomplete LU : ILU(0) stocké dans A sans la diago de 1 de L

    /*Memory Allocation*/

    for (i = 0; i < N; i++)
    {

```



```

    for (j = 0; j < 7; j++)
    {
        A[i][j] = m[i][j];
    }
}

```

```

for (i = 1; i < ndr; i++)
{
    I1 = i - 1;

    A[i][1] /= A[I1][0];

    A[i][0] -= A[i][1] * A[I1][2];

    A[i][4] -= A[i][1] * A[I1][6];

}

```

```

i = ndr;
I1 = i - ndr;
I3 = i - 1;

```

```

A[i][3] /= A[I1][0];

```

```

A[i][0] -= A[i][3] * A[I1][4];
A[i][2] -= A[i][3] * A[I1][6];

```

```

A[i][1] /= A[I3][0];

```

```

A[i][0] -= A[i][1] * A[I3][2];

```

```

A[i][4] -= A[i][1] * A[I3][6];

```

```

for (i = ndr + 1; i < N - ndr - 1; i++)
{

```

```

    I1 = i - ndr - 1;

```

```

    I2 = I1 + 1;

```

```

    I4 = i - 1;

```

```

    A[i][5] /= A[I1][0];

```

```

    A[i][3] -= A[i][5] * A[I1][2];

```

```

    A[i][1] -= A[i][5] * A[I1][4];

```

```

    A[i][0] -= A[i][5] * A[I1][6];

```

```

    A[i][3] /= A[I2][0];

```

```

    A[i][0] -= A[i][3] * A[I2][4];

```

```

    A[i][2] -= A[i][3] * A[I2][6];

```

```

    A[i][1] /= A[I4][0];

```

```

    A[i][0] -= A[i][1] * A[I4][2];

    A[i][4] -= A[i][1] * A[I4][6];

}

i = N - ndr - 1;

I4 = i - ndr - 1;
I3 = I4 + 1;
I2 = i - 1;

A[i][5] /= A[I4][0];

A[i][3] -= A[i][5] * A[I4][2];
A[i][1] -= A[i][5] * A[I4][4];
A[i][0] -= A[i][5] * A[I4][6];


A[i][3] /= A[I3][0];


A[i][0] -= A[i][3] * A[I3][4];
A[i][2] -= A[i][3] * A[I3][6];


A[i][1] /= A[I2][0];


A[i][0] -= A[i][1] * A[I2][2];

A[i][4] -= A[i][1] * A[I2][6];

```

```

for (i = N - ndr; i < N - 1; i++)
{
    I1 = i - ndr - 1;
    I2 = I1 + 1;

    I4 = i - 1;

    A[i][5] /= A[I1][0];

    A[i][3] -= A[i][5] * A[I1][2];
    A[i][1] -= A[i][5] * A[I1][4];
    A[i][0] -= A[i][5] * A[I1][6];

    A[i][3] /= A[I2][0];

    A[i][0] -= A[i][3] * A[I2][4];
    A[i][2] -= A[i][3] * A[I2][6];

    A[i][1] /= A[I4][0];

    A[i][0] -= A[i][1] * A[I4][2];

}

i = N - 1;
I1 = i - ndr - 1;

```

```
I2 = I1 + 1;
```

```
I4 = i - 1;
```

```
A[i][5] /= A[I1][0];
```

```
A[i][3] -= A[i][5] * A[I1][2];
```

```
A[i][1] -= A[i][5] * A[I1][4];
```

```
A[i][0] -= A[i][5] * A[I1][6];
```

```
A[i][3] /= A[I2][0];
```

```
A[i][0] -= A[i][3] * A[I2][4];
```

```
A[i][1] /= A[I4][0];
```

```
A[i][0] -= A[i][1] * A[I4][2];
```

```
for (i = 0; i < N; i++)  
{
```

```
    /*
```

```
    x[i]=Pn[i];
```

```
    */
```

```
    /* LAGRANGE INTERPOLATION de degré 3 */
```

```
    /*
```

```
    x[i]=Pnnn[i]+3*(Pn[i]-Pnn[i]);
```

```
    */
```

```
    /* LAGRANGE INTERPOLATION de degré 2 */
```

```

    x[i] = -Pnn[i] + 2 * Pn[i];

}

/* stockage des solutions */

for (i = 0; i < N; i++)
{

    Pnnn[i] = Pnn[i];
    Pnn[i] = Pn[i];

}

/* initialisation */

for (i = 0; i < N; i++)
{
    aux[i] = 0;
}

/* matrice creuse */

for (i = 1; i < ndr - 1; i++)
{
    for (j = 1; j < ndr - 1; j++)
    {

        I = i * ndr + j;
        I1 = I + ndr;
        I2 = I - ndr;

        aux[I] = s[I] - m[I][5] * x[I2 - 1] - m[I][3] * x[I2] - m[I][1] * x[I]
            - m[I][4] * x[I1] - m[I][6] * x[I1 + 1];

    }
}

```

```

    }

for (i = 1; i < ndr - 1; i++)
{
    J = (ndr - 1) * ndr + i;
    I1 = i + ndr;
    I2 = J - ndr;

    aux[i] = s[i] - m[i][1] * x[i - 1] - m[i][0] * x[i] - m[i][2] * x[i + 1] -
    aux[J] = s[J] - m[J][5] * x[I2 - 1] - m[J][3] * x[I2] - m[J][1] * x[J - 1]

}

for (i = 1; i < ndr - 1; i++)
{
    I = i * ndr;
    I1 = I + ndr;
    I2 = I - ndr;

    aux[I] = s[I] - m[I][3] * x[I2] - m[I][0] * x[I] - m[I][2] * x[I + 1] -
        m[I][4] * x[I1] - m[I][6] * x[I1 + 1];

    I = i * ndr + ndr - 1;
    I1 = I + ndr;
    I2 = I - ndr;

    aux[I] = s[I] - m[I][5] * x[I2 - 1] - m[I][3] * x[I2] - m[I][1] * x[I - 1] -
        m[I][4] * x[I1];

}

I = (ndr - 1) * ndr + ndr - 1;
I1 = I - ndr;

aux[I] = s[I] - m[I][5] * x[I1 - 1] - m[I][3] * x[I1] - m[I][1] * x[I - 1] - m

I = (ndr - 1) * ndr;
I1 = I - ndr;

```

```

aux[I] = s[I] - m[I][3] * x[I1] - m[I][0] * x[I] - m[I][2] * x[I + 1];
I = 0 + 0;

aux[I] = s[I] - m[I][0] * x[I] - m[I][2] * x[I + 1] - m[I][4] * x[I + ndr] - m[I][1] * x[I - 1];
I = 0 + ndr - 1;

aux[I] = s[I] - m[I][1] * x[I - 1] - m[I][0] * x[I] - m[I][4] * x[I + ndr];

soLU(ndr, A, aux);

som = 0;

for (i = 0; i < N; i++)
{
    som += aux[i] * aux[i];
}

res = som;

res = sqrt(res);

if (res <= erreur)
{
    for (i = 0; i < N; i++)
    {
        Pn[i] = x[i];
    }
}

```



```

    return 0;
}

/* demarrage des iterations */

for (it = 0; it < nit; it++)
{

    nk = nkr;

    /* orthonormalisation d'Arnoldi */

    for (i = 0; i < N; i++)
    {
        aux[i] /= res;
    }
    for (i = 1; i < nkrMax; i++)
    {
        rr[i] = 0;
    }
    rr[0] = res ;

    for (j = 0; j < nkr; j++)
    {

        for (i = 0; i < N; i++)
        {
            v[i][j] = aux[i];
        }

        /* matrice creuse */

        for (i = 1; i < ndr - 1; i++)
        {
            for (k = 1; k < ndr - 1; k++)
            {

```

```

        I = i * ndr + k;
        I1 = I + ndr;
        I2 = I - ndr;

        aux1[I] = m[I][5] * aux[I2 - 1] + m[I][3] * aux[I2] + m[I][1]
                  m[I][4] * aux[I1] + m[I][6] * aux[I1 + 1];

    }
}

for (i = 1; i < ndr - 1; i++)
{
    J = (ndr - 1) * ndr + i;

    aux1[i] = m[i][1] * aux[i - 1] + m[i][0] * aux[i] + m[i][2] * aux[
    aux1[J] = m[J][5] * aux[J - ndr - 1] + m[J][3] * aux[J - ndr] + m[

}

for (i = 1; i < ndr - 1; i++)
{
    I = i * ndr;

    aux1[I] = m[I][3] * aux[I - ndr] + m[I][0] * aux[I] + m[I][2] * au

    I = i * ndr + ndr - 1;

    aux1[I] = m[I][5] * aux[I - ndr - 1] + m[I][3] * aux[I - ndr] + m[

}

I = (ndr - 1) * ndr + ndr - 1;

aux1[I] = m[I][5] * aux[I - ndr - 1] + m[I][3] * aux[I - ndr] + m[I][1]

I = (ndr - 1) * ndr;

```

```

aux1[I] = m[I][3] * aux[I - ndr] + m[I][0] * aux[I] + m[I][2] * aux[I]

I = 0 + 0;

aux1[I] = m[I][0] * aux[I] + m[I][2] * aux[I + 1] + m[I][4] * aux[I + 1]

I = 0 + ndr - 1;

aux1[I] = m[I][1] * aux[I - 1] + m[I][0] * aux[I] + m[I][4] * aux[I + 1]

solU(ndr, A, aux1);

for (i = 0; i < N; i++)
{
    aux[i] = aux1[i];
}

for (i = 0; i < j + 1; i++)
{
    for (k = 0; k < N; k++)
    {
        vec[k] = v[k][i];
    }

    som = 0;
    for (i1 = 0; i1 < N; i1++)
    {
        som += aux1[i1] * vec[i1];
    }
    tem = som;
    hh[i][j] = tem;
    for (i1 = 0; i1 < N; i1++)
    {
        aux[i1] -= tem * v[i1][i];
    }
}

```

```

    som = 0;
    for (i1 = 0; i1 < N; i1++)
    {
        som += aux[i1] * aux[i1];
    }

    dem = som;
    dem = sqrt(dem);
    hh[j + 1][j] = dem;

    if (dem <= erreur)
    {

        nk = j;
        for (i = 0; i < N; i++)
        {
            v[i][j + 1] = aux[i];
        }

        break;

    }
    else
    {
        for (i = 0; i < N; i++)
        {
            aux[i] /= dem;
        }
    }
}

/* triangularisation et modif. du second membre */

for (i = 0; i < nk; i++)
{

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    ip = i + 1;
    hii = hh[i][i];
    hipi = hh[ip][i];
    gamm = hii * hii + hipi * hipi;
    gamm = sqrt(gamm);
    gamm = 1. / gamm;
    coss = hii * gamm;
    sinn = -hipi * gamm;

    for (j = i; j < nk; j++)
    {
        hij = hh[i][j];
        hipj = hh[ip][j];
        hh[i][j] = coss * hij - sinn * hipj;
        hh[ip][j] = sinn * hij + coss * hipj;
    }
    raux = rr[i];
    rr[i] = coss * raux;
    rr[ip] = sinn * raux;
}

/* resolution du systeme triangulaire superieur */
for (i1 = nk - 1; i1 > -1; i1--)
{
    tem = rr[i1] / hh[i1][i1];
    rr[i1] = tem;
    for (j11 = i1 - 1; j11 > -1; j11--)
    {
        rr[j11] -= hh[j11][i1] * tem;
    }
}

for (i1 = 0; i1 < nk; i1++)
{
    tem = rr[i1];
    for (j11 = 0; j11 < N; j11++)
    {
        x[j11] += tem * v[j11][i1];
    }
}

```

```

    }

/* calcul du residu */

/* matrice creuse */

for (i = 1; i < ndr - 1; i++)
{
    for (j = 1; j < ndr - 1; j++)
    {

        I = i * ndr + j;
        I1 = I + ndr;
        I2 = I - ndr;

        aux[I] = s[I] - m[I][5] * x[I2 - 1] - m[I][3] * x[I2] - m[I][1] *
            m[I][4] * x[I1] - m[I][6] * x[I1 + 1];

    }
}

for (i = 1; i < ndr - 1; i++)
{
    J = (ndr - 1) * ndr + i;

    aux[i] = s[i] - m[i][1] * x[i - 1] - m[i][0] * x[i] - m[i][2] * x[i + 1]
    aux[J] = s[J] - m[J][5] * x[J - ndr - 1] - m[J][3] * x[J - ndr] - m[J][4] * x[J + ndr]

}

for (i = 1; i < ndr - 1; i++)
{
    I = i * ndr;

    aux[I] = s[I] - m[I][3] * x[I - ndr] - m[I][0] * x[I] - m[I][2] * x[I + ndr]
        m[I][4] * x[I + ndr] - m[I][6] * x[I + ndr + 1];
}

```

```

I = i * ndr + ndr - 1;

aux[I] = s[I] - m[I][5] * x[I - ndr - 1] - m[I][3] * x[I - ndr] - m[I]
        m[I][4] * x[I + ndr];

}

I = (ndr - 1) * ndr + ndr - 1;

aux[I] = s[I] - m[I][5] * x[I - ndr - 1] - m[I][3] * x[I - ndr] - m[I][1]

I = (ndr - 1) * ndr;

aux[I] = s[I] - m[I][3] * x[I - ndr] - m[I][0] * x[I] - m[I][2] * x[I + 1]

I = 0 + 0;

aux[I] = s[I] - m[I][0] * x[I] - m[I][2] * x[I + 1] - m[I][4] * x[I + ndr]

I = 0 + ndr - 1;

aux[I] = s[I] - m[I][1] * x[I - 1] - m[I][0] * x[I] - m[I][4] * x[I + ndr]

soLU(ndr, A, aux);


som = 0;
for (i1 = 0; i1 < N; i1++)
{
    som += aux[i1] * aux[i1];
}
res = som;

res = sqrt(res);

if (res <= erreur)
{

    break;
}

```

```

    }

    iterr += 1;

}

for (i = 0; i < N; i++)
    Pn[i] = x[i];

/*Memory Desallocation*/
for (i = 0; i < N + 1; i++)
    free(v[i]);
free(v);

for (i = 0; i < nkrMax + 1; i++)
    free(hh[i]);
free(hh);

for (i = 0; i < N + 1; i++)
    free(A[i]);
free(A);

free(vec);
free(rr);
free(aux);
free(aux1);
free(x);

return 1;

}

/*****
static int bond_implicit1d(/*double maturity_option, NumFunc_1 *p, int am, */

double t, /*
double maturity_bond, /* maturité du zéro-coupon */
/*
double alpha0, /* Paramètres de la volatilité */

```



```

double alphas,          /*
double alphas,          */

/*(t,T,r,f) = (alpha0+alphar*r+alphaf*f)^gamma*exp(-lambda(T-t)) */
double gamm0,          /*
double lambda,        /*
*/
double beta0,          /* Paramètres taux forward */
double beta1,          /*
double eta,            /* f(0,t) = beta_0 + beta_1*(1-exp(-eta*t) */
/*
*/
double tau,
int ndr,              /* nombre de pas de d'espace et de temps */
int ndf,

int ndt,
double *price)
{
int i, j, k, l, ii;
double temps;
double *s, **m, **sigmarr;
double R, F;        /* localisation */
double dt, dr, df, df2, dr2, drdf, idr, jdf, sigr2, sigf2, murr, murr, sigrf;
double c0, c1, p1; /* prix interpolé */
int N;
double r00 = beta0; /* (r00,f00) */
double f00 = beta0; /* à l'instant t */

/*tau appears in forward rate volatility description*/
/* constantes */
if (tau > maturity_bond)
return PREMIA_UNTREATED_TAU_BHAR_CHIARELLA;

N = ndr * ndr;

/* Localization */
R = 1;
F = 1;

```

```

/* steps */
dr = R / ndr;
df = F / ndf;
dr2 = dr * dr;
df2 = df * df;

sigmarr = (double **)calloc(ndr, sizeof(double *));
for (i = 0; i < ndr; i++)
{
    if ((sigmarr[i] = (double *)calloc(ndf, sizeof(double))) == NULL)
    {
        printf("Impossible d'allouer le tableau sigmarr\ n");
        exit(1);
    }
}

/* calcul de sigmarr */
for (i = 0; i < ndr; i++)
{
    idr = i * dr;
    for (j = 0; j < ndf; j++)
    {
        sigmarr[i][j] = exp(gamm0 * log(alpha0 + alphas * idr + alphaf * j * d
    }
}

m = (double **)calloc(N, sizeof(double *));
for (i = 0; i < N; i++)
{
    if ((m[i] = (double *)calloc(7, sizeof(double))) == NULL)
    {
        printf("Impossible d'allouer le tableau m\ n");
        exit(1);
    }
}

if ((s = (double *)calloc(N, sizeof(double))) == NULL)
{
    printf("Impossible d'allouer le tableau s\ n");
    exit(1);
}

```

```

    }

    if ((Pn = (double *)calloc(N, sizeof(double))) == NULL)
    {
        printf("MEMORY_ALLOCATION_FAILURE\ n");
        exit(1);
    }

    if ((Pnn = (double *)calloc(N, sizeof(double))) == NULL)
    {
        printf("MEMORY_ALLOCATION_FAILURE\ n");
        exit(1);
    }

    if ((Pnnn = (double *)calloc(N, sizeof(double))) == NULL)
    {
        printf("MEMORY_ALLOCATION_FAILURE\ n");
        exit(1);
    }

    /*Maturity Condition for Bond Prices*/
    for (i = 0; i < ndr; i++)
    {
        for (j = 0; j < ndf; j++)
        {
            I = i * ndr + j;
            /* bond-pricing */
            Pn[I] = 1.;
            Pnn[I] = 1.;
            Pnnn[I] = 1.;
        }
    }

    dt = (maturity_bond - t) / ndt;

    drdf = dt * 0.5 / (dr * df);

    temps = maturity_bond;

    /* option pricing

```

```

}else{

for(i=0;i<ndr;i++){
for(j=0;j<ndf;j++){

I=i*(ndr)+j;

Pn[I]=max(Pn[I]-strike,0);
Pnn[I]=Pn[I];
Pnnn[I]=Pn[I];

}
}

dt=(maturity_option-t)/ndt;

drdf=dt*0.5/(dr*df);

temps=maturity_option;

}*/

/* mise du systeme lineaire a 0 */
for (i = 0; i < ndr; i++)
{
    for (j = 0; j < ndf; j++)
    {
        I = i * (ndr) + j;
        s[I] = 0;
        for (k = 0; k < 7; k++)

```

```

        {
            m[I][k] = 0;
        }
    }

/* conditions de Neumann homogenes sur le bord valables a chaque pas de temps
for (i = 1; i < ndr - 1; i++)
{
    I = i * ndr + 0;

    m[I][0] = 1;

    m[I][2] = -1;

    I = i * ndr + ndf - 1;

    m[I][0] = 1;

    m[I][1] = -1;
}

for (j = 1; j < ndf - 1; j++)
{
    I = 0 + j;

    m[I][0] = 1;

    m[I][4] = -1;

    I = (ndr - 1) * ndr + j;

    m[I][0] = 1;

    m[I][3] = -1;
}

```

```

    }

/* Les 4 angles */

I = (ndr - 1) * ndr + ndf - 1;

m[I][0] = 1;

m[I][5] = -1;

I = (ndr - 1) * ndr;

m[I][0] = 1;

m[I][2] = -0.5;
m[I][3] = -0.5;
I = 0 + 0;

m[I][0] = 1;

m[I][6] = -1;

I = 0 + ndf - 1;

m[I][0] = 1;

m[I][1] = -0.5;
m[I][4] = -0.5;

for (ii = 0; ii < ndt; ii++)
{
    temps -= dt;

```

```

/* remplissage du systeme lineaire */

for (i = 1; i < ndr - 1; i++)
{
    idr = i * dr;
    for (j = 1; j < ndf - 1; j++)
    {
        jdf = j * df;

        sigr2 = sigmarr[i][j];

        sigf2 = sigma1(temps, idr, jdf, lambda, tau, gamm0, alpha0, alphas, alphas2);

        sigrf = sigr2 * sigf2 * drdf;

        sigf2 = sigf2 * sigf2 * dt / df2;

        sigr2 = sigr2 * sigr2 * dt / dr2;

        murr = mur(temps, idr, jdf, lambda, beta0, beta1, eta, tau) * 0.5;

        muff = mu1(temps, idr, jdf, tau, lambda, gamm0, alpha0, alphas, alphas2);

        I = i * ndr + j;
        m[I][0] = 1 + sigf2 + sigr2 + idr * dt - 2 * sigrf;

        m[I][1] = muff - sigf2 * 0.5 + sigrf ;
        m[I][2] = m[I][1] - 2 * muff;
        m[I][3] = murr - sigr2 * 0.5 + sigrf;
        m[I][4] = -murr - sigr2 * 0.5 + sigrf;
        m[I][5] = -sigrf;
        m[I][6] = -sigrf;
        s[I] = Pn[I];

    }
}

/* resolution du systeme lineaire */

```

```

        resolution(ndr, m, Pn, Pnn, Pnnn, s);

    }

    /* Interpolation bilineaire pour le prix */
    i = 0;
    while (r00 > i * dr)
        i++;
    j = 0;
    while (f00 > j * df)
        j++;

    c0 = (r00 - (i - 1) * dr) / dr;
    c1 = (f00 - (j - 1) * df) / df;

    p1 = (1. - c0) * (1. - c1) * Pn[(i - 1) * ndr + j - 1] + c0 * (1. - c1) * Pn[i * ndr + j - 1] +
        c0 * c1 * Pn[i * ndr + j] + (1. - c0) * c1 * Pn[(i - 1) * ndr + j];

    /*Price*/
    *price = p1;

    for (i = 0; i < N; i++)
        free(m[i]);
    free(m);

    for (i = 0; i < ndr; i++)
        free(sigmarr[i]);
    free(sigmarr);

    free(Pn);
    free(Pnn);
    free(Pnnn);
    free(s);

    return OK;
}

int CALC(FD_IMPLICIT_ZCBond)(void *Opt, void *Mod, PricingMethod *Met)
{
    TYPEOPT *ptOpt = (TYPEOPT *)Opt;

```



```

    TYPEMOD *ptMod = (TYPEMOD *)Mod;

    return bond_implicit1d(ptMod->T.Val.V_DATE, ptOpt->BMaturity.Val.V_DATE, ptMod
}

static int CHK_OPT(FD_IMPLICIT_ZCBond)(void *Opt, void *Mod)
{
    if ((strcmp(((Option *)Opt)->Name, "ZeroCouponBond") == 0))
        return OK;
    else
        return WRONG;
}

static int MET(Init)(PricingMethod *Met, Option *Opt)
{
    if (Met->init == 0)
    {
        Met->init = 1;

        Met->Par[0].Val.V_LONG = 100;
        Met->Par[1].Val.V_LONG = 100;
        Met->Par[2].Val.V_LONG = 100;

    }
    return OK;
}

PricingMethod MET(FD_IMPLICIT_ZCBond) =
{
    "FD_Implicit_BharChiarella1d_ZCBond",
    { {"TimeStepNumber", LONG, {100}, ALLOW}, {"SpotRateSpaceStepNumber", LONG, {1
        {" ", PREMIA_NULLTYPE, {0}, FORBID}
    },
    CALC(FD_IMPLICIT_ZCBond),
    {{"Price", DOUBLE, {100}, FORBID} , {" ", PREMIA_NULLTYPE, {0}, FORBID}},
    CHK_OPT(FD_IMPLICIT_ZCBond),
    CHK_ok,
    MET(Init)
} ;

```